

## General Description

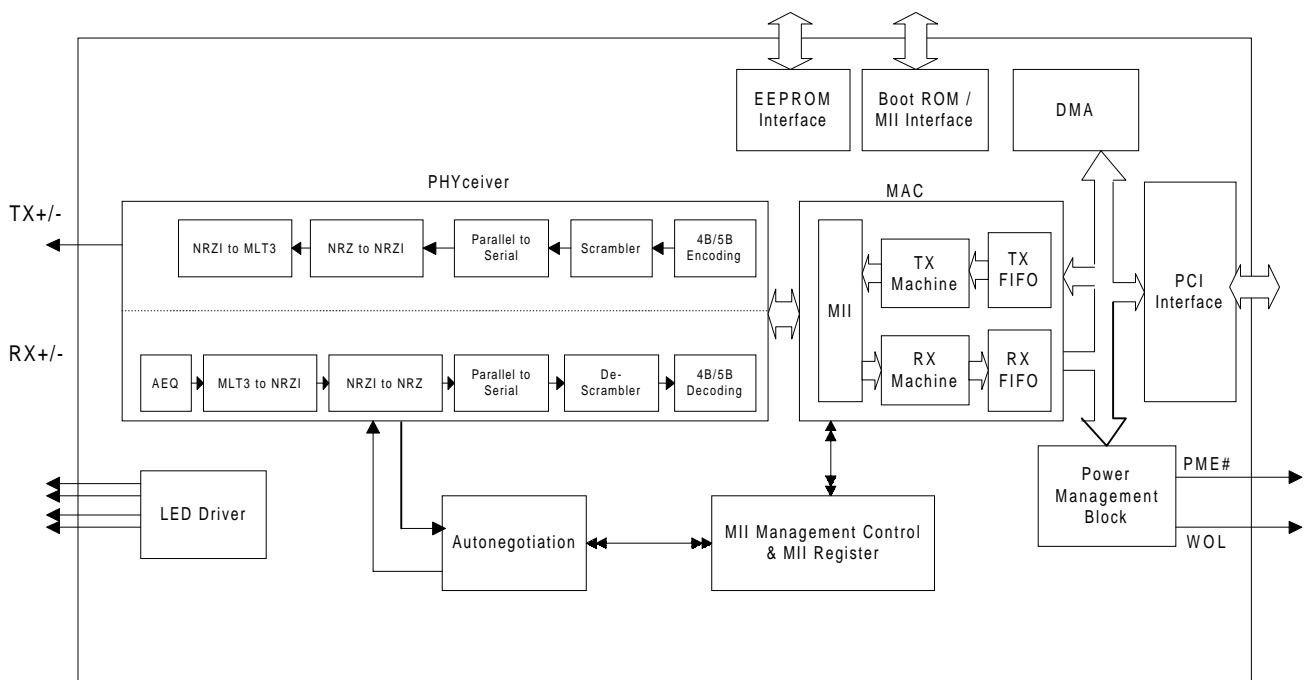
The DM9102A is a fully integrated and cost-effective single chip Fast Ethernet NIC controller. It is designed with the low power and high performance process. It is a 3.3V device with 5V tolerance then it supports 3.3V and 5V signaling.

The DM9102A provides direct interface to the PCI or the CardBus. It supports bus master capability and fully complies with PCI 2.2. In media side, The DM9102A interfaces to the UTP3,4,5 in 10Base-T and UTP5 in 100Base-TX. It is fully compliance with the IEEE 802.3u

Spec. Its auto-negotiation function will automatically configure the DM9102A to take the maximum advantage of its abilities. The DM9102A is also support IEEE 802.3x full-duplex flow control.

The DM9102A supports two types of power-management mechanisms. The main mechanism is based upon the OnNow architecture, which is required for PC99. The alternative mechanism is based upon the remote Wake-On-LAN mechanism.

## Block Diagram





### Table of Contents

|   |    |   |    |
|---|----|---|----|
| General Description .....                       | 1  | 7. Network Operation Register (CR6).....                  | 30 |
| Block Diagram.....                              | 1  | 8. Interrupt Mask Register (CR7).....                     | 32 |
| Features .....                                  | 4  | 9. Statistical Counter Register (CR8).....                | 33 |
| Pin Configuration: DM9102A 128pin QFP.....      | 5  | 10. PROM & Management Access Register (CR9) .....         | 34 |
| Pin Configuration: DM9102A 128pin TQFP .....    | 6  | 11. Programming ROM Address Register (CR10) .....         | 35 |
| Pin Description .....                           | 7  | 12. General Purpose Timer Register (CR11) .....           | 35 |
| - PCI Bus and CardBus Interface Signals .....   | 7  | 13. PHY Status Register (CR12) .....                      | 35 |
| - Boot ROM and EEPROM Interface .....           | 8  | 14. Sample Frame Access Register (CR13).....              | 36 |
| ■ Multiplex Mode .....                          | 8  | 15. Sample Frame Data Register (CR14) .....               | 36 |
| ■ Direct Mode .....                             | 10 | 16. Watching & Jabber Timer Register (CR15).....          | 36 |
| - LED Pins.....                                 | 11 | ◇ CardBus Status Changed Register .....                   | 39 |
| - Network Interface .....                       | 12 | 1. Function Event Register: (offset 80h).....             | 39 |
| - Miscellaneous Pins.....                       | 12 | 2. Function Event Mask Register: (offset 84h).....        | 39 |
| - Power Pins .....                              | 13 | 3. Function Present State Register: (offset 88h).....     | 39 |
| - Note: LED Mode .....                          | 13 | 4. Function Force Event Register: (offset 8Ch) .....      | 40 |
| Register Definition .....                       | 14 | ◇ PHY Management Register Set .....                       | 41 |
| ◇ PCI Configuration Registers .....             | 14 | Key To Default .....                                      | 41 |
| Key to Default .....                            | 14 | Basic Mode Control Register (BMCR)                        |    |
| ■ Identification ID .....                       | 15 | - Register 0.....   | 42 |
| ■ Command & Status.....                         | 15 | Basic Mode Status Register (BMSR)                         |    |
| ■ Revision ID .....                             | 17 | - Register 1.....   | 43 |
| ■ Miscellaneous Function .....                  | 18 | PHY ID Identifier Register #1 (PHYIDR1)                   |    |
| ■ I/O Base Address .....                        | 18 | - Register 2.....   | 44 |
| ■ Memory Mapped Base Address.....               | 19 | PHY ID Identifier Register #2 (PHYIDR2)                   |    |
| ■ Subsystem Identification .....                | 19 | - Register 3.....   | 44 |
| ■ CardBus CIS Pointer.....                      | 20 | Auto-negotiation Advertisement Register (ANAR)            |    |
| ■ Expansion ROM Base Address.....               | 21 | - Register 4.....   | 44 |
| ■ Capabilities Pointer.....                     | 21 | Auto-negotiation Link Partner Ability Register (ANLPAR) - |    |
| ■ Interrupt & Latency Configuration .....       | 22 | Register 5.....   | 45 |
| ■ Device Specific Configuration Register.....   | 22 | Auto-negotiation Expansion Register (ANER)                |    |
| ■ Power Management Register.....                | 23 | - Register 6.....   | 46 |
| ■ Power Management Control/Status .....         | 24 | DAVICOM Specified Configuration Register (DSCR)           |    |
| ◇ Control and Status Register (CR).....         | 25 | - Register 10.....  | 46 |
| Key to Default.....                             | 25 | DAVICOM Specified Configuration and Status Register       |    |
| 1. System Control Register (CR0).....           | 26 | (DSCSR) - Register 11 .....                               | 47 |
| 2. Transmit Descriptor Poll Demand (CR1) .....  | 27 | 10Base-T Configuration/Status (10BTSCRCR)                 |    |
| 3. Receive Descriptor Poll Demand (CR2) .....   | 27 | - Register 12.....  | 48 |
| 4. Receive Descriptor Base Address (CR3) .....  | 27 | Functional Description .....                              | 49 |
| 5. Transmit Descriptor Base Address (CR4) ..... | 28 | ◇ System Buffer Management .....                          | 49 |
| 6. Network Status Report Register (CR5).....    | 28 | 1. Overview .....   | 49 |
|   |    | 2. Data Structure and Descriptor List .....               | 49 |
|   |    | 3. Buffer Management: Chain Structure Method.....         | 49 |
|   |    | 5. Descriptor List: Buffer Descriptor Format.....         | 49 |
|   |    | (a). Receive Descriptor Format .....                      | 49 |



# DM9102A

## Single Chip Fast Ethernet NIC controller

|   |    |  |    |
|---|----|--|----|
| (b). Transmit Descriptor Format.....  | 51 | 6. Example of DM9102A SROM Format.....                         | 63 |
| ◇ Initialization Procedure.....   | 54 | External MII/SRL Interface .....                               | 66 |
| Data Buffer Processing Algorithm .....  | 54 | The Sharing Pin Table.....                                     | 66 |
| 1. Receive Data Buffer Processing .....   | 54 | Absolute Maximum Ratings .....                                 | 68 |
| 2. Transmit Data Buffer Processing .....  | 55 | Operating Conditions.....                                      | 68 |
| ◇ Network Function.....   | 56 | DC Electrical Characteristics .....                            | 69 |
| 1. Overview.....  | 56 | AC Electrical Characteristics & Timing Waveforms.....          | 70 |
| 2. Receive Process and State Machine .....  | 56 | ■ PCI Clock Spec. Timing.....                                  | 70 |
| a. Reception Initiation .....   | 56 | ■ Other PCI Signals Timing Diagram.....                        | 70 |
| b. Address Recognition.....   | 56 | ■ Multiplex Mode Boot ROM Timing.....                          | 71 |
| c. Frame Decapsulation.....   | 56 | ■ Direct Mode Boot ROM Timing.....                             | 72 |
| 3. Transmit Process and State Machine.....  | 56 | ■ EEPROM Timing.....   | 72 |
| a. Transmit Initiation.....   | 56 | ■ TP Interface.....  | 73 |
| b. Frame Encapsulation.....   | 56 | ■ Oscillator/Crystal Timing.....                               | 73 |
| c. Collision.....   | 56 | ■ Auto-negotiation and Fast Link Pulse Timing Parameters ..... | 73 |
| 4. Physical Layer Overview .....  | 56 | Package Information (128 pin, QFP) .....                       | 75 |
| ◇ Serial Management Interface .....   | 57 | Package Information (128 pin, TQFP).....                       | 76 |
| ◇ Power Management .....  | 58 | Ordering Information.....                                      | 77 |
| 1. Overview.....  | 58 | Disclaimer .....   | 77 |
| 2. PCI Function Power Management Status .....   | 58 | Company Overview.....  | 77 |
| 3. The Power Management Operation .....   | 58 | Products.....  | 77 |
| a. Detect Network Link State Change .....   | 58 | Contact Windows.....   | 77 |
| b. Active Magic Packet Function.....  | 58 | Warning.....   | 77 |
| c. Active the Sample Frame Function .....   | 58 |  |    |
| ◇ Sample Frame Programming Guide.....   | 60 |  |    |
| Serial ROM Overview.....  | 61 |  |    |
| 1. Subsystem ID Block.....  | 61 |  |    |
| 2. SROM Version.....  | 62 |  |    |
| 3. Controller Count .....   | 62 |  |    |
| 4. Controller_X Information.....  | 62 |  |    |
| 5. Controller Information Body Pointed By Controller_X Info Block Offset Item in Controller Information Header..... | 62 |  |    |

**Features**

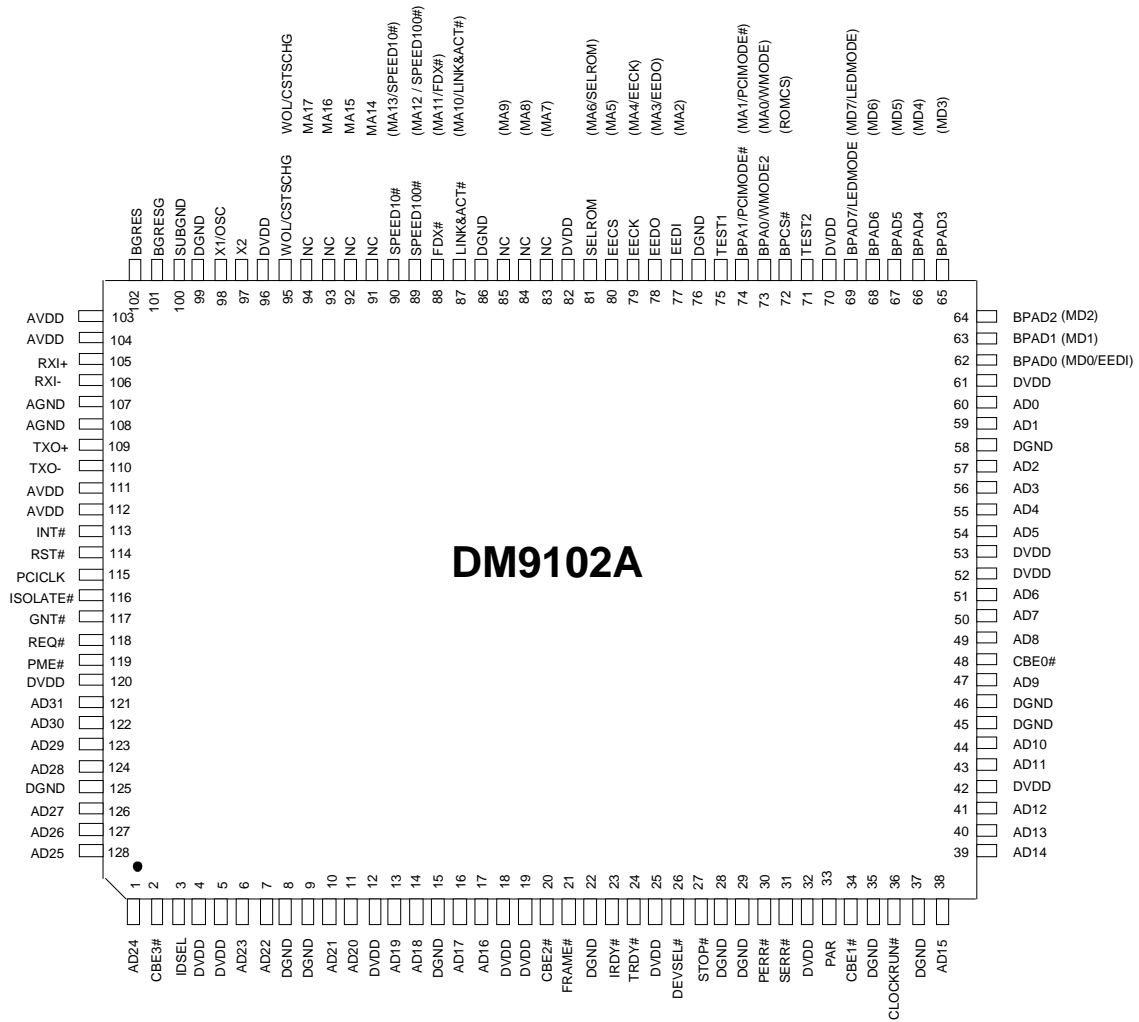
- Integrated Fast Ethernet MAC, Physical Layer and transceiver in one chip.
- 128pin QFP/128pin TQFP with CMOS process.
- +3.3V Power supply with +5V tolerant I/O.
- Supports PCI and CardBus interfaces.
- Comply with PCI specification 2.2.
- PCI clock up to 40MHz.
- PCI bus master architecture.
- PCI bus burst mode data transfer.
- Two large independent FIFO; receive FIFO & transmit FIFO.
- Up to 256K bytes Boot EPROM or Flash interface.
- EEPROM 93C46 interface supports node ID accesses configuration information and user define message.
- Node address auto-load and reload.
- Comply with IEEE 802.3u 100Base-TX and 802.3 10Base-T.
- Comply with IEEE 802.3u auto-negotiation protocol for automatic link type selection.
- Full Duplex/Half Duplex capability.
- Support IEEE 802.3x Full Duplex Flow Control
- VLAN support.
- Comply with ACPI and PCI Bus Power Management.
- Supports the MII (Media Independent Interface).
- Supports Wake-On-LAN function and remote wake-up (Magic packet, Link Change and Microsoft® wake-up frame).
- Supports 4 Wake-On-LAN (WOL) signals (active high pulse, active low pulse, active high , active low ).
- High performance 100Mbps clock generator and data recovery circuit.
- Digital clock recovery circuit using advanced digital algorithm to reduce jitter.
- Adaptive equalization circuit and Baseline wandering restoration circuit for 100Mbps receiver.
- Provides Loopback mode for easy system diagnostics.



# DM9102A

Single Chip Fast Ethernet NIC controller

## Pin Configuration : 128 pin QFP

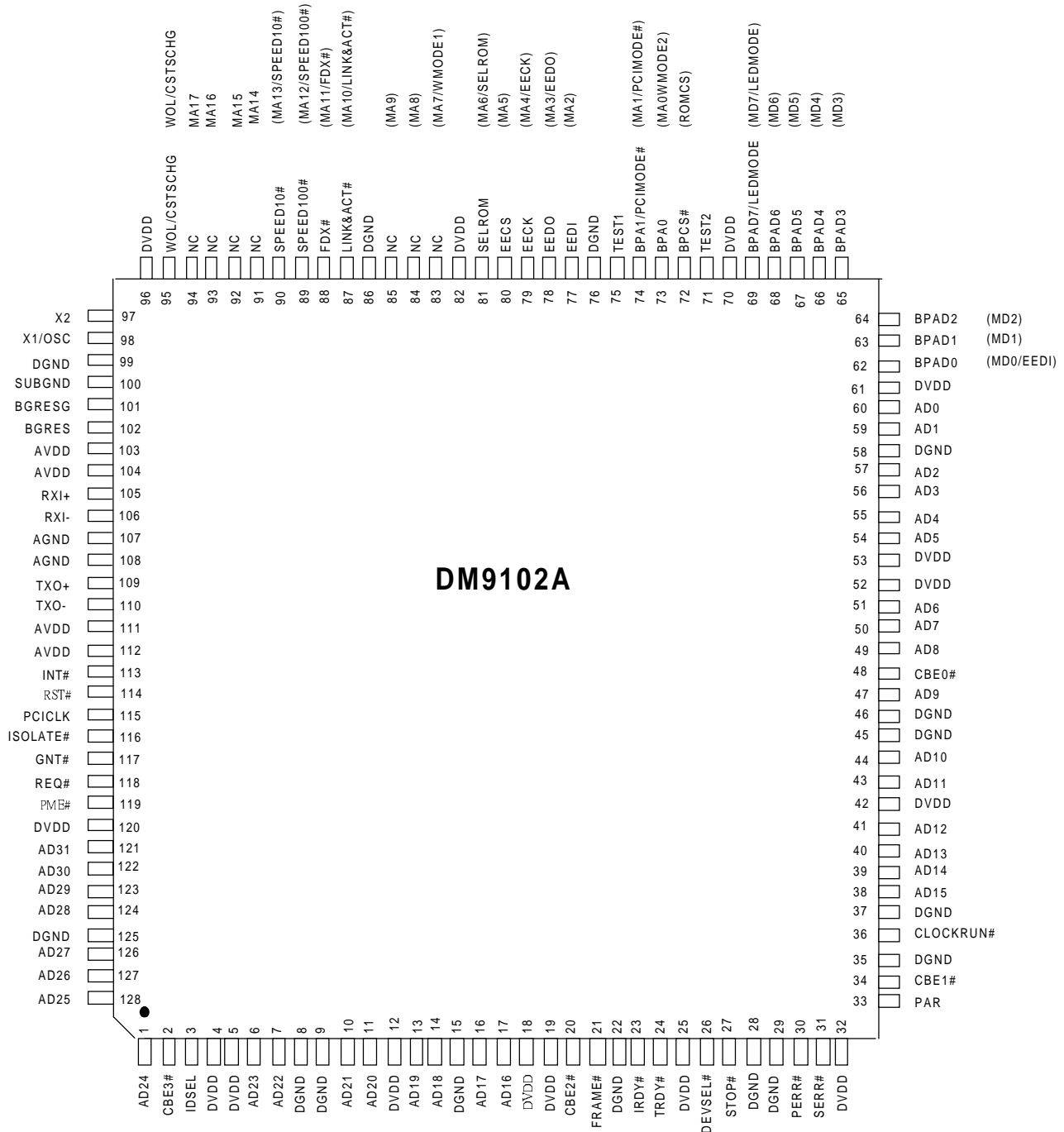




# DM9102A

Single Chip Fast Ethernet NIC controller

## Pin Configuration : 128 pin TQFP



**Pin Description**

I = Input, O = Output, I/O = Input / Output, O/D = Open Drain, P = Power,  
LI = reset Latch Input, # = asserted Low

**PCI Bus and CardBus Interface Signals**

| Pin No.<br>128QFP/128TQFP | Pin Name | I/O | Description  |
|---------------------------|----------|-----|--|
| 113                       | INT#     | O/D | Interrupt Request<br>This signal will be asserted low when an interrupt condition as defined in CR5 is set, and the corresponding mask bit in CR7 is not set.  |
| 114                       | RST#     | I   | System Reset<br>When this signal is asserted low, DM9102A performs the internal system reset to its initial state.   |
| 115                       | PCICLK   | I   | PCI system clock<br>PCI bus clock that provides timing for DM9102A related to PCI bus transactions. The clock frequency range is up to 40MHz.  |
| 117                       | GNT#     | I   | Bus Grant<br>This signal is asserted low to indicate that DM9102A has been granted ownership of the bus by the central arbiter.  |
| 118                       | REQ#     | O   | Bus Request<br>The DM9102A will assert this signal low to request the ownership of the bus.  |
| 119                       | PME#     | O/D | Power Management Event.<br>Open drain. Active Low. The DM9102A drive it low to indicates that a power management event has occurred.   |
| 3                         | IDSEL    | I   | Initialization Device Select<br>This signal is asserted high during the Configuration Space read/write access.   |
| 21                        | FRAME#   | I/O | Cycle Frame<br>This signal is driven low by the DM9102A master mode to indicate the beginning and duration of a bus transaction.   |
| 23                        | IRDY#    | I/O | Initiator Ready<br>This signal is driven low when the master is ready to complete the current data phase of the transaction. A data phase is completed on any clock both IRDY# and TRDY# are sampled asserted.   |
| 24                        | TRDY#    | I/O | Target Ready<br>This signal is driven low when the target is ready to complete the current data phase of the transaction. During a read, it indicates that valid data is asserted. During a write, it indicates the target is prepared to accept data. |
| 26                        | DEVSEL#  | I/O | Device Select<br>The DM9102A asserts the signal low when it recognizes its target address after FRAME# is asserted. As a bus master, the DM9102A will sample this signal that insures its  |



# DM9102A

Single Chip Fast Ethernet NIC controller

|   |                                      |     |   |
|---|--------------------------------------|-----|---|
|   |                                      |     | destination address of the data transfer is recognized by a target.   |
| 27  | STOP#                                | I/O | Stop<br>This signal is asserted low by the target device to request the master device to stop the current transaction.  |
| 30  | PERR#                                | I/O | Parity Error<br>The DM9102A as a master or slave will assert this signal low to indicate a parity error on any incoming data.   |
| 31  | SERR#                                | I/O | System Error<br>This signal is asserted low when address parity is detected with PCICS bit31 (detected parity error) is enabled. The system error asserts two clock cycles after the falling address if an address parity error is detected.  |
| 33  | PAR                                  | I/O | Parity<br>This signal indicates even parity across AD0~AD31 and C/BE0#~C/BE3# including the PAR pin. This signal is an output for the master and input for the slave device. It is stable and valid one clock after the address phase.  |
| 2<br>20<br>34<br>48   | C/BE3#<br>C/BE2#<br>C/BE1#<br>C/BE0# | I/O | Bus Command/Byte Enable<br>During the address phase, these signals define the bus command or the type of bus transaction that will take place. During the data phase these pins indicate which byte lanes contain valid data. C/BE0# applies to bit7-0 and C/BE3# applies to bit31-24.  |
| 121,122,123,124,126,127,<br>128,1,6,7,10,<br>11,13,14,16,<br>17,38,39,40,<br>41,43,44,47,<br>49,50,51,54,<br>55,56,57,59,<br>60 | AD31~AD0                             | I/O | Address & Data<br>These are multiplexed address and data bus signals. As a bus master, the DM9102A will drive address during the first bus phase. During subsequent phases, the DM9102A will either read or write data expecting the target to increment its address pointer. As a target, the DM9102A will decode each address on the bus and respond if it is the target being addressed. |

## Boot ROM and EEPROM Interface (Including multiplex mode or direct mode)

### Multiplex mode

| Pin No.                     | Pin Name                       | I/O     | Description  |
|-----------------------------|--------------------------------|---------|--|
| <b>128QFP/128TQFP</b>       |                                |         |  |
| 62,63,64,65,<br>66,67,68,69 | BPAD0~BPAD7<br>(BPAD7/LEDMODE) | I/O, LI | Boot ROM address and data bus (bits 0~7)<br>Boot ROM address and data multiplexed lines bits 0~7. In MUX mode, there are two consecutive address cycles, these lines contain the boot ROM address pins 7~2, out_enable and write_enable of Boot ROM in the first cycle; and these lines contain address pins 15~8 in second cycle.<br>After the first two cycles, these lines contain data bit 7~0 in consecutive cycles.<br>BPAD1 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select |





# DM9102A

## Single Chip Fast Ethernet NIC controller

|                      |               |         |  |
|----------------------|---------------|---------|--|
|                      |               |         | <p>the WOL as pulse or DC signal.<br/>           0 = WOL pulse mode (default)<br/>           1 = WOL DC mode</p> <p>BPAD2 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select the PME as pulse or DC signal.<br/>           0 = PME pulse mode (default)<br/>           1 = PME DC mode</p> <p>BPAD7 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select LED mode.<br/>           0 = LED mode 0 (default)<br/>           1 = LED mode 1</p> |
| 72                   | BPCS#         | O       | <p>Boot ROM Chip Select<br/>           Boot ROM or external register chip select signal.</p>   |
| 73                   | BPA0/W/MODE   | O, LI   | <p>Boot ROM address line/WOL mode selection<br/>           This multiplexed pin acts as boot ROM address bit 0 output signal during normal operation. When at power on reset, it used to select the type of WOL signal.<br/>           0 = WOL high active (default)<br/>           1 = WOL low active</p>   |
| 74                   | BPA1/PCIMODE# | I/O, LI | <p>Boot ROM address line / PCI mode selection<br/>           This multiplexed pin acts as the boot ROM address bit 1 output signal during normal operation. When RST# is active (low), it acts as the input system type. If the DM9102A is used in a CardBus system, this pin should be connected to a pull-up resistor; otherwise, the DM9102A consider the host as a PCI system.<br/>           0 = PCI mode (default)<br/>           1 = CardBus mode</p>   |
| 77                   | EEDI          | I       | <p>EEPROM Data In<br/>           The DM9102A will read the contents of EEPROM serially through this pin.</p>   |
| 78                   | EEDO          | O       | <p>EEPROM Data Out<br/>           The DM9102A will use this pin to serially write opcodes, addresses and data into the EEPROM.</p>   |
| 79                   | EECK          | O       | <p>EEPROM Serial Clock<br/>           This pin provides the clock for the EEPROM data transfer.</p>  |
| 80                   | EECS          | O       | <p>EEPROM Chip Select<br/>           This pin will enable the EEPROM during loading of the Configuration Data.</p>   |
| 81                   | SELROM        | I       | <p>Multiplex or Director mode selection<br/>           0 = Multiplex mode (default)<br/>           1 = Direct mode</p>   |
| 83,84,85,91,92,93,94 | NC            | NC      | In Multiplex mode, these pins are not connected.   |



**Direct mode**

| Pin No.              | Pin Name     | I/O   | Description  |
|----------------------|--------------|-------|--|
| 128QFP/128TQFP       |              |       |  |
| 62                   | MD0/EEDI     | I     | Boot ROM data input/EEPROM data in<br>This is multiplexed pin used by EEDI and MD0.<br>When boot ROM is selected, it acts as boot ROM data input.<br>When ROMCS select the EEPROM, the DM9102A will read the contents of EEPROM serially through this pin.   |
| 63,64,65,66,67,68,69 | MD1~MD7      | I     | Boot ROM data input bus<br>MD1 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select the WOL as pulse or level signal.<br>0 = WOL pulse mode (default)<br>1 = WOL level mode<br><br>MD2 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select the PME as pulse or level signal.<br>0 = PME pulse mode (default)<br>1 = PME level mode<br><br>MD7 is also a reset latch pin. It is Boot ROM address and data bus when normal operation. When at power on reset, it is used to pull up or down externally through a resistor to select LED mode.<br>0 = LED mode 0 (default)<br>1 = LED mode 1 |
| 72                   | ROMCS        | O     | Boot ROM or EEPROM chip selection.   |
| 73                   | MA0/WMODE    | O     | Boot ROM address output line/WOL mode selection<br>This multiplexed pin acts as boot ROM address output bus during normal operation. When RST# is active, it is used to pull up or down externally through a resistor to select WOL High active or LOW active. (WMODE)<br>0 = WOL high active (default)<br>1 = WOL low active  |
| 74                   | MA1/PCIMODE# | O, LI | Boot ROM address output signal/PCI mode selection<br>This multiplexed pin acts as a boot ROM address output signal during normal operation. When RST# is active, it acts as the input system type. If the DM9102A is used in a CardBus system, this pin should be connected to a pull-up resistor; otherwise, the DM9102A consider the host as a PCI system.<br>0 = PCI mode (default)<br>1 = CardBus mode   |
| 77                   | MA2          | O     | Boot ROM address output signal   |
| 78                   | MA3/EEDO     | O     | Boot ROM address output/EEPROM data out<br>This is multiplexed pin used by MA3 and EEDO.   |



# DM9102A

Single Chip Fast Ethernet NIC controller

|                 |                     |      |  |
|-----------------|---------------------|------|--|
|                 |                     |      | When The DM9102A will use this pin to serially write opcodes, addresses and data into the EEPROM.  |
| 79              | MA4/EECK            | O    | Boot ROM address output/EEPROM serial clock<br>This is multiplexed pin used by MA4 and EECK .<br>This pin provides the clock for the EEPROM data transfer.   |
| 80              | MA5                 | O    | Boot ROM address output signal   |
| 81              | MA6/SELROM          | O/LI | Boot ROM address output/Multiplex or Direct mode selection<br>This multiplexed pin acts as boot ROM address output bus during normal operation. When RST# is active, it is used as multiplex and direct mode selection :<br>0 = Boot ROM interface is in multiplex mode (default)<br>1 = Boot ROM interface is in direct mode. |
| 83,84,85        | MA7~MA9             | O    | Boot ROM address output bus  |
| 87              | MA10/LINK&ACT#      | O    | Boot ROM address output signal/Link & Active LED<br>In DIR mode, this pin represents the Boot ROM address bit 10 when at the time of boot ROM operation. When Boot ROM is not accessed, this pin acts as traffic-and- link led in LED MODE 0 or traffic led in LED MODE 1.   |
| 88              | MA11/FDX#           | O    | Boot ROM address output/Full-duplex LED<br>In DIR mode, this pin represents the Boot ROM address bit 11 when at the time of boot ROM operation. When Boot ROM is not accessed, this pin acts as full-duplex led.   |
| 89              | MA12 /<br>SPEED100# | O    | Boot ROM address output/ 100Mbps LED<br>In DIR mode, this pin represents the Boot ROM address bit 12 when at the time of boot ROM operation. When Boot ROM is not accessed, this pin acts as speed-100 led.  |
| 90              | MA13/SPEED10#       | O    | Boot ROM address output signal/10Mbps LED<br>In DIR mode, this pin represents the Boot ROM address bit 13 when at the time of boot ROM operation. When Boot ROM is not accessed, this pin acts as speed-10 led.  |
| 91,92,93,<br>94 | MA14~MA17           | O    | Boot ROM address output bus  |

## LED Pins (Please refer to p.11 "NOTE: LED Mode" for details.)

| Pin No.               | Pin Name                 | I/O | Description  |
|-----------------------|--------------------------|-----|--|
| <b>128QFP/128TQFP</b> |                          |     |  |
| 87                    | LINK&ACT#<br>/ ACT#      | O   | LED output pin, active low<br>mode 0 = Link and traffic LED. Active low to indicate normal link, and it will flash as a traffic LED when transmitting or receiving.<br>mode 1 = traffic LED only |
| 88                    | FDX#<br>/ FDX#           | O   | LED output pin, active low<br>mode 0 = Full duplex LED<br>mode 1 = Full duplex LED   |
| 89                    | SPEED100#<br>/ SPEED100# | O   | LED output pin, active low<br>mode 0 = 100Mbps LED<br>mode 1 = 100Mbps LED   |



# DM9102A

Single Chip Fast Ethernet NIC controller

|    |                     |   |  |
|----|---------------------|---|--|
| 90 | SPEED10#<br>/ LINK# | O | LED output pin, active low<br>mode 0 = 10Mbps LED<br>mode 1 = Link LED |
|----|---------------------|---|--|

## Network Interface

| Pin No.               | Pin Name     | I/O | Description   |
|-----------------------|--------------|-----|---|
| <b>128QFP/128TQFP</b> |              |     |   |
| 105,106               | RXI+<br>RX-  | I   | 100M/10Mbps differential input pair.<br>These two pins are differential receive input pair for 100BASE-TX and 10BASE-T. They are capable of receiving 100BASE-TX MLT-3 or 10BASE-T Manchester encoded data.           |
| 109,110               | TXO+<br>TXO- | O   | 100M/10Mbps differential output pair.<br>These two pins are differential output pair for 100BASE-TX and 10BASE-T. This output pair provides controlled rise and fall times designed to filter the transmitter output. |

## Miscellaneous Pins

| Pin No.               | Pin Name    | I/O         | Description   |
|-----------------------|-------------|-------------|---|
| <b>128QFP/128TQFP</b> |             |             |   |
| 36                    | CLOCKRUN#   | I/O,<br>O/D | Clockrun#<br>The clockrun# signal is used by the system to pause or slow down the PCI clock signal. It is used by the DM9102A to enable or disable suspension of the PCI clock signal or restart of the PCI clock. When the clockrun# signal is not used, this pin should connected to an external pull-down resistor.  |
| 71                    | TEST2       | I           | TEST mode control 2<br>In normal operation, this pin is pulled-high.  |
| 75                    | TEST1       | I           | TEST mode control 1<br>In normal operation, this pin is pulled low.   |
| 95                    | WOL/CSTSCHG | O           | Wake up signal/Card Status Change<br>This is multiplexed pin to provide Wake on LAN signal or Card Status Change. In a PCI system, it is used as a WOL signal. In a CardBus system, it is used as the Card Status Change output signal and is asynchronous to the clock signal. It indicates that a power management event has occurred in a CardBus system. The DM9102A can assert this pin if it detects link status change, or magic packet, or sample frame. The default is "normal low, active high pulse". DM9102A also support High/Low and Pulse/Level options. |
| 97                    | X2          | O           | Crystal feedback output pin used for crystal connection only.<br>Leave this pin open if oscillator is used.   |
| 98                    | X1/OSC      | I           | Crystal or Oscillator input. (25MHZ± 50ppm)<br>25MHz Oscillator or series-resonance, fundamental frequency crystal.   |
| 102                   | BGRES       | I           | Bandgap Voltage Reference Resistor.   |



# DM9102A

Single Chip Fast Ethernet NIC controller

|     |          |   |   |
|-----|----------|---|---|
|     |          |   | It connects to a 6200 $\Omega$ , 1% error tolerance resistor between this pin and BGRESG pin to provide an accurate current reference for DM9102A..   |
| 101 | BGRESG   | I | For Bandgap circuit<br>It is used together with the BGRESG pin.   |
| 116 | ISOLATE# | I | Isolate<br>This isolate signal is used to isolate the DM9102A from the system, and it is suitable for LAN on motherboard. When isolate signal is active low, it disables the DM9102A function and the DM9102A will not drive any outputs and sample inputs. In this case, the power consumption is minimum. |

## Power Pins

| Pin No.   | Pin Name | I/O | Description          |
|---|----------|-----|----------------------|
| <b>128QFP/128TQFP</b>                           |          |     |                      |
| 100,107,<br>108                                 | AGND     | P   | Analog ground        |
| 103,104,<br>111,112                             | AVDD     | P   | Analog power, +3.3V  |
| 8,9,15,22,28,29,35,37,45,<br>46,58,76,86,99,125 | DGND     | P   | Digital ground       |
| 4,5,12,18,19,25,32,42,52,<br>53,61,70,82,96,120 | DVDD     | P   | Digital power, +3.3V |

## NOTE :

### LED Mode

| Pin No.               | MODE 0                            | MODE 1                   |
|-----------------------|-----------------------------------|--------------------------|
| <b>128QFP/128TQFP</b> |                                   |                          |
| 87                    | LINK&ACT#<br>Link and traffic LED | ACT#<br>Traffic LED      |
| 88                    | FDX#<br>Full-duplex LED           | FDX#<br>Full-duplex LED  |
| 89                    | SPEED100#<br>100Mbps LED          | SPEED100#<br>100Mbps LED |
| 90                    | SPEED10#<br>10Mbps LED            | LINK#<br>Link LED        |

## Register Definition

### PCI Configuration Registers

The definitions of PCI Configuration Registers are based on the PCI specification revision 2.2 and provides the initialization and configuration information to operate the PCI interface in the DM9102A. All registers can be accessed

with byte, word, or double word mode. As defined in PCI specification 2.1, read accesses to reserve or unimplemented registers will return a value of "0." These registers are to be described in the following sections.

The default value of PCI configuration registers after reset.

| Description                            | Identifier | Address Offset | Value of Reset         |
|--|------------|----------------|------------------------|
| Identification                         | PCIID      | 00H            | 91021282H              |
| Command & Status                       | PCICS      | 04H            | 02100007H              |
| Revision                               | PCIRV      | 08H            | 02000031H              |
| Miscellaneous                          | PCILT      | 0CH            | BIOS determine         |
| I/O Base Address                       | PCIIO      | 10H            | System allocate        |
| Memory Base Address                    | PCIMEM     | 14H            | System allocate        |
| Reserved                               | -----      | 18H - 28H      | 00000000H              |
| CardBus ICS pointer                    | CIS        | 24H            | 00000000H              |
| Subsystem Identification               | PCISID     | 2CH            | load from SROM         |
| Expansion ROM Base Address             | PCIROM     | 30H            | 00000000H              |
| Capability Pointer                     | CAP_PTR    | 34H            | 00000050H              |
| Reserved                               | -----      | 38H            | 00000000H              |
| Interrupt & Latency                    | PCIINT     | 3CH            | System allocate bit7~0 |
| Device Specific Configuration Register | PCIUSR     | 40H            | 00000000H              |
| Power Management Register              | PCIPMR     | 50H            | C0310001H              |
| Power Management Control & Status      | PMCSR      | 54H            | 00000100H              |

### Key to Default

In the register description that follows, the default column takes the form <Reset Value>

Where :

<Reset Value>:

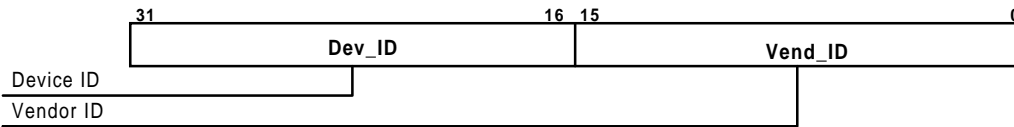
- 1 Bit set to logic one
- 0 Bit set to logic zero
- X No default value

<Access Type>:

- RO = Read only
- RW = Read/Write
- R/C: means Read / Write & Write "1" for Clear.

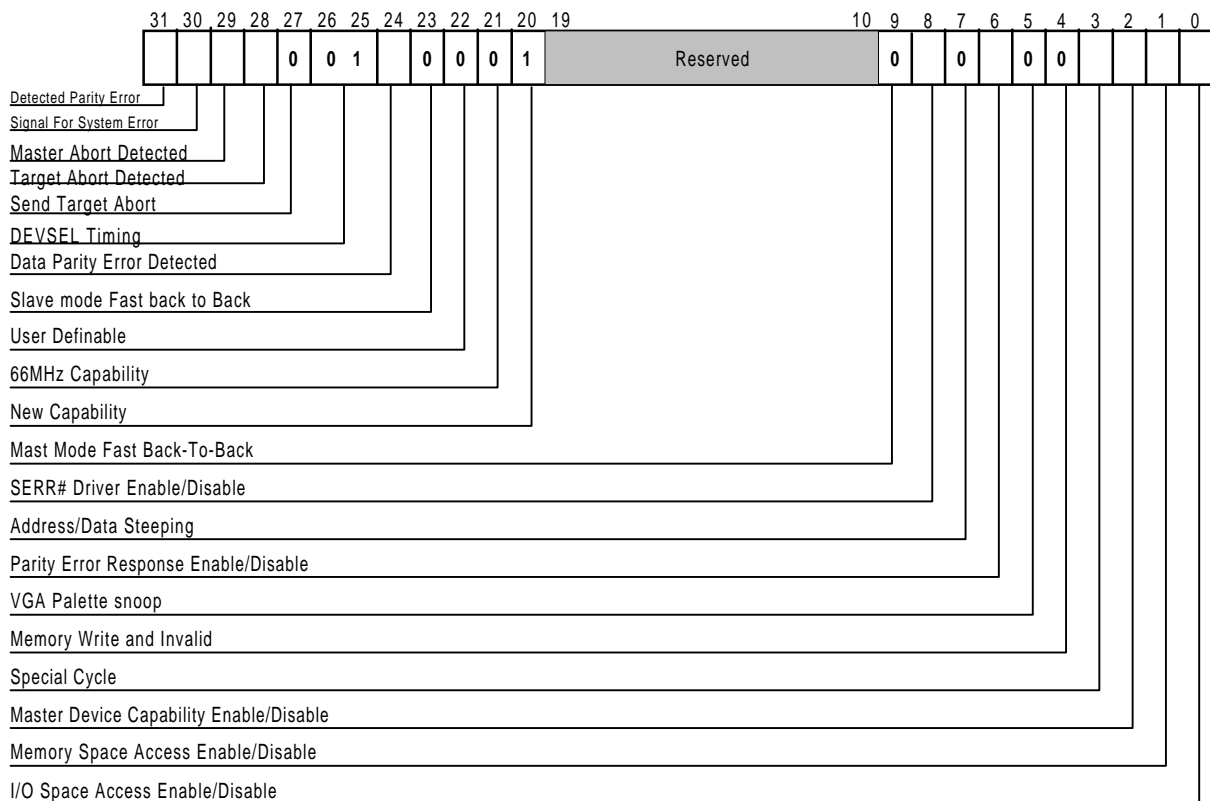
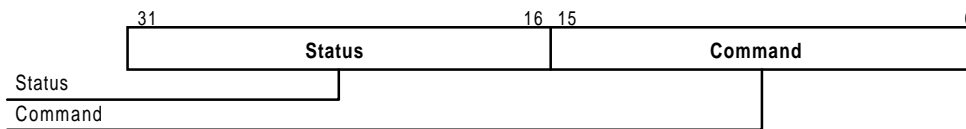


**Identification ID (xxxxxx00 - PCIID)**



| Bit   | Default | Type | Description   |
|-------|---------|------|---|
| 16:31 | 9102h   | RO   | The field identifies the particular device. Unique and fixed number for the DM9102A is 9102h. It is the product number assigned by DAVICOM. |
| 0:15  | 1282h   | RO   | This field identifies the manufacturer of the device. Unique and fixed number for Davicom is 1282h. It is a registered number from SIG.     |

**Command & Status (xxxxxx04 - PCICS)**





# DM9102A

Single Chip Fast Ethernet NIC controller

| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31    | 0       | R/C  | <p>Detected Parity Error</p> <p>The DM9102A samples the AD[0:31], C/BE[0:3]#, and the PAR signal to check parity and to set parity errors. In slave mode, the parity check falls on command phase and data valid phase (IRDY# and TRDY# both active). While in master mode, the DM9102A will check during each data phase of a memory read cycle for a parity error. During a memory write cycle, if an error occurs, the PERR# signal will be driven by the target. This bit is set by the DM9102A and cleared by writing "1". There is no effect by writing "0".</p> |
| 30    | 0       | R/C  | <p>Signal For System Error</p> <p>This bit is set when the SERR# signal is driven by the DM9102A. This system error occurs when an address parity is detected under the condition that bit 8 and bit 6 in command register below are set.</p>  |
| 29    | 0       | R/C  | <p>Master Abort Detected</p> <p>This bit is set when the DM9102A terminates a master cycle with the master-abort bus transaction.</p>  |
| 28    | 0       | R/C  | <p>Target Abort Detected</p> <p>This bit is set when the DM9102A terminates a master cycle due to a target-abort signal from other targets.</p>  |
| 27    | 0       | R/C  | <p>Send Target Abort (0 For No Implementation)</p> <p>The DM9102A will never assert the target-abort sequence.</p>   |
| 26:25 | 01      | R/C  | <p>DEVSEL Timing (01 Select Medium Timing)</p> <p>Medium timing of DEVSEL# means the DM9102A will assert DEVSEL# signal two clocks after FRAME# is sample "asserted."</p>  |
| 24    | 0       | R/C  | <p>Data Parity Error Detected</p> <p>This bit will take effect only when operating as a master and when a Parity Error Response Bit in command configuration register is set. It is set under two conditions:</p> <p>(i) PERR# asserted by the DM9102A in memory data read error, (ii) PERR# sent from the target due to memory data write error.</p>  |
| 23    | 0       | RO   | <p>Slave mode Fast Back-To-Back Capable (0 For Not Support)</p> <p>This bit is always reads "1" to indicate that the DM9102A is capable of accepting fast back-to-back transaction as a slave mode device.</p>   |
| 22    | 0       | RO   | User-Definable-Feature Supported (0 For Not Support)   |
| 21    | 0       | RO   | 66 MHz Capable (0 For No Capability)   |
| 20    | 1       | RO   | <p>New Capabilities (1 For Good Capability)</p> <p>This bit indicates whether this function implements a list of extended capabilities such as PCI power management. When set this bit indicates the presence of New Capabilities. A value of 0 means that this function does not implement New Capabilities.</p>  |
| 19:10 | 0       | RO   | Reserved   |
| 9     | 0       | RO   | <p>Master Mode Fast Back-To-Back (0 For Not Support)</p> <p>The DM9102A does not support master mode fast back-to-back capability and will not generate fast back-to-back cycles.</p>  |
| 8     | 0       | RW   | <p>SERR# Driver Enable/Disable</p> <p>This bit controls the assertion of SERR# signal output. The SERR# output will be asserted on detection of an address parity error and if both this bit</p>   |



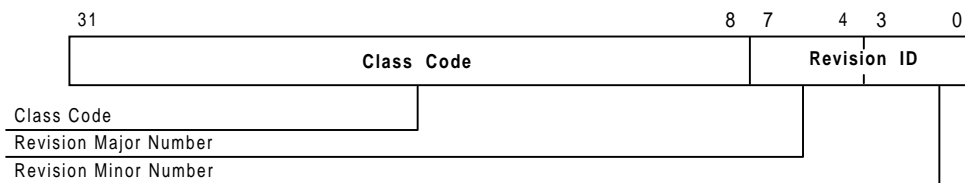


# DM9102A

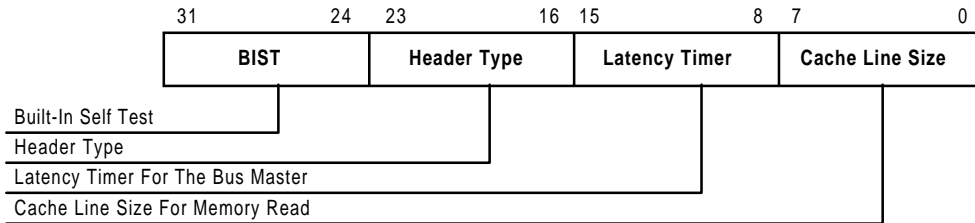
Single Chip Fast Ethernet NIC controller

|   |   |    |   |
|---|---|----|---|
|   |   |    | and bit 6 are set.  |
| 7 | 0 | RO | Address/Data Stepping (0 For No Stepping)   |
| 6 | 0 | RW | Parity Error Response Enable/Disable<br>Setting this bit will enable the DM9102A to assert PERR# on the detection of a data parity error and to assert SERR# for reporting address parity error.  |
| 5 | 0 | RO | VGA Palette Snooping (0 For Not Support)  |
| 4 | 0 | RO | Memory Write and Invalid (0 For Not Implementation)<br>The DM9102A only generates Memory write cycle.   |
| 3 | 0 | RO | Special Cycles (0 For Not Implementation)   |
| 2 | 1 | RW | Master Device Capability Enable/Disable<br>When this bit is set, DM9102A has the ability of master mode operation.  |
| 1 | 1 | RW | Memory Space Access Enable/Disable<br>This bit controls the ability of memory space access. The memory access includes memory mapped I/O access and Boot ROM access. As the system boots up, this bit will be enabled by BIOS for Boot ROM memory access. While in normal operation using memory mapped I/O access, this bit should be set by driver before memory access cycles. |
| 0 | 1 | RW | I/O Space Access Enable/Disable<br>This bit controls the ability of I/O space access. It will be set by BIOS after power on.  |

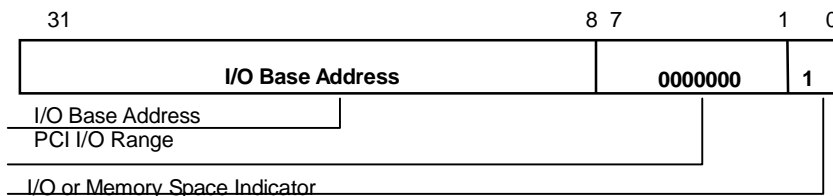
## Revision ID (xxxxxx08 - PCIRV)



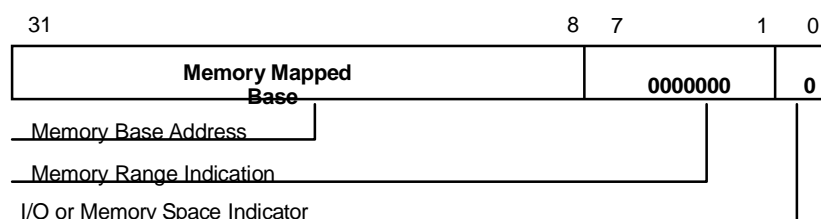
| Bit  | Default | Type | Description   |
|------|---------|------|---|
| 31:8 | 020000h | RO   | Class Code (020000h)<br>This is the standard code for Ethernet LAN controller.  |
| 7:4  | 0011    | RO   | Revision Major Number<br>This is the silicon-major revision number that will increase for the subsequent versions of the DM9102A. |
| 3:0  | 0001    | RO   | Revision Minor Number<br>This is the silicon-minor revision number that will increase for the subsequent versions of the DM9102A. |

**Miscellaneous Function (xxxxxx0c - PCILT)**


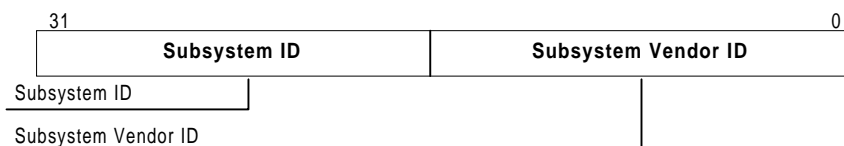
| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:24 | 00h     | RO   | Built In Self Test ( 00h Means Not Implementation)   |
| 23:16 | 00h     | RO   | Header Type ( 00h Means single function with Predefined Header Type )  |
| 15:8  | 00h     | RW   | Latency Timer For The Bus Master.<br>The latency timer is guaranteed by the system and measured by clock cycles. When the FRAME# asserted at the beginning of a master period by the DM9102A the value will be copied into a counter and start counting down. If the FRAME# is de-asserted prior to count expiration, this value is meaningless. When the count expires before GNT# is de-asserted, the master transaction will be terminated as soon as the GNT# is removed.<br>While GNT# signal is removed and the counter is non-zero, the DM9102A will continue with its data transfers until the count expires. The system host will read MIN_GNT and MAX_LAT registers to determine the latency requirement for the device and then initialize the latency timer with an appropriate value. The reset value of Latency Timer is determined by BIOS. |
| 7:0   | 00h     | RO   | Cache line Size For Memory Read Mode Selection ( 00h Means Not Implementation For Use)   |

**I/O Base Address (xxxxxx10 - PCIIO)**


| Bit  | Default   | Type | Description  |
|------|-----------|------|--|
| 31:7 | Undefined | RW   | PCI I/O Base Address<br>This is the base address value for I/O accesses cycles. It will be compared to AD[31:7] in the address phase of bus command cycle for the I/O resource access. |
| 6:1  | 000000    | RO   | PCI I/O Range Indication<br>It indicates that the minimum I/O resource size is 80h.  |
| 0    | 1         | RO   | I/O Space Or Memory Space Base Indicator<br>Determines that the register maps into the I/O space.( = 1 Indicates I/O Base)   |

**Memory Mapped Base Address (xxxxxx14 - PCIMEM)**


| Bit  | Default   | Type | Description   |
|------|-----------|------|---|
| 31:7 | Undefined | RW   | PCI Memory Base Address<br>This is the base address value for Memory accesses cycles. It will be compared to the AD[31:7] in the address phase of bus command cycle for the Memory resource access. |
| 6:1  | 000000    | RO   | PCI Memory Range Indication<br>It indicates that the minimum Memory resource size is 80h.   |
| 0    | 0         | RO   | I/O Space Or Memory Space Base Indicator<br>Determines that the register maps into the memory space( = 0 Indicates Memory Base)   |

**Subsystem Identification (xxxxxx2c - PCISID)**


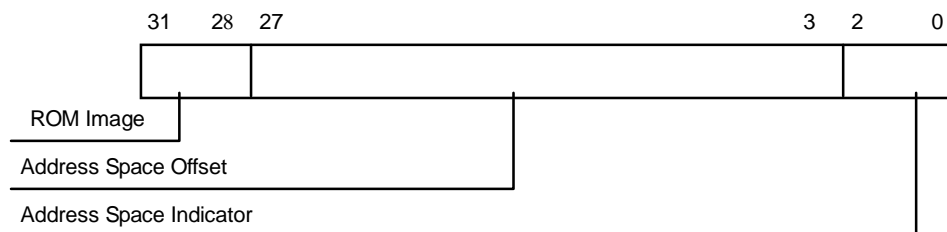
| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:16 | XXXXh   | RO   | Subsystem ID<br>It can be loaded from EEPROM word 1 and different from each card.    |
| 15:0  | XXXXh   | RO   | Subsystem Vendor ID<br>Unique number given by PCI SIG and loaded from EEPROM word 0. |

### CardBus CIS Pointer (xxxxxx28 - CCIS)

This Card Information Structure (CIS), also known as tuples, is a set of data structures saved in a nonvolatile memory on the CardBus Card. The data stored in CIS describes the product. Included in this data are the product manufacturer's name, product name, and most importantly, the hardware description. The CIS is supported in the boot ROM space or the memory space (serial ROM).

CIS is read upon card insertion into the socket. The software entity that traditionally reads the CIS is usually known as Card Services and Socket Services (CS & SS).

The CCIS pointer register is a read-only 32-bit register. This register points to one of the possible address space where the card information structure (CIS) begins. The pointer is used in a CardBus environment. The content of CCIS is loaded from the serial ROM after a hardware reset. A value of 0 in this register indicates that CIS is not supported.

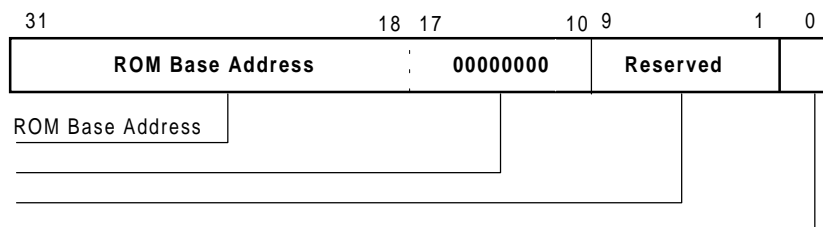


| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:28 | Note    | R/W  | ROM Image<br>The 4-bit ROM image field value when the CIS reside in an expansion ROM.  |
| 27:3  | Note    | R/W  | Address Space Offset<br>This field contains the address offset within the address space indicated by the address space indicator field (CCIS<2:0>)   |
| 2:0   | Note    | R/W  | Address Space Indicator<br>This field indicates the location of the CIS base address. The value of 2 indicates that the CIS is stored in the serial ROM, and 7, indicates that the CIS is stored in the expansion ROM. |

**note : read from serial ROM**

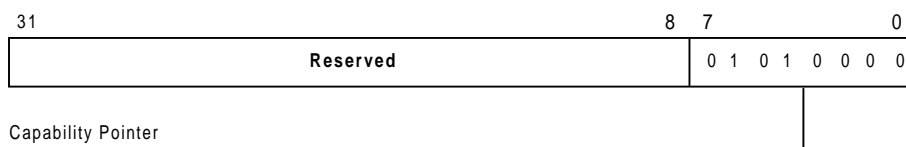


**Expansion ROM Base Address (xxxxxx30 - PCIROM)**

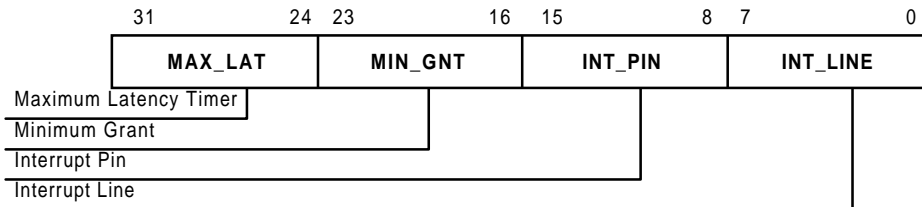


| Bit   | Default   | Type | Description  |
|-------|-----------|------|--|
| 31:10 | 00h       | RW   | ROM Base Address With 256K Boundary<br>PCIROM bit17~10 are hardwired to 0, indicating ROM Size is up to 256K Size                                      |
| 9:1   | 000000000 | RO   | Reserved Bits Read As 0  |
| 0     | 0         | RW   | Expansion ROM Decoder Enable/Disable<br>If this bit and the memory space access bit are both set to 1, the DM9102A will responds to its expansion ROM. |

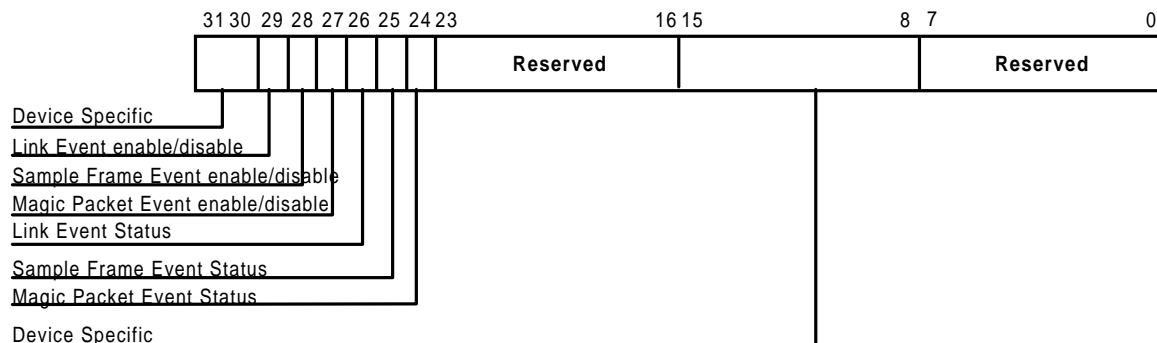
**Capabilities Pointer (xxxxxx34 - Cap\_Ptr)**



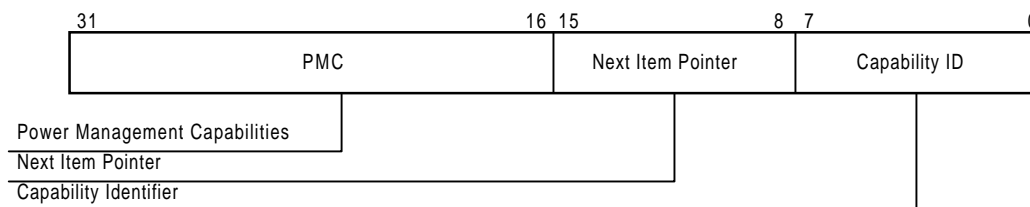
| Bit  | Default  | Type | Description   |
|------|----------|------|---|
| 31:8 | 000000h  | RO   | Reserved  |
| 7:0  | 01010000 | RO   | Capability Pointer<br>The Cap_Ptr provides an offset (default is 50h) into the function's PCI Configuration Space for the location of the first term in the Capabilities Linked List. The Cap_Ptr offset is DOUBLE WORD aligned so the two least significant bits are always "0"s |

**Interrupt & Latency Configuration (xxxxxx3c - PCIINT)**


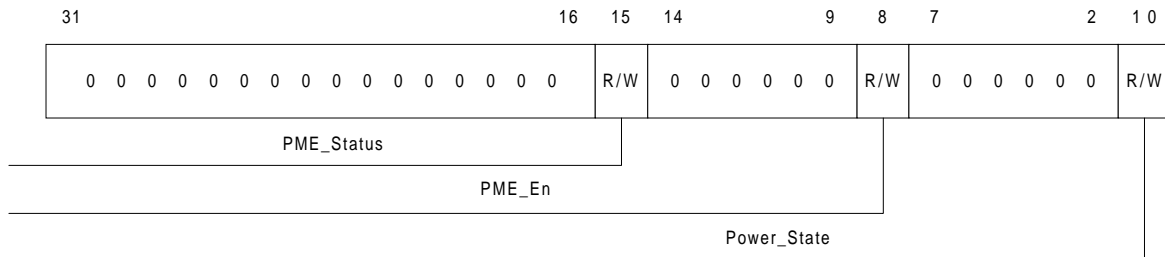
| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:24 | 28h     | RO   | Maximum Latency Timer that can be sustained (Read Only and Read As 28h)                      |
| 23:16 | 14h     | RO   | Minimum Grant<br>Minimum Length of a Burst Period (Read Only and Read As 14h)                |
| 15:8  | 01h     | RO   | Interrupt Pin read as 01h to indicate INTA#  |
| 7:0   | XXh     | RW   | Interrupt Line that Is Routed to the Interrupt Controller<br>The value depends on mainboard. |

**Device Specific Configuration Register (xxxxxx40h- PCIUSR)**


| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31    | 0       | RW   | Device Specific Bit (sleep mode)   |
| 30    | 0       | RW   | Device Specific Bit (snooze mode)  |
| 29    | 0       | RW   | When set enable Link Status Change Wake-up Event                                 |
| 28    | 0       | RW   | When set enable Sample Frame Wake-up Event                                       |
| 27    | 0       | RW   | When set enable Magic Packet Wake-up Event                                       |
| 26    | 0       | RO   | When set, indicates link change and Link Status Change Event occurred            |
| 25    | 0       | RO   | When set, indicates the sample frame is received and Sample Frame Event occurred |
| 24    | 0       | RO   | When set, indicates the Magic Packet is received and Magic packet Event occurred |
| 23:16 | 00h     | RO   | Reserved Bits Read As 0  |
| 15:8  | 00h     | RW   | Device Specific  |
| 7:0   | 00h     | RO   | Reserved Bits Read As 0  |

**Power Management Register (xxxxxx50h~PCIPMR)**


| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:27 | 11000   | RO   | <b>PME_Support</b><br>These five bits field indicate the power states in which the function may assert PME#. A value of 0 for any bit indicates that the function is not capable of asserting the PME# signal while in that power state.<br>bit27 → PME# support D0<br>bit28 → PME# support D1<br>bit29 → PME# support D2<br>bit30 → PME# support D3(hot)<br>bit31 → PME# support D3(cold)<br>DM9102A's bit31~27=11000 indicates PME# can be asserted from D3(hot) & D3(cold). |
| 26:22 | 00000   | RO   | Reserved (DM9102A not supports D1, D2)   |
| 21    | 1       | RO   | A "1" indicates that the function requires a device specific initialization sequence following transition to the D0 uninitialized state.   |
| 20    | 1       | RO   | <b>Auxiliary Power Source</b><br>This bit is only meaningful if bit31 is a "1".<br>This bit is "1" in DM9102A indicates that support for PME# in D3(cold) requires auxiliary power.  |
| 19    | 0       | RO   | <b>PME# Clock</b><br>"0" indicates that no PCI clock is required for the function to generate PME#.  |
| 18:16 | 001     | RO   | <b>Version</b><br>A value of 001 indicates that this function complies with the Revision 1.0 of the PCI Power Management Interface Specification.<br>A value of 010 is for DM9102A/A that complies with the revision 1.1 of the PCI Power Management Interface Specification.  |
| 15:8  | 00h     | RO   | <b>Next Item Pointer</b><br>The offset into the function's PCI Configuration Space pointing to the location of next item in the function's capability list is "00h"  |
| 7:0   | 01h     | RO   | <b>Capability Identifier</b><br>When "01h" indicates the linked list item as being the PCI Power Management Registers.   |

**Power Management Control/Status (xxxxxx54h~PMCSR)**


| Bit   | Default | Type | Description  |
|-------|---------|------|--|
| 31:16 | 0000h   | RO   | Reserved   |
| 15    | 0       | RW/C | PME_Status<br>This bit is set when the function would normally assert the PME# signal independent of the state of the PME_En bit. Writing a "1" to this bit will clear it. This bit defaults to "0" if the function does not support PME# generation from D3(cold). If the function supports PME# from D3(cold) then this bit is sticky and must be explicitly cleared by the operating system each time the operating system is initially loaded. |
| 14:9  | 000000  | RO   | Reserved.<br>It means that the DM9102A does not support reporting power consumption.   |
| 8     | 1       | RW   | PME_En<br>Write "1" to enables the function to assert PME#, write "0" to disable PME# assertion.<br>This bit defaults to "0" if the function does not support PME# generation from D3(cold).<br>If the function supports PME# from D3(cold) then this bit is sticky and must be explicitly cleared by the operating system each time the operating system is initially loaded.   |
| 7:2   | 000000  | RO   | Reserved   |
| 1:0   | 00      | RW   | This two bits field is both used to determine the current power state of a function and to set the function into a new power state. The definitions given below.<br>00 : D0<br>11 : D3(hot)  |



**Control and Status Registers (CR)**

The DM9102A implements 16 control and status registers, which can be accessed by the host. These CRs are double long word aligned. All CRs are set to their default values by

hardware or software reset unless otherwise specified. All Control and Status Registers with their definitions and offset from IO or memory Base Address are shown below:

| Register | Description                               | Offset from CSR Base Address | Default value after reset |
|----------|---|------------------------------|---------------------------|
| CR0      | System Control Register                   | 00H                          | FEC00000                  |
| CR1      | Transmit Descriptor Poll Demand           | 08H                          | FFFFFFFF                  |
| CR2      | Receive Descriptor Poll Demand            | 10H                          | FFFFFFFF                  |
| CR3      | Receive Descriptor Base Address Register  | 18H                          | 00000000                  |
| CR4      | Transmit Descriptor Base Address Register | 20H                          | 00000000                  |
| CR5      | Network Status Report Register            | 28H                          | FC000000                  |
| CR6      | Network Operation Mode Register           | 30H                          | 02040000                  |
| CR7      | Interrupt Mask Register                   | 38H                          | FFFE0000                  |
| CR8      | Statistical Counter Register              | 40H                          | 00000000                  |
| CR9      | External Management Access Register       | 48H                          | 044097FF                  |
| CR10     | Programming ROM Address Register          | 50H                          | Unpredictable             |
| CR11     | General Purpose Timer Register            | 58H                          | FFFE0000                  |
| CR12     | PHY Status Register                       | 60H                          | FFFFFFFX                  |
| CR13     | Sample Frame Access Register              | 68H                          | XXXXXX00                  |
| CR14     | Sample Frame Data Register                | 70H                          | Unpredictable             |
| CR15     | Watchdog And Jabber Timer Register        | 78H                          | 0000000H                  |

**Key to Default**

In the register description that follows, the default column takes the form:

<Reset Value>, <Access Type>

Where :

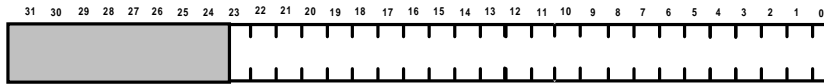
<Reset Value>:

- 1 Bit set to logic one
- 0 Bit set to logic zero
- X No default value

<Access Type>:

- RO = Read only
- RW = Read/Write
- RW/C = Read/Write and Clear
- WO = Write only

Reserved bits are shaded and should be written with 0.  
Reserved bits are undefined on read access.

**1. System Control Register (CR0)**


| Bit    | Name     | Default            | Description  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
|--------|----------|--------------------|--|--------|--------|--------------------|---------------|---|----------|---|------------|---------------|---|---|----------------|---|---|----------------|-------|---|---|---|-------|---|---|---|--------|---|---|---|--------|---|---|---|--------|---|---|---|---------|
| 24:22  | Reserved | 0,RO               | Reserved   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 21     | MRM      | 0,RW               | Memory Read Multiple<br>When set, the DM9102A will use memory read multiple command (C/BE3~0 = 1100) when it initialize the memory read burst transaction as a master device. When reset, it will use memory read command (C/BE3 ~ 0 = 0110) for the same master operation.  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 20     | Reserved | 0,RO               | Reserved   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 19:17  | TXAP     | 000,RW             | Transmit Automatic polling interval time<br>When set, the DM9102A will poll transmit descriptor automatically when it is in the suspend state due to buffer unavailable. The polling interval time is programmable based on the table shown below.<br><table border="1" style="margin-left: 20px;"> <thead> <tr> <th>Bit 19</th> <th>Bit 18</th> <th>Bit 17</th> <th>Time Interval</th> </tr> </thead> <tbody> <tr><td>0</td><td>0</td><td>0</td><td>No polling</td></tr> <tr><td>0</td><td>0</td><td>1</td><td>200us</td></tr> <tr><td>0</td><td>1</td><td>0</td><td>800us</td></tr> <tr><td>0</td><td>1</td><td>1</td><td>1.6ms</td></tr> <tr><td>1</td><td>0</td><td>0</td><td>12.8us</td></tr> <tr><td>1</td><td>0</td><td>1</td><td>25.6us</td></tr> <tr><td>1</td><td>1</td><td>0</td><td>51.2us</td></tr> <tr><td>1</td><td>1</td><td>1</td><td>102.4us</td></tr> </tbody> </table> | Bit 19 | Bit 18 | Bit 17             | Time Interval | 0 | 0        | 0 | No polling | 0             | 0 | 1 | 200us          | 0 | 1 | 0              | 800us | 0 | 1 | 1 | 1.6ms | 1 | 0 | 0 | 12.8us | 1 | 0 | 1 | 25.6us | 1 | 1 | 0 | 51.2us | 1 | 1 | 1 | 102.4us |
| Bit 19 | Bit 18   | Bit 17             | Time Interval  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 0        | 0                  | No polling   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 0        | 1                  | 200us  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 1        | 0                  | 800us  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 1        | 1                  | 1.6ms  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 0        | 0                  | 12.8us   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 0        | 1                  | 25.6us   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 1        | 0                  | 51.2us   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 1        | 1                  | 102.4us  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 16     | Reserved | 0,RO               | Reserved   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 15:14  | ABA      | 00,RW              | Address Boundary Alignment<br>When set, the DM9102A will execute each burst cycles to stop at the programmed address boundary. The address boundary can be programmed to be 8, 16, or 32 doubleword as shown below.<br><table border="1" style="margin-left: 20px;"> <thead> <tr> <th>Bit 15</th> <th>Bit 14</th> <th>Alignment Boundary</th> </tr> </thead> <tbody> <tr><td>0</td><td>0</td><td>Reserved</td></tr> <tr><td>0</td><td>1</td><td>8-double word</td></tr> <tr><td>1</td><td>0</td><td>16-double word</td></tr> <tr><td>1</td><td>1</td><td>32-double word</td></tr> </tbody> </table>  | Bit 15 | Bit 14 | Alignment Boundary | 0             | 0 | Reserved | 0 | 1          | 8-double word | 1 | 0 | 16-double word | 1 | 1 | 32-double word |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| Bit 15 | Bit 14   | Alignment Boundary |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 0        | Reserved           |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 0      | 1        | 8-double word      |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 0        | 16-double word     |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | 1        | 32-double word     |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 13:8   | BL       | 000000,<br>RW      | Burst Length<br>When reset, the DM9102A's burst length in one DMA transfer is limited by the amount of data in the receive FIFO ( when receive ) or the amount of free space in the transmit FIFO (when transmit ). When set, the DMA's burst length is limited by the programmed value. The permissible values are 0, 1, 2, 4, 8, 16, or 32 doublewords.  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 7      | Reserved | 0,RO               | Reserved   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 6:2    | Reserved | 00000              |  |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |
| 1      | Reserved | 0,RO               | Reserved   |        |        |                    |               |   |          |   |            |               |   |   |                |   |   |                |       |   |   |   |       |   |   |   |        |   |   |   |        |   |   |   |        |   |   |   |         |

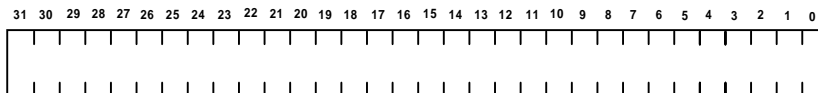


# DM9102A

Single Chip Fast Ethernet NIC controller

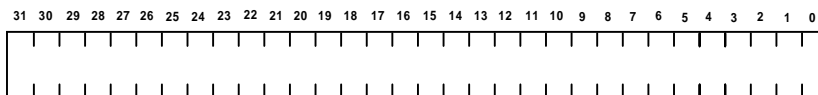
| Bit | Name | Default | Description   |
|-----|------|---------|---|
| 0   | SR   | 0,RW    | Software Reset<br>When set, the DM9102A will make a internal reset cycle. All consequent action to DM9102A2 should wait at least 32 PCI clock cycles to start and no necessary to reset this bit. |

## 2. Transmit Descriptor Poll Demand (CR1)



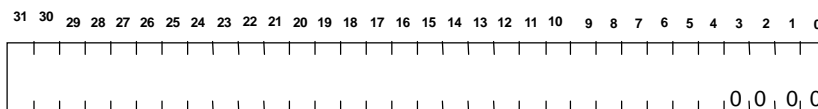
| Bit  | Name | Default          | Description  |
|------|------|------------------|--|
| 31:0 | TDP  | FFFFFFFFh<br>,WO | Transmit Descriptor Polling Command<br>Writing any value to this port will force DM9102A to poll the transmit descriptor. If the acting descriptor is not available, transmit process will return to suspend state. If the descriptor shows buffer available, transmit process will begin the data transfer. |

## 3. Receive Descriptor Poll Demand (CR2)

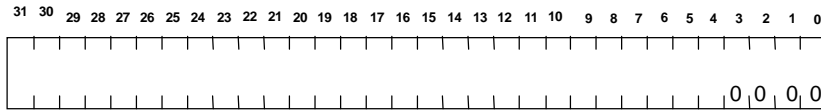


| Bit  | Name | Default          | Description  |
|------|------|------------------|--|
| 31:0 | RDP  | FFFFFFFFh<br>,WO | Receive Descriptor Polling Command<br>Writing any value to this port will force DM9102A to poll the receive descriptor. If the acting descriptor is not available, receive process will return to suspend state. If the descriptor shows buffer available, receive process will begin the data transfer. |

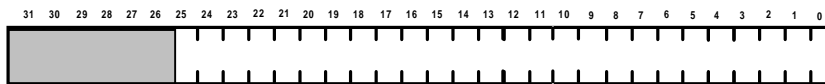
## 4. Receive Descriptor Base Address (CR3)



| Bit  | Name | Default          | Description  |
|------|------|------------------|--|
| 31:0 | RDBA | 00000000h<br>,RW | Receive Descriptor Base Address<br>This register defines base address of receive descriptor-chain. The receive descriptor- polling command after CR3 is set will make DM9102A to fetch the descriptor at the Base-Address. |

**5. Transmit Descriptor Base Address (CR4)**


| Bit  | Name | Default          | Description   |
|------|------|------------------|---|
| 31:0 | TDBA | 00000000h,<br>RW | Transmit Descriptor Base Address<br>This register defines base address of transmit descriptor-chain. The transmit descriptor- polling command after CR4 is set will make DM9102A to fetch the descriptor at the Base-Address. |

**6. Network Status Report Register (CR5)**


| Bit   | Name  | Default | Description   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
|-------|-------|---------|---|-------|-------|-------|----------------|---|---|---|--------------------------|---|---|---|---------------------------|---|---|---|---|---|---|---|---|---|---|---|--|---|---|---|-------------------------|---|---|---|---|---|---|---|--------------------------|
| 25:23 | SBEB  | 000,RO  | <p>System Bus Error Bits<br/>These bits are read only and used to indicate the type of system bus fetal error. Valid only when System Bus Error is set. The mapping bits are shown below.</p> <table border="1" style="margin-left: 40px;"> <thead> <tr> <th>Bit25</th> <th>Bit24</th> <th>Bit23</th> <th>Bus Error Type</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Parity error</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Master abort</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>Slave abort</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Reserved</td> </tr> <tr> <td>1</td> <td>X</td> <td>X</td> <td>Reserved</td> </tr> </tbody> </table>   | Bit25 | Bit24 | Bit23 | Bus Error Type | 0 | 0 | 0 | Parity error             | 0 | 0 | 1 | Master abort              | 0 | 1 | 0 | Slave abort                                       | 0 | 1 | 1 | Reserved                                    | 1 | X | X | Reserved   |   |   |   |                         |   |   |   |   |   |   |   |                          |
| Bit25 | Bit24 | Bit23   | Bus Error Type  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 0       | Parity error  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 1       | Master abort  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 0       | Slave abort   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 1       | Reserved  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 1     | X     | X       | Reserved  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 22:20 | TXPS  | 000,RO  | <p>Transmit Process State<br/>These bits are read only and used to indicate the state of transmit process. The mapping table is shown below.</p> <table border="1" style="margin-left: 40px;"> <thead> <tr> <th>Bit22</th> <th>Bit21</th> <th>Bit20</th> <th>Process State</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Transmit process stopped</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Fetch transmit descriptor</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>Move Setup Frame from the host memory</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Move data from host memory to transmit FIFO</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>Close descriptor by clearing owner bit of descriptor</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>Waiting end of transmit</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>Transmit end and Close descriptor by writing status</td> </tr> <tr> <td>1</td> <td>1</td> <td>1</td> <td>Transmit process suspend</td> </tr> </tbody> </table> | Bit22 | Bit21 | Bit20 | Process State  | 0 | 0 | 0 | Transmit process stopped | 0 | 0 | 1 | Fetch transmit descriptor | 0 | 1 | 0 | Move Setup Frame from the host memory             | 0 | 1 | 1 | Move data from host memory to transmit FIFO | 1 | 0 | 0 | Close descriptor by clearing owner bit of descriptor | 1 | 0 | 1 | Waiting end of transmit | 1 | 1 | 0 | Transmit end and Close descriptor by writing status | 1 | 1 | 1 | Transmit process suspend |
| Bit22 | Bit21 | Bit20   | Process State   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 0       | Transmit process stopped  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 1       | Fetch transmit descriptor   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 0       | Move Setup Frame from the host memory   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 1       | Move data from host memory to transmit FIFO   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 1     | 0     | 0       | Close descriptor by clearing owner bit of descriptor  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 1     | 0     | 1       | Waiting end of transmit   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 1     | 1     | 0       | Transmit end and Close descriptor by writing status   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 1     | 1     | 1       | Transmit process suspend  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 19:17 | RXPS  | 000,RO  | <p>Receive Process State<br/>These bits are read only and used to indicate the state of receive process. The mapping table is shown below.</p> <table border="1" style="margin-left: 40px;"> <thead> <tr> <th>Bit19</th> <th>Bit18</th> <th>Bit17</th> <th>Process State</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Receive process stopped</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>Fetch receive descriptor</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>Waiting for receive packet under buffer available</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>Move data from receive FIFO to host memory</td> </tr> </tbody> </table>  | Bit19 | Bit18 | Bit17 | Process State  | 0 | 0 | 0 | Receive process stopped  | 0 | 0 | 1 | Fetch receive descriptor  | 0 | 1 | 0 | Waiting for receive packet under buffer available | 0 | 1 | 1 | Move data from receive FIFO to host memory  |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| Bit19 | Bit18 | Bit17   | Process State   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 0       | Receive process stopped   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 0     | 1       | Fetch receive descriptor  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 0       | Waiting for receive packet under buffer available   |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |
| 0     | 1     | 1       | Move data from receive FIFO to host memory  |       |       |       |                |   |   |   |                          |   |   |   |                           |   |   |   |   |   |   |   |   |   |   |   |  |   |   |   |                         |   |   |   |   |   |   |   |                          |

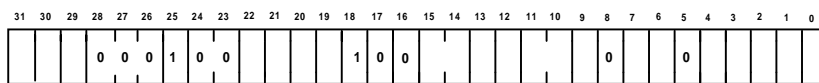


|    |      |      |  |
|----|------|------|--|
|    |      |      | 1 0 0 Close descriptor by clearing owner bit of descriptor<br>1 0 1 Close descriptor by writing status<br>1 1 0 Receive process suspended due to buffer unavailable<br>1 1 1 Purge the current frame from the receive FIFO because of unavailable receive buffer   |
| 16 | NIS  | 0,RW | Normal Interrupt Summary<br>Normal interrupt includes any of the three conditions :<br>CR5<0> – TXCI : Transmit Complete Interrupt<br>CR5<2> – TXDU : Transmit Buffer Unavailable<br>CR5<6> – RXCI : Receive Complete Interrupt  |
| 15 | AIS  | 0,RW | Abnormal Interrupt Summary<br>Abnormal interrupt includes any interrupt condition as shown below excluding Normal Interrupt conditions. They are TXPS(bit1), TXJT(bit3), TXFU(bit5), RXDU(bit7), RXPS(bit8), RXWT(bit9), TXER(bit10), GPT(bit11), SBE(bit13).  |
| 14 | ERI  | 0,RW | Early Receive Interrupt<br>This bit will be set when early receive interrupt has happened.   |
| 13 | SBE  | 0,RW | System Bus Error<br>The PCI system bus errors will set this bit. The type of system bus error is shown in CR5<25:23>.  |
| 12 | LCI  | 0,RW | Link Status Change Interrupt<br>This bit will be set when link status change.  |
| 11 | GPT  | 0,RW | General-purpose Timer Expired<br>This bit is set to indicate the general-purpose timer (described in CR11) has expired.  |
| 10 | TXER | 0,RW | Transmit Early Interrupt<br>Transmit Early Interrupt is set when the full packet data has been moved from host memory into transmit FIFO. It will inform the host to process next step before the transmission end. Transmit complete event CR5<0> will clear this bit automatically.  |
| 9  | RXWT | 0,RW | Receive Watchdog Timer Expired<br>This bit is set to indicate receive watchdog timer has expired.  |
| 8  | RXPS | 0,RW | Receive Process Stopped<br>This bit is set to indicate receive process enters the stopped state.   |
| 7  | RXDU | 0,RW | Receive Buffer Unavailable<br>This bit is set when the DM9102A fetches the next receive descriptor that is still owned by the host. Receive process will be suspended until a new frame enters or the receive polling command is set.  |
| 6  | RXCI | 0,RW | Receive Complete Interrupt<br>This bit is set when a received frame is fully moved into host memory and receive status has been written to descriptor. Receive process is still running and continues to fetch next descriptor.  |
| 5  | TXFU | 0,RW | Transmit FIFO Underrun<br>This bit is set when transmit FIFO has underrun condition during the packet transmission. It may happen due to the heavy load on bus, receive process dominates in full-duplex operation, or transmit buffer unavailable before end of packet. In this case, transmit process is placed in the suspend state and underrun error TDES0<1> is set. |
| 3  | TXJT | 0,RW | Transmit Jabber Timer Expired<br>This bit is set when the jabber timer expired with the transmitter is still active. Transmit process will be aborted and placed in the stop state. It also causes transmit jabber timeout TDES0<14> to assert.  |
| 2  | TXDU | 0,RW | Transmit Buffer Unavailable  |



|   |      |      |   |
|---|------|------|---|
|   |      |      | This bit is set when the DM9102A fetches the next transmit descriptor that is still owned by the host. Transmit process will be suspended until the transmit polling command is set or auto-polling timer time-out.                             |
| 1 | TXPS | 0,RW | Transmit Process Stopped<br>This bit is set to indicate transmit process enters the stopped state.  |
| 0 | TXCI | 0,RW | Transmit Complete Interrupt<br>This bit is set when a frame is fully transmitted and transmit status has been written to descriptor (the TDES1<31> is also asserted). Transmit process is still running and continues to fetch next descriptor. |

**7. Network Operation Mode Register (CR6)**



| Bit   | Name              | Default | Description   |
|-------|-------------------|---------|---|
| 30    | RXA               | 0,RW    | Receive All<br>When set, all incoming packet will be received, regardless the destination address. The address match is checked according to the CR6<7>, CR6<6>, CR6<4>, CR6<2>, CR6<0>, and RDES0<30> will show this match.  |
| 29    | NPFIFO            | 0,RW    | Set to not purge RX FIFO if RX buffer unavailable   |
| 28:26 | Reserved          | 000,RO  | Must be Zero  |
| 25    | Reserved          | 1,RO    | Must be One   |
| 24:23 | Reserved          | 00,RO   | Must be Zero  |
| 22    | TXTM              | 1,RW    | Transmit Threshold Mode<br>When set, the transmit threshold mode is 10Mb/s. When reset, the threshold mode is 100Mb/s. This bit is used together with CR6<15:14> to decide the exact threshold level.   |
| 21    | SFT               | 0,RW    | Store and Forward Transmit<br>When set, the packet transmission from MAC will be started after a full frame has been moved from the host memory to transmit FIFO. When reset, the packet transmission's start will depend on the threshold value specified in CR6<15:14>                                      |
| 20    | STI               | 0,RW    | Start Transmission Immediately<br>When this bit is set, the packet transmission from MAC will be started immediately after transmit FIFO's threshold level reaches 16 bytes, regardless of the setting in CR6<22> and CR6<15:14>. This mode will make transmit FIFO underrun condition to happen more easily. |
| 19    | Reserved          | 0,RO    | Reserved  |
| 18    | External MII_Mode | 1,RW    | 1: Select external MII interface.<br>0: Select external SRL interface.<br>In external MII mode that the pins TEST1, TEST2, and CLOCKRUN# are forced to low, the DM9102A bypasses internal PHY and uses external PHY, by setting this bit properly.<br>See page 66 for details.                                |
| 17    | Reserved          | 0,RO    | Reserved  |
| 16    | 1pkt              | 0,RW    | One Packet Mode<br>When this bit is set, only one packet is stored at TX FIFO.  |



| 15:14 | TSB      | 0,RW                          | <p>Threshold Bits</p> <p>These bits are set together with CR6&lt;22&gt; (chosed 10Mb or 100Mb) and will decide the exact FIFO threshold level. The packet transmission will start after the data level exceeds the threshold value.</p> <table border="1"> <thead> <tr> <th>Bit15</th> <th>Bit14</th> <th>Threshold(100M)</th> <th>Threshold(10M)</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>128</td> <td>72</td> </tr> <tr> <td>0</td> <td>1</td> <td>256</td> <td>96</td> </tr> <tr> <td>1</td> <td>0</td> <td>512</td> <td>128</td> </tr> <tr> <td>1</td> <td>1</td> <td>Reserved</td> <td>Reserved</td> </tr> </tbody> </table> | Bit15 | Bit14 | Threshold(100M) | Threshold(10M) | 0 | 0      | 128 | 72 | 0                 | 1 | 256 | 96                            | 1 | 0 | 512                          | 128 | 1 | 1 | Reserved | Reserved |
|-------|----------|-------------------------------|---|-------|-------|-----------------|----------------|---|--------|-----|----|-------------------|---|-----|-------------------------------|---|---|------------------------------|-----|---|---|----------|----------|
| Bit15 | Bit14    | Threshold(100M)               | Threshold(10M)  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 0     | 0        | 128                           | 72  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 0     | 1        | 256                           | 96  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 1     | 0        | 512                           | 128   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 1     | 1        | Reserved                      | Reserved  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 13    | TXSC     | 0,RW                          | <p>Transmit Start/stop Command</p> <p>When set, transmit process will begin by fetching the transmit descriptor for available packet data to be transmitted (running state). If the fetched descriptor is owned by the host, transmit process will enter the suspend state and transmit buffer unavailable (CR5&lt;2&gt;) is set. Otherwise it will begin to move data from host to FIFO and transmit out after reaching threshold level.</p> <p>When reset, transmit process is placed in the stopped state after completing the transmission of the current frame.</p>  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 12    | FCM      | 0,RW                          | <p>Force Collision Mode</p> <p>When set, the transmission process is forced to be the collision status. Meaningful only in the internal loopback mode.</p>  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 11:10 | LBM      | 0,RW                          | <p>Loopback Mode</p> <p>These bits decide two loopback modes besides normal operation. External loopback mode expects transmitted data back to receive path and makes no collision detection.</p> <table border="1"> <thead> <tr> <th>Bit11</th> <th>Bit10</th> <th>Loopback Mode</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>normal</td> </tr> <tr> <td>0</td> <td>1</td> <td>internal loopback</td> </tr> <tr> <td>1</td> <td>0</td> <td>internal PHY digital loopback</td> </tr> <tr> <td>1</td> <td>1</td> <td>internal PHY analog loopback</td> </tr> </tbody> </table>   | Bit11 | Bit10 | Loopback Mode   | 0              | 0 | normal | 0   | 1  | internal loopback | 1 | 0   | internal PHY digital loopback | 1 | 1 | internal PHY analog loopback |     |   |   |          |          |
| Bit11 | Bit10    | Loopback Mode                 |   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 0     | 0        | normal                        |   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 0     | 1        | internal loopback             |   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 1     | 0        | internal PHY digital loopback |   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 1     | 1        | internal PHY analog loopback  |   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 9     | FDM      | 0,RW                          | <p>Full-duplex Mode</p> <p>This bit is set to make DM9102A operate in the full-duplex mode. Transmit and receive processes can work simultaneously.</p> <p>There is no collision detection needed during this mode operation.</p>   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 8     | Reserved | 0,RO                          | Must be zero.   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 7     | PAM      | 0,RW                          | <p>Pass All Multicast</p> <p>When set, any packet with a multicast destination address is received by the DM9102A. The packet with a physical address will also be filtered based on the filter mode setting.</p>   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 6     | PM       | 1,RW                          | <p>Promiscuous mode</p> <p>When set, any incoming valid frame is received by the DM9102A, and no matter what the destination address. The DM9102A is initialized to this mode after reset operation.</p>  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 5     | Reserved | 0,RO                          | Must be Zero.   |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |
| 4     | IAFM     | 0,RO                          | <p>Inverse Address Filtering Mode</p> <p>It is set to indicate the DM9102A operate in a Inverse Filtering Mode. This is a read only bit and mapped from the setup frame together with CR6&lt;2&gt;, CR6&lt;0&gt; setting. That is, it is valid only during perfect filtering mode.</p>  |       |       |                 |                |   |        |     |    |                   |   |     |                               |   |   |                              |     |   |   |          |          |

|   |      |      |   |
|---|------|------|---|
| 3 | PBF  | 0,RW | <b>Pass Bad Frame</b><br>When set, the DM9102 is indicated to receive the bad frames including runt packets, truncated frames caused by the FIFO overflow. The bad frame also has to pass the address filtering if the DM9102A is not set in promiscuous mode.  |
| 2 | HOFM | 0,RO | <b>Hash-only Filter Mode</b><br>This is a read-only bit and mapped from the set-up frame together with bit4,0 of CR6.<br>It is set to indicate the DM9102A operate in a Hash-only Filtering Mode.   |
| 1 | RXRC | 0,RW | <b>Receive Start/Stop Command</b><br>When set, receive process will begin by fetching the receive descriptor for available buffer to store the new-coming packet (placed in the running state). If the fetched descriptor is owned by the host (no descriptor is owned by the DM9102A), the receive process will enter the suspend state and receive buffer unavailable CR5<7> sets. Otherwise it runs to wait for the packet's income. When reset, receive process is placed in the stopped state after completing the reception of the current frame. |
| 0 | HPFM | 0,RO | <b>Hash/Perfect Filter Mode</b><br>This is a read only bit and mapped from the setup frame together with CR6<4>, CR6<2>. When reset, the DM9102A does a perfect address filter of incoming frames according to the addresses specified in the setup frame. When set, the DM9102A does a imperfect address filtering for the incoming frame with a multicast address according to the hash table specified in the setup frame. The filtering mode (perfect / imperfect) for the frame with a physical address will depend on CR6<2>.                     |

**8. Interrupt Mask Register (CR7)**

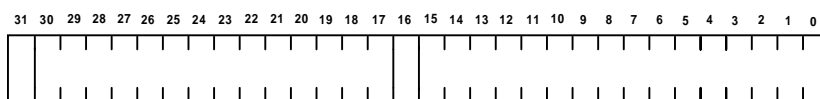

| Bit | Name | Default | Description  |
|-----|------|---------|--|
| 16  | NISE | 0,RW    | <b>Normal Interrupt Summary Enable</b><br>This bit is set to enable the interrupt for Normal Interrupt Summary.<br>Normal interrupt includes three conditions :<br>CR5<0> – TXCI : Transmit Complete Interrupt<br>CR5<2> – TXDU : Transmit Buffer Unavailable<br>CR5<6> – RXCI : Receive Complete Interrupt  |
| 15  | AISE | 0,RW    | <b>Abnormal Interrupt Summary Enable</b><br>This bit is set to enable the interrupt for Abnormal Interrupt Summary.<br>Abnormal interrupt includes all interrupt condition as shown below excluding Normal Interrupt conditions. They are TXPS(bit1), TXJT(bit3), TXFU(bit5), RXDU(bit7), RXPS(bit8), RXWT(bit9), TXER(bit10), GPT(bit11), SBE(bit13). |
| 14  | ERIE | 0,RW    | <b>Early Receive Interrupt Enable</b><br>This bit is set to enable the interrupt for Early Receive.  |
| 13  | SBEE | 0,RW    | <b>System Bus Error Enable</b><br>When set together with CR7<15>, CR5<13>, it enables the interrupt for System Bus Error. The type of system bus error is shown in CR5<24:23>.   |
| 12  | LCIE | 0,RW    | <b>Link Status Change Interrupt Enable</b><br>This bit is set to enable the interrupt for link status change.  |





|    |          |      |  |
|----|----------|------|--|
| 11 | GPTE     | 0,RW | General-purpose Timer Expired Enable<br>This bit is set together with CR7<15>, CR5<11> then it will enable the interrupt for the condition of the general-purpose timer (described in CR11) expired. |
| 10 | TXERE    | 0,RW | Transmit Early Interrupt Enable<br>This bit is set together with CR7<16>, CR5<10> then it enables the interrupt of the early transmit event.   |
| 9  | RXWTE    | 0,RW | Receive Watchdog Timer Expired Enable<br>When this bit and CR7<15>, (CR5<9> are set together, it enable the interrupt of the condition of the receive watchdog timer expired.                        |
| 8  | RXPSE    | 0,RW | Receive Process Stopped Enable<br>When set together with CR7<15> and CR5<8>. This bit is set to enable the interrupt of receive process stopped condition.   |
| 7  | RXDUE    | 0,RW | Receive Buffer Unavailable Enable<br>When this bit and CR7<15>, CR5<7> are set together, it will enable the interrupt of receive buffer unavailable condition.                                       |
| 6  | RXCIE    | 0,RW | Receive Complete Interrupt Enable<br>When this bit and CR7<16>, CR5<6> are set together, it will enable the interrupt of receive process complete condition.   |
| 5  | TXFUE    | 0,RW | Transmit FIFO Underrun Enable<br>When set together with CR7<15>, CR5<5>, it will enable the interrupt of transmit FIFO underrun condition.   |
| 4  | Reserved | 0,RO | Reserved   |
| 3  | TXJTE    | 0,RW | Transmit Jabber Timer Expired Enable<br>When this bit and CR7<15>, CR5<3> are set together, it enables the interrupt of transmit Jabber Timer Expired condition.                                     |
| 2  | TXDUE    | 0,RW | Transmit Buffer Unavailable Enable<br>When this bit and CR7<16>, CR5<2> are set together, transmit buffer unavailable interrupt is enabled.  |
| 1  | TXPSE    | 0,RW | Transmit Process Stopped Enable<br>When this bit is set together with CR7<15> and CR5<1>, it will enable the interrupt of the transmit process stopped   |
| 0  | TXCIE    | 0,RW | Transmit Complete Interrupt Enable<br>When this bit and CR7<16>, CR5<0> are set, the transmit interrupt is enabled.  |

**9. Statistical Counter Register (CR8)**

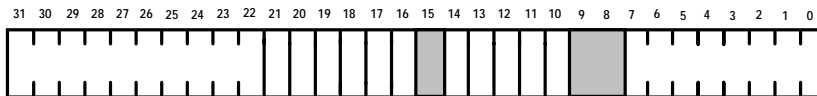


| Bit   | Name | Default | Description   |
|-------|------|---------|---|
| 31    | RXFU | 0,RO    | Receive Overflow Counter Overflow<br>This bit is set when the Purged Packet Counter (RXDU) has an overflow condition. It is a read only register bit. |
| 30:17 | RXDU | 0,RO    | Receive Purged Packet Counter<br>This is a statistic counter to indicate the purged received packet count upon FIFO overflow.                         |



|      |      |      |   |
|------|------|------|---|
| 16   | RXPS | 0,RO | Receive Missed Counter Overflow<br>This bit is set when the Receive Missed Frame Counter (RXCI) has an overflow condition. It is a read only register bit.                    |
| 15:0 | RXCI | 0,RO | Receive Missed Frame Counter<br>This is a statistic counter to indicate the Receive Missed Frame Count when there is a host buffer unavailable condition for receive process. |

**10. PROM & Management Access Register (CR9)**

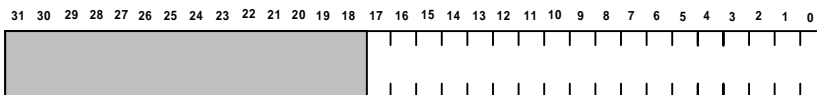


| Bit   | Name      | Default | Description  |
|-------|-----------|---------|--|
| 31:22 | Undefined | X,RO    | Undefined  |
| 21    | LES       | 0,RO    | Load EEPROM status<br>It is set to indicate the load of EEPROM is finished.  |
| 20    | RLM       | 0,RW    | Reload EEPROM<br>It is set to reload the content of EEPROM.  |
| 19    | MDIN      | 0,RO    | MII Management Data_In<br>This is read only bit to indicate the MDIO input data.   |
| 18    | MRW       | 0,RW    | MII Management Read/Write Mode Selection<br>This bit defines the Read/Write Mode for MII management interface for PHY access.  |
| 17    | MDOUT     | 0,RW    | MII Management Data_Out<br>This bit is used to generate the output data signal for the MDIO pin.   |
| 16    | MDCLK     | 0,RW    | MII Management Clock<br>This bit is used to generate the output clock signal for the MDC pin.  |
| 15    | MBO       | 1,RO    | Must be One.   |
| 14    | MRC       | 0,RW    | Memory Read Control<br>This bit is set to perform the read operation for the Boot PROM or EEPROM access.   |
| 13    | EWC       | 0,RW    | Memory Write Control<br>This bit is set to perform the write operation for the Boot PROM (Multiplex mode) or EEPROM access.  |
| 12    | BRS       | 1,RW    | Boot ROM Selected<br>This bit is set to select the Boot ROM access for memory interface.   |
| 11    | ERS       | 0,RW    | EEPROM Selected<br>This bit is set to select the EEPROM access for memory interface.   |
| 10    | XRS       | 1,RW    | External Register Selected<br>This bit is set to select an external register.  |
| 9:8   | MBO       | 1,RO    | Must be One  |
| 7:0   | DATA      | 1,RW    | Data input/output of Boot ROM<br>This field contains the data which reads from or write to the Boot ROM when the Boot ROM mode is selected. ( CR9<12> = 1 )<br>If EEPROM is selected ( CR9<11> = 1 ), then CR9<3:0> are connected the serial ROM control pins. |



|   |         |      |  |
|---|---------|------|--|
| 3 | CRDOOUT | 1,RW | Data_Out from EEPROM<br>This bit is set to reflect the signal status of EEDI pin when EEPROM mode is selected.   |
| 2 | CRDIN   | 1,RW | Data_In to EEPROM<br>This bit is set to generate the output signal to EEDO pin when EEPROM mode is selected.     |
| 1 | CRCLK   | 1,RW | Clock to EEPROM<br>This bit is set to generate the output clock to EECLK pin when EEPROM mode is selected.       |
| 0 | CRCS    | 1,RW | Chip_Select to EEPROM<br>This bit is set to generate the output signal to EECS pin when EEPROM mode is selected. |

**11. Programming ROM Address Register (CR10)**



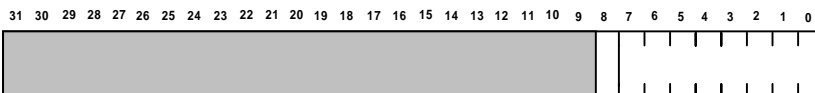
| Bit  | Name | Default       | Description  |
|------|------|---------------|--|
| 17:0 | BADR | Unpredictable | Boot ROM Address<br>This field contains the address pointer for Boot ROM when the mode of programming by register is selected. |

**12. General Purpose Timer Register (CR11)**



| Bit  | Name  | Default  | Description  |
|------|-------|----------|--|
| 16   | TCON  | 0,RW     | Continuous Mode of Timer<br>When this bit is set, the timer will continuously re-initiated upon the set time is up. When reset, the timer will be one-shot response after BCLK value is programmed.        |
| 15:0 | MBCLK | 0000h,RW | Multiple of Base Clock<br>This field set the iteration number of base clock. The base clock duration is defined to be<br>81.92us --- for MII port/100M is selected<br>2us --- for MII port/10M is selected |

**13. PHY Status Register (CR12)**



| Bit | Name | Default | Description |
|-----|------|---------|-------------|
|-----|------|---------|-------------|

|     |           |                |   |
|-----|-----------|----------------|---|
| 8   | GEPC      | X,RW           | <p>GEPC Bits Control</p> <p>When in initialization, this bit is set and the unique "80h" must be written to the GEPC(7:0). After initialization, this bit is reset and it controls the functional mode of GEPC in bit0~7.</p>   |
| 7   | GEPC(7)   | X,RW           | <p>General PHY Reset Control</p> <p>It must be set to "1" if CR12&lt;8&gt; is set.</p> <p>When CR12&lt;8&gt; is reset, write "1" to this bit will reset the PHY of the DM9102A.</p>   |
| 6:0 | GEPC(6:0) | XXXXXXX<br>,RW | <p>General PHY Status</p> <p>When CR12&lt;8&gt; is set at initialization, it operates the only write operation and write the unique "0000000" to these seven bits.</p> <p>After initialization, CR12&lt;8&gt; is reset, write operation is meaningless and read these seven bits to indicate the PHY status.</p> <p>These status bits are shown below.</p> <p>bit 6:Current Media Link Status</p> <p>bit 5:Signal Detection</p> <p>bit 4:RX-lock</p> <p>bit 3:Internal PHY Link status (the same as bit2 of PHY Register)</p> <p>bit 2:Full-duplex</p> <p>bit 1:Speed 100Mbps link</p> <p>bit 0:Speed 10Mbps link</p> |

#### 14. Sample Frame Access Register (CR13) (reference to Power Management section)



| register  | general definition                        | bit8 ~ 3 | RW |
|-----------|---|----------|----|
| TxFIFO    | transmit FIFO access port                 | 32h      | RW |
| RxFIFO    | receive FIFO access port                  | 35h      | RW |
| DiagReset | general reset for diagnostic pointer port | 38h      | W  |

#### 15. Sample Frame Data Register (CR14) (reference to Power Management section)



#### 16. Watchdog and Jabber Timer Register (CR15)



| Bit   | Name     | Default | Description |
|-------|----------|---------|-------------|
| 31:25 | Reserved | 0,RO    | Reserved    |

| 24:22 | ERIT     | 000,RW    | <p>Early Receive Interrupt Threshold</p> <p>These three bits determine the threshold of the received packet data from RX FIFO to host memory.</p> <table border="1"> <thead> <tr> <th>bit24</th> <th>bit 23</th> <th>bit22</th> <th>threshold (percentage)</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>0</td> <td>Disable</td> </tr> <tr> <td>0</td> <td>0</td> <td>1</td> <td>12.5%</td> </tr> <tr> <td>0</td> <td>1</td> <td>0</td> <td>25.0%</td> </tr> <tr> <td>0</td> <td>1</td> <td>1</td> <td>37.5%</td> </tr> <tr> <td>1</td> <td>0</td> <td>0</td> <td>50.0%</td> </tr> <tr> <td>1</td> <td>0</td> <td>1</td> <td>62.5%</td> </tr> <tr> <td>1</td> <td>1</td> <td>0</td> <td>75.0%</td> </tr> <tr> <td>1</td> <td>1</td> <td>1</td> <td>87.5%</td> </tr> </tbody> </table> | bit24 | bit 23 | bit22 | threshold (percentage) | 0 | 0 | 0 | Disable | 0 | 0 | 1 | 12.5% | 0 | 1 | 0 | 25.0% | 0 | 1 | 1 | 37.5% | 1 | 0 | 0 | 50.0% | 1 | 0 | 1 | 62.5% | 1 | 1 | 0 | 75.0% | 1 | 1 | 1 | 87.5% |
|-------|----------|-----------|--|-------|--------|-------|------------------------|---|---|---|---------|---|---|---|-------|---|---|---|-------|---|---|---|-------|---|---|---|-------|---|---|---|-------|---|---|---|-------|---|---|---|-------|
| bit24 | bit 23   | bit22     | threshold (percentage)   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 0     | 0        | 0         | Disable  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 0     | 0        | 1         | 12.5%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 0     | 1        | 0         | 25.0%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 0     | 1        | 1         | 37.5%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 1     | 0        | 0         | 50.0%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 1     | 0        | 1         | 62.5%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 1     | 1        | 0         | 75.0%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 1     | 1        | 1         | 87.5%  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 21:16 | FIFOT    | 000000,RW | <p>RX FIFO flow control threshold option</p> <p>The value of bit21~16 determine the threshold of RX FIFO overflow when in flow control mode. The exact threshold is 32bytes multiplied by this value.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 15    | TXPM     | 0,RW      | <p>Transmit pause packet condition control</p> <p>1 = Indicate Transmit pause packet either CR15&lt;11&gt; or CR15&lt;12&gt; is set.<br/>0 = Indicate Transmit pause packet both CR15&lt;11&gt; and CR15&lt;12&gt; are set.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 14    | TXP0     | 0,RW      | <p>Transmit pause packet</p> <p>Set to Transmit pause packet with pause timer = 0000h</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 13    | TXPF     | 0,RW      | <p>Transmit pause packet</p> <p>Set to Transmit pause packet with pause timer = FFFFh, this bit will be cleared if packet had transmitted.</p>   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 12    | TXPE1    | 0,RW      | <p>Transmit pause packet enable</p> <p>Set to enable Transmit pause packet if descriptor unavailable</p>   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 11    | TXPE2    | 0,RW      | <p>Transmit pause packet enable</p> <p>Set to enable Transmit pause packet with time = FFFFh if FIFO near overflow, or with time = 0000h if FIFO empty.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 10    | FLCE     | 0,RW      | <p>Flow Control Enable</p> <p>Set to enable the decode of the pause packet.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 9     | RXPS     | 0,R/C     | <p>The latched status of the decode of the pause packet.</p>   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 8     | Reserved | 0,RO      | Reserved.  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 7     | RXPCS    | 0,RO      | Of the decode of the pause packet.   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 6     | VLAN     | 0,RW      | <p>VLAN Capability Enable</p> <p>It is set to enable the VLAN mode.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 5     | TWDR     | 0,RW      | <p>Time Interval of Watchdog Release</p> <p>This bit is used to select the time interval between receive Watchdog timer expiration until re-enabling of the receive channel. When this bit is set, the time interval is 40~48 bits time. When this bit is reset, it is 16~24 bits time.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 4     | TWDE     | 0,RW      | <p>Watchdog Timer Disable</p> <p>When set, the Watchdog Timer is disabled. Otherwise it is enabled.</p>  |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |
| 3     | Reserved | 0,RO      | Reserved   |       |        |       |                        |   |   |   |         |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |   |   |   |       |



# DM9102A

Single Chip Fast Ethernet NIC controller

|   |      |      |   |
|---|------|------|---|
| 2 | JC   | 0,RW | <p>Jabber Clock</p> <p>When set, the transmission is cut off after a range of 2048 bytes to 2560 bytes is transmitted.</p> <p>When resets, transmission for the 10Mbps port is cut off after a range of 26ms to 33ms.</p> <p>When resets, transmission for the 100Mbps port is cut off after a range of 2.6ms to 3.3ms.</p>                 |
| 1 | TUNJ | 0,RW | <p>Transmit Unjabber Interval</p> <p>This bit is used to select the time interval between transmit jabber timer expiration until re-enabling of the transmit channel. When set, transmit channel is released right after the jabber expiration. When reset, the time interval is 365~420ms for 10Mb/s port and 36.5~42.0ms for 100Mb/s.</p> |
| 0 | TJE  | 0,RW | <p>Transmit Jabber Disable</p> <p>When set, the transmit Jabber Timer is disabled. Otherwise it is enabled.</p>   |



## CardBus Status Changed Registers

The DM9102A implements four status changed registers. These status changed registers are accessed by the CardBus system software. These registers are mapped

only to the memory address space and not to the I/O address space.

### 1. Function Event Register: (offset 80h)

| Bit   | Name                  | Default | Description  |
|-------|-----------------------|---------|--|
| 0:3   | Reserved              | R/W     | Unpredictable on read  |
| 4     | General Wake-up Event | R/WC    | This bit is set when the DM9102A has detected a power management event. This bit is cleared upon power-up reset and by write 1. It is unaffected by either hardware or software reset. When the PME_Status bit in the PCI configuration is cleared, this bit is automatically cleared as well. |
| 5:14  | Reserved              | R/W     | Unpredictable on read  |
| 15    | Interrupt             | R/WC    | This bit is set when there is an interrupt pending. This bit is cleared by write 1. This bit is cleared upon hardware or software reset.   |
| 16:31 | Reserved              | R/W     | Unpredictable on read  |

### 2. Function Event Mask Register: (offset 84h)

| Bit   | Name                         | Default | Description  |
|-------|------------------------------|---------|--|
| 0:3   | Reserved                     | R/W     | Unpredictable on read  |
| 4     | General Wake-up Event Enable | R/WC    | When set together with the Wake-up Event Summary Enable bit (Function Event Mask Register<14>), enables the assertion of the CSTSCHG pin. To disable the assertion of the CSTSCHG, the PME_Enable bit in the PCI configuration register (PMC<8>) must be cleared as well. This bit is cleared upon power up reset. |
| 5:13  | Reserved                     | R/W     | Unpredictable on read  |
| 14    | Wake-up Event Summary Enable | R/W     | When set together with the General Wake-up Event Enable bit (Function Event Mask Register<4>), enables the assertion of the CSTSCHG pin. To disable the assertion of the CSTSCHG pin, the PME_Enable bit in the PCI configuration register (PMC<8>) must be cleared as well. This is cleared upon power up reset.  |
| 15    | Interrupt Register Enable    | R/W     | When set, enable the assertion of the interrupt pin (INT#). This bit is cleared upon hardware or software reset.   |
| 16:31 | Reserved                     | R/W     | Unpredictable on read  |

### 3. Function Present State Register: (offset 88h)

| Bit | Name     | Default | Description           |
|-----|----------|---------|-----------------------|
| 0:3 | Reserved | R/W     | Unpredictable on read |



|       |                       |     |   |
|-------|-----------------------|-----|---|
| 4     | General Wake-up Event | R   | This bit reflects the current state of the wake-up event. It is cleared when either the General Wake-up Event in the Function Event Register is cleared or when the PME_Status in the PMC is cleared.<br>This bit is cleared upon hardware or software reset. |
| 5:14  | Reserved              | R/W | Unpredictable on read   |
| 15    | Interrupt             | R   | This bit reflects the internal state of a function specific interrupt. It is cleared when the event that caused the interrupt was either masked in CSR7, or cleared in CSR5.<br>This bit is cleared upon hardware or software reset.                          |
| 16:31 | Reserved              | R/W | Unpredictable on read   |

**4. Function Force Event Register: (offset 8Ch)**

| Bit   | Name            | Default | Description  |
|-------|-----------------|---------|--|
| 0:3   | Reserved        | R/W     | Unpredictable on read  |
| 4     | Force Wake-up   | W       | Writing 1 to this bit sets the wake-up event field in the Function Event Register (Function Event Register<4>), but not in the Function Present State Register (Function Present State Register<4>).<br>Writing 0 has no effect. |
| 5:14  | Reserved        | R/W     | Unpredictable on read  |
| 15    | Force Interrupt | W       | Writing 1 to this bit sets the interrupt field in the Function Event Register (Function Event Register<15>), but not in the Function Present State Register (Function Present State Register<15>).<br>Writing 0 has no effect.   |
| 16:31 | Reserved        | R/W     | Unpredictable on read  |



**PHY Management Registers**

| Offset | Register Name | Description   | Default value after reset |
|--------|---------------|---|---------------------------|
| 0      | BMCR          | Basic Mode Control Register                                   | 3100h                     |
| 1      | BMSR          | Basic Mode Status Register                                    | 7809h                     |
| 2      | PHYIDR1       | PHY Identifier Register #1                                    | 0181h                     |
| 3      | PHYIDR2       | PHY Identifier Register #2                                    | B840h                     |
| 4      | ANAR          | Auto-Negotiation Advertisement Register                       | 01E1h                     |
| 5      | ANLPAR        | Auto-Negotiation Link Partner Ability Register                | 0000h                     |
| 6      | ANER          | Auto-Negotiation Expansion Register                           | 0000h                     |
| 7-15   | Reserved      | Reserved  | 0000h                     |
| 10h    | DSCR          | DAVICOM Specified Configuration Register                      | 0000h                     |
| 11h    | DSCSR         | DAVICOM Specified Configuration/Status Register               | F010h                     |
| 12h    | 10BTCSR       | 10BASE-T Configuration/Status Register                        | 7800h                     |
| Others | Reserved      | Reserved for future use, do not Read/Write to these Registers | 0000h                     |

**Key to Default**

In the register description that follows, the default column takes the form:

<Reset Value>, <Access Type> / <Attribute(s)>

Where :

<Reset Value>:

- 1 Bit set to logic one
- 0 Bit set to logic zero
- X No default value
- (PIN#) Value latched in from pin # at reset

<Access Type>:

- RO = Read only
- RW = Read/Write

<Attribute (s)>:

- SC = Self clearing
- P = Value permanently set
- LL = Latching low
- LH = Latching high

**Basic Mode Control Register (BMCR) – 0**

| Bit  | Name                     | Default  | Description   |
|------|--------------------------|----------|---|
| 0.15 | Reset                    | 0, RW/SC | Reset:<br>1=Software reset<br>0=Normal operation<br>This bit sets the status and controls the PHY registers of the DM9102A to their default states. This bit, which is self-clearing, will keep returning a value of one until the reset process is completed   |
| 0.14 | Loopback                 | 0, RW    | Loopback:<br>1=Loop-back enabled<br>0=Normal operation<br>When in 100Mbps operation mode, setting this bit may cause the descrambler to lose synchronization and produce a 720ms "dead time" before any valid data appear at the MII receive outputs  |
| 0.13 | Speed Selection          | 1, RW    | Speed Select:<br>1=100Mbps<br>0=10Mbps<br>Link speed may be selected either by this bit or by Auto-negotiation. When Auto-negotiation is enabled and bit 12 is set, this bit will return Auto-negotiation selected media type.  |
| 0.12 | Auto-negotiation Enable  | 1, RW    | Auto-negotiation Enable:<br>1= Auto-negotiation enabled: bit 8 and 13 will be in Auto-negotiation status<br>0= Auto-negotiation disabled: bit 8 and 13 will determine the link speed and mode   |
| 0.11 | Power Down               | 0, RW    | Power Down:<br>Setting this bit willpower down the whole chip except crystal / oscillator circuit.<br>1=Power Down<br>0=Normal Operation  |
| 0.10 | Isolate                  | 0,RW     | Isolate:<br>1= Isolates the DM9102A from the MII with the exception of the serial management.<br>0= Normal Operation  |
| 0.9  | Restart Auto-negotiation | 0,RW/SC  | Restart Auto-negotiation:<br>1= Restart Auto-negotiation. Re-initiates the Auto-negotiation process. When Auto-negotiation is disabled (bit 12 of this register cleared), this bit has no function and it should be cleared. This bit is self-clearing and it will keep returning a value of 1 until Auto-negotiation is initiated by the DM9102A. The operation of the Auto-negotiation process will not be affected by the management entity that clears this bit.<br>0= Normal Operation |
| 0.8  | Duplex Mode              | 1,RW     | Duplex Mode:<br>1= Full Duplex operation. Duplex selection is allowed when Auto-negotiation is disabled (bit 12 of this register is cleared). With Auto-negotiation enabled, this bit reflects the duplex capability selected by Auto-negotiation.<br>0= Normal operation   |
| 0.7  | Collision Test           | 0,RW     | Collision Test:<br>1= Collision Test enabled. When set, this bit will cause the COL signal to be asserted in response to the assertion of TX_EN.  |



|         |          |               |                                      |
|---------|----------|---------------|--------------------------------------|
|         |          |               | 0= Normal Operation                  |
| 0.6:0.0 | Reserved | <0000000>, RO | Reserved. Write as 0, ignore on read |

### Basic Mode Status Register (BMSR) – 1

| Bit      | Name                      | Default  | Description  |
|----------|---------------------------|----------|--|
| 1.15     | 100BASE-T4                | 0,RO/P   | 100BASE-T4 Capable:<br>1=DM9102A is able to perform in 100BASE-T4 mode<br>0=DM9102A is not able to perform in 100BASE-T4 mode  |
| 1.14     | 100BASE-TX Full Duplex    | 1,RO/P   | 100BASE-TX FULL DUPLEX CAPABLE:<br>1= DM9102A able to perform 100BASE-TX in Full Duplex mode<br>0= DM9102A not able to perform 100BASE-TX in Full Duplex mode  |
| 1.13     | 100BASE-TX Half Duplex    | 1,RO/P   | 100BASE-TX Half Duplex Capable:<br>1=DM9102A is able to perform 100BASE-TX in Half Duplex mode<br>0=DM9102A is not able to perform 100BASE-TX in Half Duplex mode  |
| 1.12     | 10BASE-T Full Duplex      | 1,RO/P   | 10BASE-T Full Duplex Capable:<br>1=DM9102A is able to perform 10BASE-T in Full Duplex mode<br>0=DM9102A is not able to perform 10BASE-T in Full Duplex mode  |
| 1.11     | 10BASE-T Half Duplex      | 1,RO/P   | 10BASE-T Half Duplex Capable:<br>1=DM9102A is able to perform 10BASE-T in Half Duplex mode<br>0=DM9102A is not able to perform 10BASE-T in Half Duplex mode  |
| 1.10-1.7 | Reserved                  | 0000,RO  | Reserved:<br>Write as 0, ignore on read  |
| 1.6      | MF Preamble Suppression   | 0,RO     | MII Frame Preamble Suppression:<br>1=PHY will accept management frames with preamble suppressed<br>0=PHY will not accept management frames with preamble suppressed  |
| 1.5      | Auto-negotiation Complete | 0,RO     | Auto-negotiation Complete:<br>1=Auto-negotiation process completed<br>0=Auto-negotiation process not completed   |
| 1.4      | Remote Fault              | 0, RO/LH | Remote Fault:<br>1= Remote fault condition detected (cleared on read or by a chip reset). Fault criteria and detection method is DM9102A implementation specific. This bit will set after the RF bit in the ANLPAR (bit 13, register address 05) is set<br>0= No remote fault condition detected   |
| 1.3      | Auto-negotiation Ability  | 1,RO/P   | Auto Configuration Ability:<br>1=DM9102A able to perform Auto-negotiation<br>0=DM9102A not able to perform Auto-negotiation  |
| 1.2      | Link Status               | 0,RO/LL  | Link Status:<br>1=Valid link established (for either 10Mbps or 100Mbps operation)<br>0=Link not established<br>The link status bit is implemented with a latching function, so that the occurrence of a link failure condition causes the Link Status bit to be cleared and remain cleared until it is read via the management interface |
| 1.1      | Jabber Detect             | 0, RO/LH | Jabber Detect:<br>1=Jabber condition detected<br>0=No jabber<br>This bit is implemented with a latching function. Jabber conditions will set this bit unless it is cleared by a read to this register through a management   |



|     |                     |        |  |
|-----|---------------------|--------|--|
|     |                     |        | interface or a DM9102A reset. This bit works only in 10Mbps mode                           |
| 1.0 | Extended Capability | 1,RO/P | Extended Capability:<br>1=Extended register capability<br>0=Basic register capability only |

**PHY ID Identifier Register #1 (PHYIDR1) – 2**

The PHY Identifier Register#1 and Register#2 work together in a single identifier of the DM9102A. The Identifier consists of a concatenation of the Organizationally Unique Identifier (OUI), a vendor's model number, and a model revision number. DAVICOM Semiconductor's IEEE assigned OUI is 00606E.

| Bit      | Name    | Default | Description  |
|----------|---------|---------|--|
| 2.15-2.0 | OUI_MSB | <0181H> | OUI Most Significant Bits:<br>This register stores bit 3 to 18 of the OUI (00606E) to bit 15 to 0 of this register respectively. The most significant two bits of the OUI are ignored (the IEEE standard refers to these as bit 1 and 2) |

**PHY Identifier Register #2 (PHYIDR2) - 3**

| Bit       | Name     | Default           | Description  |
|-----------|----------|-------------------|--|
| 3.15-3.10 | OUI_LSB  | <101110>,<br>RO/P | OUI Least Significant Bits:<br>Bit 19 to 24 of the OUI (00606E) are mapped to bit 15 to 10 of this register respectively |
| 3.9-3.4   | VNDR_MDL | <000100>,<br>RO/P | Vendor Model Number:<br>Six bits of vendor model number mapped to bit 9 to 4 (most significant bit to bit 9)             |
| 3.3-3.0   | MDL_REV  | <0000>,<br>RO/P   | Model Revision Number:<br>Four bits of vendor model revision number mapped to bit 3 to 0 (most significant bit to bit 3) |

**Auto-negotiation Advertisement Register (ANAR) – 4**

This register contains the advertised abilities of this DM9102A device as they will be transmitted to its link partner during Auto-negotiation.

| Bit  | Name | Default | Description   |
|------|------|---------|---|
| 4.15 | NP   | 0,RO/P  | Next Page Indication:<br>0=No next page available<br>1=Next page available<br>The DM9102A has no next page, so this bit is permanently set to 0   |
| 4.14 | ACK  | 0,RO    | Acknowledge:<br>1=Link partner ability data reception acknowledged<br>0=Not acknowledged<br>The DM9102A's Auto-negotiation state machine will automatically control this bit in the outgoing FLP bursts and set it at the appropriate time during the Auto-negotiation process. Software should not attempt to write to this bit. |
| 4.13 | RF   | 0, RW   | Remote Fault:   |



|           |          |                |   |
|-----------|----------|----------------|---|
|           |          |                | 1=Local Device senses a fault condition<br>0=No fault detected  |
| 4.12-4.11 | Reserved | 00, RW         | Reserved:<br>Write as 0, ignore on read   |
| 4.10      | FCS      | 0, RW          | Flow Control Support:<br>1=Controller chip supports flow control ability<br>0=Controller chip doesn't support flow control ability  |
| 4.9       | T4       | 0, RO/P        | 100BASE-T4 Support:<br>1=100BASE-T4 supported by the local device<br>0=100BASE-T4 not supported<br>The DM9102A does not support 100BASE-T4 so this bit is permanently       |
| 4.8       | TX_FDX   | 1, RW          | 100BASE-TX Full Duplex Support:<br>1=100BASE-TX Full Duplex supported by the local device   |
| 4.7       | TX_HDX   | 1, RW          | 100BASE-TX Support:<br>1=100BASE-TX supported by the local device<br>0=100BASE-TX not supported   |
| 4.6       | 10_FDX   | 1, RW          | 10BASE-T Full Duplex Support:<br>1=10BASE-T Full Duplex supported by the local device<br>0=10BASE-T Full Duplex not supported   |
| 4.5       | 10_HDX   | 1, RW          | 10BASE-T Support:<br>1=10BASE-T supported by the local device<br>0=10BASE-T not supported   |
| 4.4-4.0   | Selector | <00001>,<br>RW | Protocol Selection Bits:<br>These bits contain the binary encoded protocol selector supported by this node. <00001> indicates that this device supports IEEE 802.3 CSMA/CD. |

**Auto-negotiation Link Partner Ability Register (ANLPAR) – 5**

This register contains the advertised abilities of the link partner when received during Auto-negotiation.

| Bit       | Name     | Default | Description  |
|-----------|----------|---------|--|
| 5.15      | NP       | 0, RO   | Next Page Indication:<br>0= Link partner, no next page available<br>1= Link partner, next page available   |
| 5.14      | ACK      | 0, RO   | Acknowledge:<br>1=Link partner ability data reception acknowledged<br>0=Not acknowledged<br>The DM9102A's Auto-negotiation state machine will automatically control this bit from the incoming FLP bursts. Software should not attempt to write to this bit. |
| 5.13      | RF       | 0, RO   | Remote Fault:<br>1=Remote fault indicated by link partner<br>0=No remote fault indicated by link partner   |
| 5.12-5.10 | Reserved | 000, RO | Reserved:<br>Write as 0, ignore on read  |
| 5.9       | T4       | 0, RO   | 100BASE-T4 Support:<br>1=100BASE-T4 supported by the link partner<br>0=100BASE-T4 not supported by the link partner  |
| 5.8       | TX_FDX   | 0, RO   | 100BASE-TX Full Duplex Support:<br>1=100BASE-TX Full Duplex supported by the link partner<br>0=100BASE-TX Full Duplex not supported by the link partner  |
| 5.7       | TX_HDX   | 0, RO   | 100BASE-TX Support:  |



|         |          |             |  |
|---------|----------|-------------|--|
|         |          |             | 1=100BASE-TX Half Duplex supported by the link partner<br>0=100BASE-TX Half Duplex not supported by the link partner                           |
| 5.6     | 10_FDX   | 0, RO       | 10BASE-T Full Duplex Support:<br>1=10BASE-T Full Duplex supported by the link partner 0=10BASE-T Full Duplex not supported by the link partner |
| 5.5     | 10_HDX   | 0, RO       | 10BASE-T Support:<br>1=10BASE-T Half Duplex supported by the link partner<br>0=10BASE-T Half Duplex not supported by the link partner          |
| 5.4-5.0 | Selector | <00000>, RO | Protocol Selection Bits:<br>Link partner's binary encoded protocol selector  |

**Auto-Negotiation Expansion Register (ANER) – 6**

| Bit      | Name       | Default  | Description   |
|----------|------------|----------|---|
| 6.15-6.5 | Reserved   | 0, RO    | Reserved:<br>Write as 0, ignore on read   |
| 6.4      | PDF        | 0, RO/LH | Local Device Parallel Detection Fault:<br>PDF=1: A fault detected via parallel detection function.<br>PDF=0: No fault detected via parallel detection function                  |
| 6.3      | LP_NP_ABLE | 0, RO    | Link Partner Next Page Able:<br>LP_NP_ABLE=1: Link partner, next page available<br>LP_NP_ABLE=0: Link partner, no next page   |
| 6.2      | NP_ABLE    | 0,RO/P   | Local Device Next Page Able:<br>NP_ABLE=1: DM9102A, next page available<br>NP_ABLE=0: DM9102A, no next page<br>DM9102A does not support this function, so this bit is always 0. |
| 6.1      | PAGE_RX    | 0, RO/LH | New Page Received:<br>A new link code word page received. This bit will be automatically cleared when the register (Register 6) is read by management                           |
| 6.0      | LP_AN_ABLE | 0, RO    | Link Partner Auto-negotiation Able:<br>A "1" in this bit indicates that the link partner supports Auto-negotiation.   |

**DAVICOM Specified Configuration Register (DSCR) - 10h**

| Bit        | Name       | Default | Description   |
|------------|------------|---------|---|
| 16.15:16.8 | Reserved   | 0, RO   | Reserved  |
| 16.7       | F_LINK_100 | 0, RW   | Force Good Link in 100Mbps:<br>0 = Normal 100Mbps operation<br>1 = Force 100Mbps good link status<br>This bit is useful for diagnostic purposes.            |
| 16.6:16.4  | Reserved   | 0,RO    | Reserved  |
| 16.3       | SMRST      | 0,RW    | Reset State Machine:<br>When writes 1 to this bit, all state machines of PHY will be reset. This bit is self-clear after reset is completed.                |
| 16.2       | MFPSC      | 0,RW    | MF Preamble Suppression Control:<br>MII frame preamble suppression control bit<br>1 = MF preamble suppression bit on<br>0 = MF preamble suppression bit off |



|      |       |      |   |
|------|-------|------|---|
| 16.1 | SLEEP | 0,RW | Sleep Mode:<br>Writing a 1 to this bit will cause PHY entering the Sleep mode and power down all circuit except oscillator and clock generator circuit. When waking up from Sleep mode (write this bit to 0), the configuration will go back to the state before sleep; but the state machine will be reset |
| 16.0 | RLOUT | 0,RW | Remote Loop out Control:<br>When this bit is set to 1, the received data will loop out to the transmit channel<br>This is useful for bit error rate testing   |

**DAVICOM Specified Configuration and Status Register (DSCSR) - 11h**

| Bit        | Name       | Default   | Description  |
|------------|------------|-----------|--|
| 17.15      | 100FDX     | 1, RO     | 100M Full Duplex Operation Mode:<br>After Auto-negotiation is completed, results will be written to this bit. If this bit is 1, it means the operation 1 mode is a 100Mbps Full Duplex mode. The software can read bit[15:12] to see which mode is selected after Auto-negotiation. This bit is invalid when it is not in the Auto-negotiation mode. |
| 17.14      | 100HDX     | 1, RO     | 100M Half Duplex Operation Mode:<br>After Auto-negotiation is completed, results will be written to this bit. If this bit is 1, it means the operation 1 mode is a 100Mbps Half Duplex mode. The software can read bit[15:12] to see which mode is selected after Auto-negotiation. This bit is invalid when it is not in the Auto-negotiation mode. |
| 17.13      | 10FDX      | 1, RO     | 10M Full Duplex Operation Mode:<br>After Auto-negotiation is completed, results will be written to this bit. If this bit is 1, it means the operation 1 mode is a 10Mbps Full Duplex mode. The software can read bit[15:12] to see which mode is selected after Auto-negotiation. This bit is invalid when it is not in the Auto-negotiation mode.   |
| 17.12      | 10HDX      | 1, RO     | 10M Half Duplex Operation Mode:<br>After Auto-negotiation is completed, results will be written to this bit. If this bit is 1, it means the operation 1 mode is a 10Mbps Half Duplex mode. The software can read bit[15:12] to see which mode is selected after Auto-negotiation. This bit is invalid when it is not in the Auto-negotiation mode.   |
| 17.11-17.9 | Reserved   | 000, RW   | Reserved:<br>Write as 0, ignore on read  |
| 17.8-17.4  | PHYAD[4:0] | 00001, RW | PHY Address Bit 4:0:<br>The first PHY address bit transmitted or received is the MSB of the address (bit 4). A station management entity connected to multiple PHY entities must know the appropriate address of each PHY. A PHY address of <00000> will cause the isolate bit of the BMCR (bit 10, Register Address 00) to be set.                  |
| 17.3-17.0  | ANMB[3:0]  | 0000, RO  | Auto-negotiation Monitor Bits:<br>These bits are for debug only. The Auto-negotiation status will be written to these bits.  |



|  |  |  |  |    |    |    |    |   |
|--|--|--|--|----|----|----|----|---|
|  |  |  |  | b3 | b2 | b1 | b0 |   |
|  |  |  |  | 0  | 0  | 0  | 0  | In IDLE state                           |
|  |  |  |  | 0  | 0  | 0  | 0  | Ability match                           |
|  |  |  |  | 0  | 0  | 1  | 0  | Acknowledge match                       |
|  |  |  |  | 0  | 0  | 1  | 1  | Acknowledge match fail                  |
|  |  |  |  | 0  | 1  | 0  | 0  | Consistency match                       |
|  |  |  |  | 0  | 1  | 0  | 1  | Consistency match fail                  |
|  |  |  |  | 0  | 1  | 1  | 0  | Parallel detects signal_link_ready      |
|  |  |  |  | 0  | 1  | 1  | 1  | Parallel detects signal_link_ready fail |
|  |  |  |  | 1  | 0  | 0  | 0  | Auto-negotiation completed successfully |

**10BASE-T Configuration/Status (10BTCRCSR) - 12h**

| Bit        | Name     | Default | Description  |
|------------|----------|---------|--|
| 18.15      | Reserved | 0, RO   | Reserved:<br>Write as 0, ignore on read  |
| 18.14      | LP_EN    | 1, RW   | Link Pulse Enable:<br>1=Transmission of link pulses enabled<br>0=Link pulses disabled, good link condition forced<br>This bit is valid only in 10Mbps operation.   |
| 18.13      | HBE      | 1,RW    | Heartbeat Enable:<br>1=Heartbeat function enabled<br>0=Heartbeat function disabled<br>When the DM9102A is configured for Full Duplex operation, this bit will be ignored (the collision/heartbeat function is invalid in Full Duplex mode). It must set to be 1. |
| 18.12      | SQUELCH  | 1, RW   | Squelch Enable<br>1 = normal squelch<br>0 = low squelch  |
| 18.11      | JABEN    | 1, RW   | Jabber Enable:<br>Enables or disables the Jabber function when the DM9102A is in 10BASE-T Full Duplex or 10BASE-T Transceiver Loopback mode<br>1= Jabber function enabled<br>0= Jabber function disabled   |
| 18.10-18.0 | Reserved | 0, RO   | Reserved   |



## Functional Description

### System Buffer Management

#### 1. Overview

The data buffers for reception and transmission of data resides in the host memory. They are directed by the descriptor list that is located in another region of the host memory. All actions for the buffer management are operated by the DM9102A in conjunction with the driver. The data structures and processing algorithms are described in the following text.

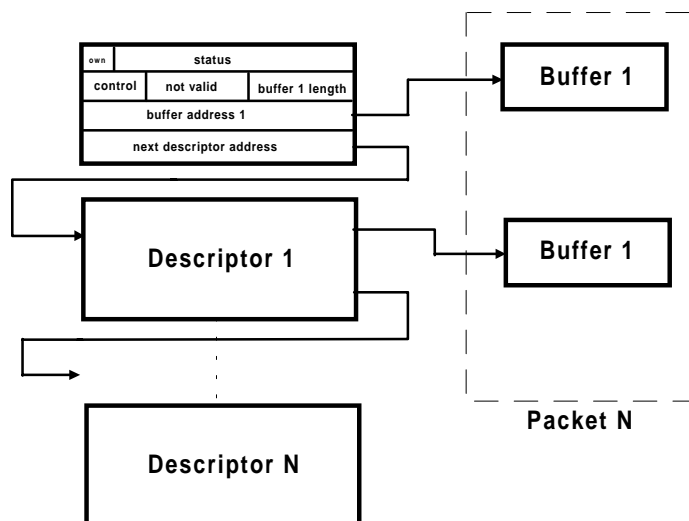
#### 2. Data Structure and Descriptor List

There are two types of buffers that reside in the host memory, the transmit buffer and the receive buffer. The buffers are composed of many distributed regions in the host memory. They are linked together and controlled by the

descriptor lists that reside in another region of the host memory. The content of each descriptor includes pointer to the buffer, count of the buffer, command and status for the packet to be transmitted or received. Each descriptor list starts from the address setting of CR3 (receive descriptor base address) and CR4 (transmit descriptor base address). The descriptor list is Chain structure.

#### 3. Buffer Management – Chain Structure Method

As the Chain structure depicted below, each descriptor contains two pointers, one point to a single buffer and the other to the next descriptor chained. The first descriptor is chained to the last descriptor under host driver's control. With this structure, a descriptor can be allocated anywhere in host memory and is chained to the next descriptor.

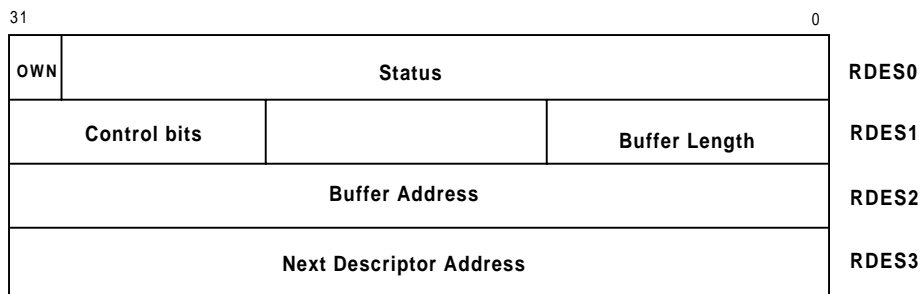


#### 4. Descriptor List: Buffer Descriptor Format

##### (a). Receive Descriptor Format

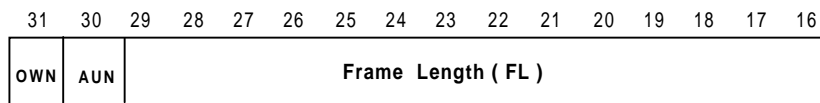
Each receive descriptor has four double-word entries and may be read or written by the host or the DM9102A. The

descriptor format is shown below with a detailed functional description.



**Receive Descriptor Format**

**RDES0:**



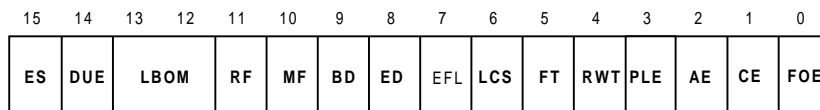
**OWN: Owner bit of received status**

1=owned by DM9102, 0=owned by host  
This bit should be reset after packet reception is completed.  
The host will set this bit after received data is removed.

**AUN: Received address unmatched.**

**FL: Frame Length**

Frame length indicating total byte count of received packet.



This word-wide content includes status of received frame. They are loaded after the received buffer that belongs to the corresponding descriptor is full. All status bits are valid only when the last descriptor (End Descriptor) bit is set.

**Bit 15: ES, Error Summary**

It is set for the following error conditions: Descriptor Unavailable Error (DUE =1), Runt Frame (RF=1), Excessive Frame Length (EFL=1), Late Collision Seen (LCS=1), CRC error (CE=1), FIFO Overflow error (FOE=1). Valid only when ED is set.

**Bit 14: DUE, Descriptor Unavailable Error**

It is set when the frame is truncated due to the buffer unavailable. It is valid only when ED is set.

**Bit 13,12: LBOM, Loopback Operation Mode**

These two bits show the received frame is derived from:  
00 --- normal operation  
01 --- internal loopback  
10 --- PHY loopback  
11 --- external loopback

**Bit 11: RF, Runt Frame**

It is set to indicate the received frame has the size smaller than 64 bytes. It is valid only when ED is set and FOE is reset.

**Bit 10: MF, Multicast Frame**

It is set to indicate the received frame has a multicast address. It is valid only when ED is set.

**Bit 9: BD, Begin Descriptor**

This bit is set for the descriptor indicating start of a received frame.

**Bit 8: ED, Ending Descriptor**

This bit is set for descriptor to indicate end of a received frame.

**Bit 7: EFL, Excessive Frame Length**

It is set to indicate the received frame length exceeds 1518 bytes. Valid only when ED is set.

**Bit 6: LCS: Late Collision Seen**

It is set to indicate a late collision found during the frame reception. Valid only when ED is set.

**Bit 5: FT, Frame Type**

It is set to indicate the received frame is the Ethernet-type. It is reset to indicate the received frame is the IEEE802.3- type. Valid only when ED is set

**Bit 4: RWT, Receive Watchdog Time-Out**

It is set to indicate receive Watchdog time-out during the frame reception. CR5<9> will also be set. Valid only when ED is set.

**Bit 3: PLE, Physical Layer Error**

It is set to indicate a physical layer error found during the frame reception.

**Bit 2: AE, Alignment Error**

It is set to indicate the received frame ends with a non-byte boundary.

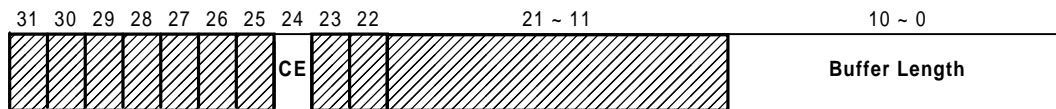
**Bit 1: CE, CRC Error**

It is set to indicate the received frame ends with a CRC error. Valid only when ED is set.

**Bit 0: FOE, FIFO Overflow Error**

This bit is valid for Ending Descriptor is set. (ED = 1). It is set to indicate a FIFO Overflow error happens during the frame reception.

**RDES1: Descriptor Status and Buffer Size**



**Bit 24: CE, Chain Enable**

Must be 1.

**Bit 10-0: Buffer Length**

Indicates the size of the buffer.

**RDES2: Buffer Starting Address**

Indicates the physical starting address of buffer. This address must be double word alignment.



**IRDES3: Next descriptor Address**

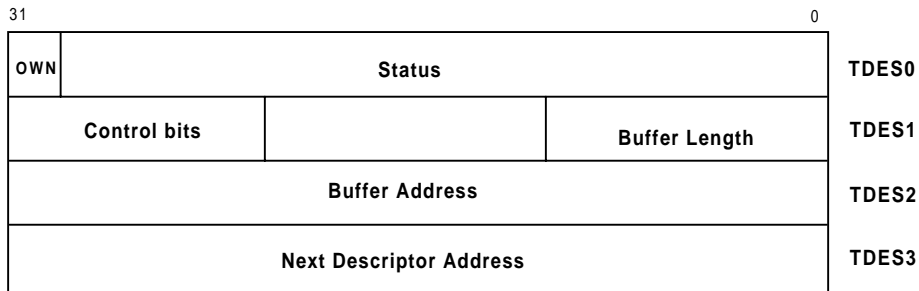
Indicates the physical starting address of the chained descriptor under the Chain descriptor structure. This address must be eight word alignment.



**(b). Transmit Descriptor Format**

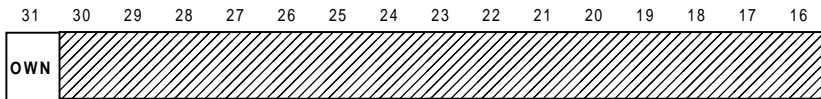
Each transmit descriptor has four double-word content and may be read or written by the host or by the DM9102A.

The descriptor format is shown below with detailed description



**Transmit Descriptor Format**

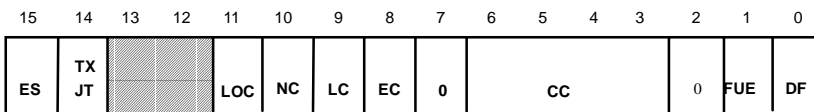
**TDES0: Owner Bit with Transmit Status**



**Bit 31: OWN,**

1=owned by DM9102A, 0=owned by host, this bit should be set when the transmitting buffer is filled with data and ready

to be transmitted. It will be reset by DM9102A after transmitting the whole data buffer.



This word wide content includes status of transmitted frame. They are loaded after the data buffer that belongs to the corresponding descriptor is transmitted.

**Bit 15: ES, Error Summary**

It is set for the following error conditions: Transmit Jabber Time-out (TXJT=1), Loss of Carrier (LOC=1), No Carrier (NC=1), Late Collision (LC=1), Excessive Collision (EC=1), FIFO Underrun Error (FUE=1).

**Bit 14: TXJT, Transmit Jabber Time Out**

It is set to indicate the transmitted frame is truncated due to transmit jabber time out condition. The transmit jabber time out interrupt CR5<3> is set.

**Bit 11: LOC, Loss of Carrier**

It is set to indicate the loss of carrier during the frame transmission. It is not valid in internal loopback mode.

**Bit 10: NC, No Carrier**

It is set to indicate that no carrier signal from transceiver is found. It is not valid in internal loopback mode.

**Bit 9: LC, Late Collision**

It is set to indicate a collision occurs after the collision window of 64 bytes. Not valid if FUE is set.

**Bit 8: EC, Excessive collision**

It is set to indicate the transmission is aborted due to 16 excessive collisions.

**Bit 7: Reserved**

This bit is 0 when read.

**Bits 6-3: CC, Collision Count**

These bits show the number of collision before transmission. Not valid if excessive collision bit is also set.

**Bit 2: Reserved**

This bit is 0 when read.

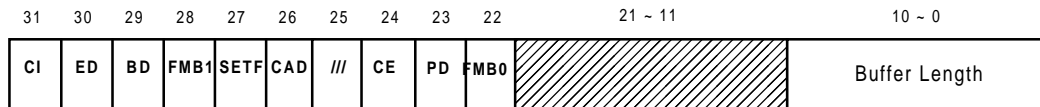
**Bit 1: FUE, FIFO Underrun Error**

It is set to indicate the transmission aborted due to transmit FIFO underrun condition.

**Bit 0: DF, Deferred**

It is set to indicate the frame is deferred before ready to transmit.

**TDES1: Transmit buffer control and buffer size**



**Bit 31: CI, Completion Interrupt**

It is set to enable transmit interrupt after the present frame has been transmitted. It is valid only when TDES1<30> is set or when it is a setup frame.

It is set to disable the CRC appending at the end of the transmitted frame. Valid only when TDES1<29> is set.

**Bit 30: ED, Ending Descriptor**

It is set to indicate the pointed buffer contains the last segment of a frame.

**Bit 24: CE, Chain Enable**

Must be "1".

**Bit 29: BD, Begin Descriptor**

It is set to indicate the pointed buffer contains the first segment of a frame.

**Bit 23: PD, Padding Disable**

This bit is set to disable the padding field for a packet shorter than 64 bytes.

**Bit 28: FMB1, Filtering Mode Bit 1**

This bit is used with FMB0 to indicate the filtering type when the present frame is a setup frame.

**Bit 22: FMB0, Filtering Mode Bit 0**

This bit is used with FMB1 to indicate the filtering type when the present frame is a setup frame.

| FMB1 | FMB0 | Filtering Type       |
|------|------|----------------------|
| 0    | 0    | Perfect Filtering    |
| 0    | 1    | Hash Filtering       |
| 1    | 0    | Inverse Filtering    |
| 1    | 1    | Hash-Only Filtering. |

**Bit 27: SETF, Setup Frame**

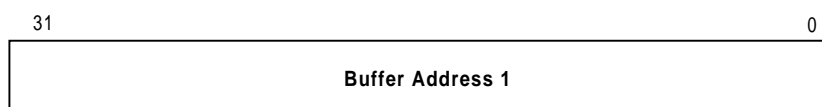
It is set to indicate the current frame is a setup frame.

**Bit 10-0: Buffer 1 length**

Indicates the size of buffer in Chain type structure.

**Bit 26: CAD, CRC Append Disable**

**TDES2: Buffer Starting Address indicates the physical starting address of buffer.**



**TDES3: Address indicates the next descriptor starting address**

Indicates the physical starting address of the chained descriptor under the Chain descriptor structure. This address must be eight word alignment.



**Initialization Procedure**

After hardware or software reset, transmit and receive processes are placed in the state of STOP. The DM9102A

can accept the host commands to start operation. The general procedure for initialization is described below:

- (1) Read/write suitable values for the PCI configuration registers.
- (2) Write CR3 and CR4 to provide the starting address of each descriptor list.
- (3) Write CR0 to set global host bus operation parameters.
- (4) Write CR7 to mask causes of unnecessary interrupt.
- (5) Write CR6 to set global parameters and start both receive and transmit processes. Receive and transmit processes will enter the running state and attempt to acquire descriptors from the respective descriptor lists.
- (6) Wait for any interrupt.

### Data Buffer Processing Algorithm

The data buffer process algorithm is based on the cooperation of the host and the DM9102A. The host sets CR3 (receive descriptor base address) and CR4 (transmit descriptor base address) for the descriptor list initialization. The DM9102A will start the data buffer transfer after the descriptor polling and get the ownership. For detailed processing procedure, please see below.

### 1. Receive Data Buffer Processing

The DM9102A always attempts to acquire an extra descriptor in anticipation of the incoming frames. Any incoming frame size covers a few buffer regions and descriptors. The following conditions satisfy the descriptor acquisition attempt:

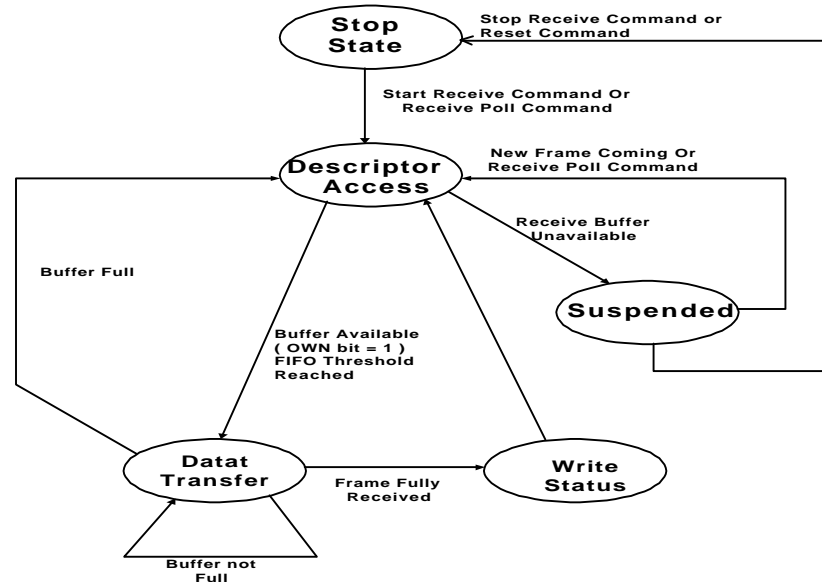
When start/stop receive sets immediately after being placed in the running state.

When the DM9102A begins writing frame data to a data buffer pointed to by the current descriptor and the buffer ends before the frame ends.

When the DM9102A completes the reception of a frame and the current receiving descriptor is closed.

When receive process is suspended due to no free buffer for the DM9102A and a new frame is received.

When receive polling demand is issued. After acquiring the free descriptor, the DM9102A processes the incoming frame and places it in the acquired descriptor's data buffer. When whole the received frame data has been transferred, the DM9102A will write the status information to the last descriptor. The same process will repeat until it encounters a descriptor flagged as being owned by the host. If this occurs, receive process enters the suspended state and waits the host to service.



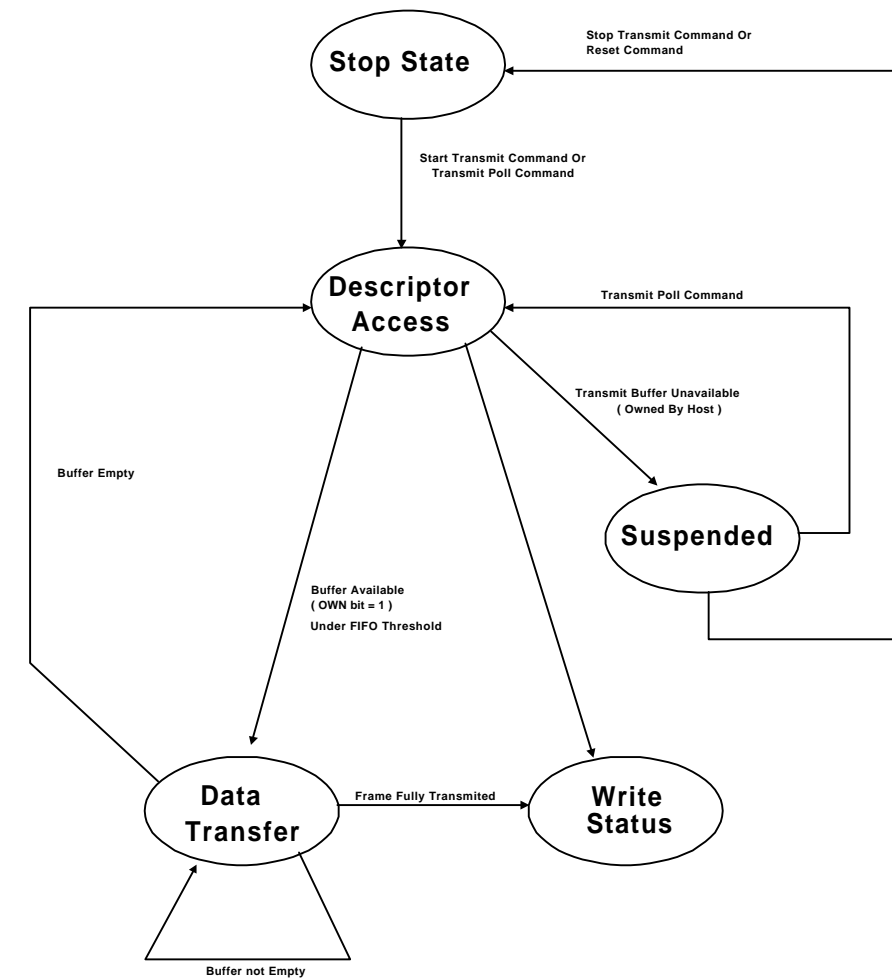
Receive Buffer Management State Transition

## 2. Transmit Data Buffer Processing

When start/stop transmit command is set and the DM9102A is in running state, transmit process polls transmit descriptor list for frames requiring transmission. When it completes a frame transmission, the status related to the transmitted frame will be written into the transmit descriptor. If the DM9102A detects a descriptor flagged as owned by the host and no transmit buffers are available, transmit process will be suspended. While in the running state, transmit process can simultaneously acquire two frames. As transmit process completes copying the first frame, it immediately

polls transmit descriptor list for the second frame. If the second frame is valid, transmit process copies the frame before writing the status information of the first frame.

Both conditions will make transmit process suspend. (i) The DM9102A detects a descriptor owned by the host. (ii) A frame transmission is aborted when a locally induced error is detected. Under either condition, the host driver has to service the condition before the DM9102A can resume.



Transmit Buffer Management State Transition

## Network Function

### 1. Overview

This chapter will introduce the normal state machine operation and MAC layer management like collision backoff algorithm. In transmit mode, the DM9102A initiates a DMA cycle to access data from a transmit buffer. It prefaces the data with the preamble, the SFD pattern, and it appends a 32-bit CRC. In receive mode, the data is de-serialized by receive mechanism and fed into the internal FIFO. For detailed process, please see below.

### 2. Receive Process and State Machine

#### a. Reception Initiation

As a preamble being detected on receive data lines, the DM9102A synchronizes itself to the data stream during the preamble and waits for the SFD. The synchronization process is based on byte boundary and the SFD byte is 10101011. If the DM9102A receives a 00 or a 11 after the first 8 preamble bits and before receiving the SFD, the reception process will be terminated.

#### b. Address Recognition

After initial synchronization, the DM9102A will recognize the 6-byte destination address field. The first bit of the destination address signifies whether it is a physical address (=0) or a multicast address (=1). The DM9102A filters the frame based on the node address of receive address filter setting. If the frame passes the filter, the subsequent serial data will be delivered into the host memory.

#### c. Frame Decapsulation

The DM9102A checks the CRC bytes of all received frames before releasing the frame along with the CRC to the host processor.

### 3. Transmit Process and State Machine

#### a. Transmission Initiation

Once the host processor prepares a transmit descriptor for the transmit buffer, the host processor signals the DM9102A to take it. After the DM9102A has been notified of this transmit list, the DM9102A will start to move the data bytes from the host memory to the internal transmit FIFO. When the transmit

FIFO is adequately filled to the programmed threshold level, or when there is a full frame buffered into the transmit FIFO, the DM9102A begins to encapsulate the frame. The transmit encapsulation is performed by the transmit state machine, which delays the actual transmission onto the network until the network has been idle for a minimum inter frame gap time.

#### b. Frame Encapsulation

The transmit data frame encapsulation stream consists of two parts: Basic frame beginning and basic frame end. The former contains 56 preamble bits and SFD, the later, FCS. The basic frame read from the host memory includes the destination address, the source address, the type/length field, and the data field. If the data field is less than 46 bytes, the DM9102A will pad the frame with pattern up to 46 bytes.

#### c. Collision

When concurrent transmissions from two or more nodes occur (termed; collision), the DM9102A halts the transmission of data bytes and begins a jam pattern consisting of AAAAAAAAAA. At the end of the jam transmission, it begins the backoff wait time. If the collision was detected during the preamble transmission, the jam pattern is transmitted after completing the preamble. The backoff process is called truncated binary exponential backoff. The delay is a random integer multiple of slot times. The number of slot times of delay before the N<sup>th</sup> retransmission attempt is chosen as a uniformly distributed random integer in the range:

$$0 \leq r < 2^k$$
$$k = \min(n, N) \text{ and } N=10$$

### 4. Physical Layer Overview:

The DM9102A provides 100M/10Mbps dual port operation. It provides a direct interface either to Unshielded Twisted pair Cable UTP5 for 100BASE-TX Fast Ethernet, or UTP5/UTP3 Cable for 10BASE-T Ethernet. In physical level operation, it consists of the following blocks:

- PCS
- Clock generator
- NRE/NREI, MLT-3 encoder/decoder and driver
- MANCHESTER encoder/decoder
- 10BASE-T filter and driver



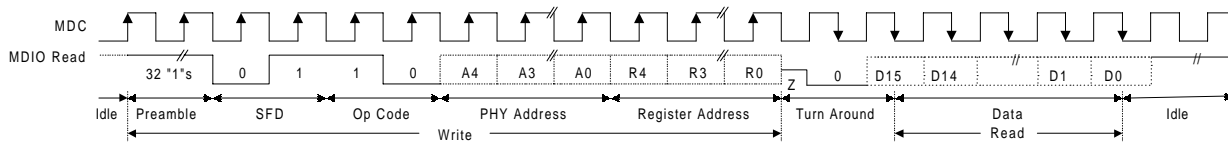
## Serial Management Interface

The serial management interface uses a simple, two-wired serial interface to obtain and control the status of PHY management register set through an MDC and MDIO. The Management Data Clock (MDC) is equipped with a maximum clock rate of 2.5MHz, while Management Data Input /Output (MDIO) works as a bi-directional, shared by up to 32 devices.

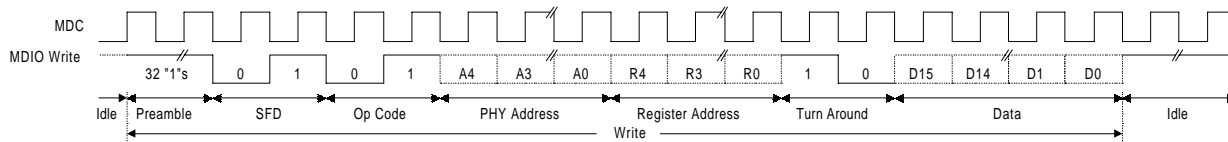
In read/write operation, the management data frame is 64-bit long start with 32 contiguous logic one bits (preamble)

synchronization clock cycles on MDC. The Start of Frame Delimiter (SFD) is indicated by a <01> pattern followed by the operation code (OP): <10> indicates Read operation and <01> indicates Write operation. For read operation, a 2-bit turnaround (TA) filling between Register Address field and Data field is provided for MDIO to avoid contention. "Z" stands for the state of high impedance. Following turnaround time, a 16-bit data is read from or written onto management registers.

### Management Interface - Read Frame Structure



### Management Interface - Write Frame Structure



## Power Management

### 1. Overview

The DM9102A supports power management mechanism. It complies with the ACPI Specification Rev 1.0, the Network Device Class Power Management Specification Rev 1.0, and PCI Bus Power Management Interface Specification Rev 1.0. In addition, it also support Wake-On LAN (WOL) which is the features of the AMD's Magic Packet™ technology. With this function, it can wake-up a remote sleeping station.

### 2. PCI Function Power Management States

The DM9102A supports PCI function power states D0, D3(hot), D3(cold), and not supports D1, D2 states. Additional PCI signal PME# (power management event, open drain) to pin A19 of the standard PCI connector.

**D0:** normal & fully functional state

**D3(hot) :** For controller, configuration space can be accessed and wake-up on LAN circuit can be enabled. PME# operational circuit is active, full function is supported to detect the wake-up Frame & Link status. Because of functions in D3(hot) must respond to configuration space accesses as long as power and clock are supplied so that they can be returned to D0 state by software.

**D3(cold) :** If Vcc is removed from a PCI device, all of its PCI functions transition immediately to D3(cold), no bus transaction is active under no pci\_clk condition and wake-up on LAN operation should be alive. PME# operational circuit is active. Full function is supported under auxiliary power to detect the wake-up Frame & Link status. When power restored, PCI RST# must be asserted and functions will return to D0 with a full PCI Spec. 2.2 compliant power-on reset sequence. The power required in D3(cold) must be provided by some auxiliary power source.

### 3. The Power Management Operation

It complies with the PCI Bus Power Management Interface Specification Rev. 1.0. The Power Management Event (PME#) signal is an optional open drain, active low signal that is intended to be driven low by a PCI function to request a change in its current power management state and/or to indicate that a power management event has occurred.

The PME# signal has been assigned to pin A19 of the standard PCI Connector configuration. The assertion and de-assertion of PME# is asynchronous to the PCI clock.

Software will enable its use by setting the PME\_En bit in the PMCSR (write 1 to PMCSR<8>). When a PCI function generates or detects an event that requires the system to change its power state, the function will assert PME#. It must continue to assert PME# until software either clears the PME\_En bit (PMCSR<8> is set to 0) or clears the PME\_Status bit in the PMCSR (write 1 to PMCSR<15>).

DM9102A support three main categories of network device wake-up events specified in Network Device Class Power Management Rev1.0. That is, the DM9102A can monitor the network for a Link Change, Magic Packet or a Wake-up Frame and notify the system by generating PME# if any of three events occurs. Program the PCIUSR (offset = 40h) can select the PME# event, and write 1 to PMCSR<15> will clear the PME#.

#### a. Detect Network Link State Change

Any link status change will set the wake-up event.

1. Writes 1 into PMCSR<15>(54h) to clear previous PME# status
2. Writes 1 into PMCSR<8> to enable PME# function
3. Writes 1 into PCIUSR<29> to enable the link status change function

#### b. Active Magic Packet Function

Could be optionally enabled from EEPROM contents. Send a setup frame with a magic node address at first filter address using perfect address filtering mode.

1. Writes 1 into PMCSR<15> to clear previous PME status
2. Writes 1 into PMCSR<8> to enable PME# function
3. Writes 1 into PCIUSR<27> to enable magic packet function.

#### c. Active the Sample Frame Function

Could be optionally enabled from PCIUSR<28>. Sample frame data and corresponding byte mask are loaded into transmit FIFO & receive FIFO before entering D3(hot). The software driver has to stop the TX/RX process before setting the sample frame and byte mask into the FIFO. Transmit &

receive FIFO can be accessed from CR13 & CR14 by programming CR6<28:25> = 0011.

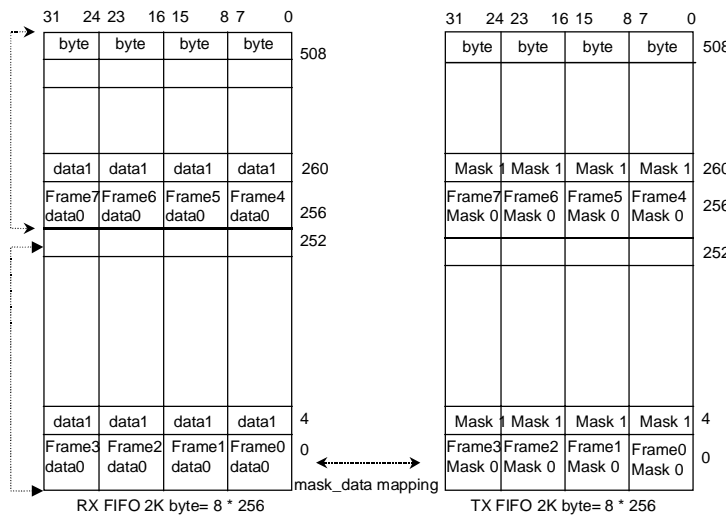
The operational sequence from D0 to D3 should be:  
 Stop TX/RX process → wait for entering stop state → set test mode, CR6<28:25> = 0011 → programming FIFO contents → exit test mode → enter D3(hot) state

The sample frame data comparison is completed when the received frame data has exceeded the programmed frame length or the full packet has been fully received. The operation procedure is shown below.

DM9102A can handle 8 sample frames. The max byte count is 256 byte each sample frame.

| bit1 | bit0 | description               |
|------|------|---------------------------|
| 0    | 0    | this byte don't care      |
| 0    | 1    | this byte musk check      |
| 1    | 0    | this byte don't care      |
| 1    | 1    | end of mask(sample frame) |

Frame mask definition: only used bit0&bit1



### CR13: Sample Frame Access Register

| Name      | General definition                        | Bit8:3 | Type |
|-----------|---|--------|------|
| TxFIFO    | Transmit FIFO access port                 | 32h    | RW   |
| RxFIFO    | Receive FIFO access port                  | 35h    | RW   |
| DiagReset | General reset for diagnostic pointer port | 38h    | RW   |

In DiagReset port there are 7 bits:

- Bit 0: clear TX FIFO write\_address to 0.
- Bit 1: clear TX FIFO read\_address to 0.,
- Bit 2: clear RX FIFO write\_address to 0.
- Bit 3: clear RX FIFO read\_address to 0.,

Bit 4: reserved.

- Bit 5: set TX FIFO write\_address to 100H.,
- Bit 6: set RX FIFO write\_address to 100H.

**Sample Frame Programming Guide:**

1. Enter the sample frame access mode  
Let CR6<28:25>=0011
2. Reset the TX/RX FIFO, write pointer to offset 0  
Write 38h to CR13<8:3>  
Write 01h to CR14 (reset)  
Write 00h to CR14 (clear)
3. Write the sample frame 0-3 data to RX FIFO  
Write 35h to CR13<8:3>  
Write xxxxxxxxh to CR14 (Frame1~3 first byte)  
Write xxxxxxxxh to CR14 (Frame1~3 second byte)  
:  
:  
Repeat write until all frame data written to RX FIFO
4. RESET RX FIFO, write pointer to offset 100h  
Write 38h to CR13<8:3>  
Write 40h to CR14 (reset)  
Write 00h to CR14 (clear)
5. Write the sample frame 4-7 to RX FIFO  
Write 35h to CR13<8:3>  
Write xxxxxxxxh to CR14 (Frame4~7 first byte)  
Write xxxxxxxxh to CR14 (Frame4~7 second byte)  
:  
:

- Repeat write until all frame data written to RX FIFO
6. Write the sample frame 0-3 mask to TX FIFO  
Write 32h to CR13<8:3>  
Write xxxxxxxxh to CR14 (Frame0~3 first mask byte)  
Write xxxxxxxxh to CR14 (Frame0~3 second mask byte)  
:  
:  
Repeat write until all frame mask which is written to TX FIFO
  7. RESET TX FIFO, write pointer to offset 100h  
Write 38h to CR13<8:3>  
Write 20h to CR14 (reset)  
Write 00h to CR14 (clear)
  8. Write the sample frame 4-7 mask to TX FIFO  
Write 32h to CR13<8:3>  
Write xxxxxxxxh to CR14 (Frame4~7 first mask byte)  
Write xxxxxxxxh to CR14 (Frame4~7 second mask byte)  
:  
:  
Repeat write until all frame mask which is written to TX FIFO



## Serial ROM Overview

The purpose of Configuration ROM (EEPROM) is to support the DM9102A information to the driver for the card. The

SRROM must support 64 words or more space for configuration data. The format of the SRROM is as followed

The format of EEPROM

| Field Name                      | Offset | Size |
|---------------------------------|--------|------|
| Subsystem ID block              | 0      | 18   |
| CROM version                    | 18     | 1    |
| Controller count                | 19     | 1    |
| Controller_0 Information        | 20     | n    |
| Controller_1 Information        | 20+n   | m    |
| : (depends on controller count) | :      | :    |
| CRC checksum                    | 126    | 2    |

### 1. Subsystem ID Block

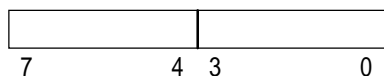
Every card must have a Subsystem ID to indicate the system vendor information. The content will be transferred into the PCI configuration space during hardware reset function.

Vendor ID & Device ID can be set in EEPROM content & auto-loaded to PCI configuration register after reset. (default value = 1282, 9102) This function must be selectable for enable/disable by Auto\_Load\_Control (offset 08 of

EEPROM) setting to avoid damaging default value due to incorrectly auto-load operation. CRC check circuit of EEPROM contents to decide the auto-load operation of Vendor ID & Subsystem.

| Subsystem ID Block  |                   | Byte Offset. |
|---------------------|-------------------|--------------|
| Subsystem Vendor ID |                   | 0            |
| Subsystem ID        |                   | 2            |
| Reserved            |                   | 4            |
| Reserved            |                   | 6            |
| NCE                 | Auto_load_control | 8            |
| PCI Vender ID       |                   | 10           |
| PCI Device ID       |                   | 12           |
| PMCSR               | PMC               | 14           |
| Reserved            | ID_block_CRC      | 17,16        |

### Byte Offset (08): Auto\_Load\_Control



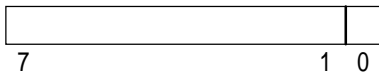
Bit3~0: "1010" to enable auto-load of PCI Vendor\_ID & Device\_ID, "0" to disable.

Bit7~4: "1X1X" to enable auto-load of NCE, PME & PMC & PMCSR to PCI configuration space. These four bits can also control the inverse of WOL or PULSE WOL..

If bit4 = 0, WOL is Active HIGH.  
If bit4=1, WOL is Active LOW

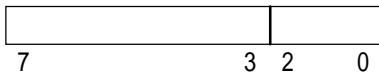
If bit6 = 0, WOL is PULSE signal  
If bit6=1, WOL is DC LEVEL signal.

### Byte Offset (09): New\_Capabilities\_Enable



Bit0: Directly mapping to bit20 (New Capabilities) of the PCICS

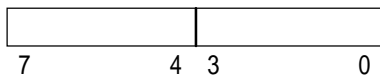
### Byte Offset (14): PMC



Bit7~3: Directly mapping to bit15~11 of PMC (that is bit31~27 of Power Management Register)

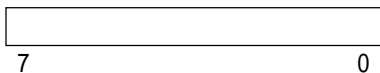
Bit2~0: Directly mapping to bit5~3 of PMC (that is bit21~19 of Power Management Register)

### Byte Offset (15):



Bit7~4: Reserved  
Bit3: Set to disable the output of PME# pin.  
Bit2: Set to disable the output of WOL pin.  
Bit1: Set to enable the link change wake up event.  
Bit0: Set to enable the Magic packet wake up event.

### Byte Offset (16): ID\_BLOCK\_CRC



This field is implemented to confirm the correct reading of the EEPROM contents.

### 2. SROM Version

Current version number is 03.

### 3. Controller Count

The configuration ROM supports multiple controllers in one board. Every controller has its unique controller information block. Controller count indicates the number of controllers put in the card.

### 4. Controller\_X Information

Each controller has its information block to address its node ID, GPR control, supported connect media types (Media Information Block) and other application circuit information block.

#### Controller Information Header

| ITEM                            | Offset | Size |
|---------------------------------|--------|------|
| Node Address                    | 0      | 6    |
| Controller_x Number             | 6      | 1    |
| Controller_x Info. Block Offset | 7      | 1    |

### 5. Controller Information Body Pointed By Controller\_X Info Block Offset Item In Controller Information Header:

| Item                     | Offset | Size |
|--------------------------|--------|------|
| Connection Type Selected | 0      | 2    |
| GPR Control              | 2      | 1    |
| Block Count              | 3      | 1    |
| Block_1                  | 4      | n    |
| :                        | 4+n    | m    |

\* Connect Type Selected indicates the default connect media type selected.

\* GPR Control defines the input or output direction of GPR.

There are three types of block:

1. PHY Information Block (type=01)
2. Media Information Block (type=00)
3. Delay Period Block (type=80)

### PHY information Block: (type=01)

| Item                       | Offset    | Size |
|----------------------------|-----------|------|
| Block Length               | 0         | 1    |
| Block Type(01)             | 1         | 1    |
| PHY Number                 | 2         | 1    |
| GPR Initial Length(G_i)    | 3         | 1    |
| GPR Initial Data           | 4         | G_i  |
| Reset Sequence Length(R_i) | 4+G_i     | 1    |
| Reset Data                 | 5+G_i     | R_i  |
| Media Capabilities         | 5+G_i+R_i | 2    |
| Nway Advertisement         | 7+G_i+R_i | 2    |
| FDX Bit Map                | 9+G_i+R_i | 2    |



# DM9102A

Single Chip Fast Ethernet NIC controller

|             |            |   |
|-------------|------------|---|
| TTM Bit Map | 11+G_i+R_i | 2 |
|-------------|------------|---|

Note 1: The definition of Media Capabilities and Nway Advertisement is the same with 802.3U in terms of Auto-negotiation.

10 BASE\_T Full Duplex 04  
 100 BASE\_T Half Duplex 01  
 100 BASE\_T Full Duplex 05

Note 2: Command Format

## Media Information Block: (Type = 00)

| ITEM           | Offset | Size |
|----------------|--------|------|
| Block Length   | 0      | 1    |
| Block Type(00) | 1      | 1    |
| Media Code     | 2      | 1    |
| GPR Data       | 3      | 1    |
| Command        | 4      | 2    |

Note 1: Media Code: 10BASE\_T Half Duplex 00

**Delay Period Block (Type = 80):** Define the delay time unit in us.

| ITEM           | Offset | Size |
|----------------|--------|------|
| Block Length   | 0      | 1    |
| Block Type(80) | 1      | 1    |
| Time Unit      | 2      | 2    |

## 6. Example of DM9102A SROM Format

Total Size: 128 Bytes

| Field Name                              | Offset (Bytes) | Size (Bytes) | Value (Hex) | Commentary  |
|---|----------------|--------------|-------------|---|
| Sub-Vendor ID                           | 0              | 2            | 1282        | ID Block  |
| Sub-Device ID                           | 2              | 2            | 9102        |   |
| Reserved1                               | 4              | 4            | 00000000    |   |
| Auto_Load_Control                       | 8              | 1            | 00          | Auto-load function definition:<br>Bit 3-0 = 1010 → Auto-Load PCI Vendor ID/Device ID enabled<br>Bit 7-4 = 1x1x → Auto-Load NCE, PMC/PMCSR enabled |
| New_Capabilities_Enable (NCE)           | 9              | 1            | 00          | Please refer to DM9102A Spec.   |
| PCI Vendor ID                           | 10             | 2            | 1282        | If Auto-Load PCI Vendor ID/Device ID function disabled, the PCI Vendor ID/Device ID will use the default values (1282h, 9102h).                   |
| PCI Device ID                           | 12             | 2            | 9102        |   |
| Power Management Capabilities (PMC)     | 14             | 1            | 00          | Please refer to DM9102A Spec.   |
| Power Management Control/Status (PMCSR) | 15             | 1            | 00          | Please refer to DM9102A Spec.   |
| ID_BLOCK_CRC                            | 16             | 1            | -           | Offset 0..15, 17 ID CRC   |
| Reserved2                               | 17             | 1            | 00          |   |

| Field Name                 | Offset (Bytes) | Size (Bytes) | Value (Hex) | Commentary             |
|----------------------------|----------------|--------------|-------------|------------------------|
| SROM Format Version        | 18             | 1            | 03          | Version 3.0            |
| Controller Count           | 19             | 1            | 01          |                        |
| IEEE Network Address       | 20             | 6            | -           | Controller Info Header |
| Controller_0 Device Number | 26             | 1            | 00          |                        |



# DM9102A

Single Chip Fast Ethernet NIC controller

| Field Name                    | Offset (Bytes) | Size (Bytes) | Value (Hex) | Commentary                   |
|-------------------------------|----------------|--------------|-------------|------------------------------|
| Controller_0 Info Leaf Offset | 27             | 2            | 001E        | Offset 30                    |
| Reserved3                     | 29             | 1            | 00          |                              |
| Selected Connected Type       | 30             | 2            | 0800        | Controller_0 Info Leaf Block |
| General Purpose Control       | 32             | 1            | 80          | MAC CR12 Register            |
| Block Count                   | 33             | 1            | 06          | 6 Blocks                     |
| F(1)+Length                   | 34             | 1            | 8E          | Block 1 (PHY Info Block)     |
| Type                          | 35             | 1            | 01          | PHY Information Block        |
| PHY Number                    | 36             | 1            | 01          | PHY Address                  |
| GPR Length                    | 37             | 1            | 00          |                              |
| Reset Sequence Length         | 38             | 1            | 02          |                              |
| Reset Sequence                | 39             | 2            | 0080        |                              |
| Media Capabilities            | 41             | 2            | 7800        |                              |
| Nway Advertisement            | 43             | 2            | 01E0        |                              |
| FDX Bit Map                   | 45             | 2            | 5000        |                              |
| TTM Bit Map                   | 47             | 2            | 1800        |                              |
| F(1)+Length                   | 49             | 1            | 85          | Block 2 (Delay Period Block) |
| Type                          | 50             | 1            | 80          | Delay Period Block           |
| Delay Sequence                | 51             | 4            | 40002000    | Micro-Second                 |





| Field Name  | Offset (Bytes) | Size (Bytes) | Value (Hex) | Commentary                 |
|-------------|----------------|--------------|-------------|----------------------------|
| F(1)+Length | 55             | 1            | 85          | Block 3 (Media Info Block) |
| Type        | 56             | 1            | 00          | Media Information Block    |
| Media Code  | 57             | 1            | 00          | 10Base-T Half_Duplex       |
| GPR Data    | 58             | 1            | 00          |                            |
| Command     | 59             | 2            | 0087        |                            |
| F(1)+Length | 61             | 1            | 85          | Block 4 (Media Info Block) |
| Type        | 62             | 1            | 00          | Media Information Block    |
| Media Code  | 63             | 1            | 01          | 100Base-TX Half_Duplex     |
| GPR Data    | 64             | 1            | 00          |                            |
| Command     | 65             | 2            | 0087        |                            |
| F(1)+Length | 67             | 1            | 85          | Block 5 (Media Info Block) |
| Type        | 68             | 1            | 00          | Media Information Block    |
| Media Code  | 69             | 1            | 04          | 10Base-T Full_Duplex       |
| GPR Data    | 70             | 1            | 00          |                            |
| Command     | 71             | 2            | 0087        |                            |
| F(1)+Length | 73             | 1            | 85          | Block 6 (Media Info Block) |
| Type        | 74             | 1            | 00          | Media Information Block    |
| Media Code  | 75             | 1            | 05          | 100Base-TX Full_Duplex     |
| GPR Data    | 76             | 1            | 00          |                            |
| Command     | 77             | 2            | 0087        |                            |
|             |                |              |             |                            |
| SROM_CRC    | 126            | 2            | -           | Offset 0..125 SROM CRC     |



**External MII/SRL Interface**

DM9102A provides one external MII/SRL interface sharing with all the pins with Boot ROM interface. This external MII/SRL interface can be connected with external PHYceiver such as Home Networking PHYceiver or other future

technology applications. This external MII/SRL interface can be set up by hardware and software. The setup methods are listed as below:

|                           | Test 1 (pin 75) | Test 2 (pin 71) | Clkrun# (pin 36) | MA8 (pin 84) | MA9 (pin 85) |
|---------------------------|-----------------|-----------------|------------------|--------------|--------------|
| <b>Normal Operation</b>   | 0               | 1               | X                | X            | X            |
| <b>External MII mode</b>  | 0               | 0               | 0                | 0            | 1/0          |
| <b>External SRL mode</b>  | 0               | 0               | 0                | 1            | 1/0          |
| <b>Internal Test mode</b> | 1               | X               | X                | X            | X            |

**Note 1**  
**Note 2**

**Note 1:** External MII mode

MA9 = 1 (Set up by hardware; Mode cannot be changed.)  
 MA9 = 0 & MII\_Mode = 1 (Select external MII interface; Mode can be changed by software.)  
 Where MII\_Mode is the bit 18 of CR6.

**Note 2:** External SRL mode:

MA9 = 1 (Set up by hardware; Mode cannot be changed.)  
 MA9 = 0 & MII\_Mode = 0 (Select external SRL interface; Mode can be changed by software.)

**The Sharing Pin Table** (o): output, (i): input, (b): bi-direction

| Pin | Normal Operation             |                              | External MII/SRL Interface        |                                   |
|-----|------------------------------|------------------------------|-----------------------------------|-----------------------------------|
|     | Boot ROM Mux mode<br>MA6 = 0 | Boot ROM Dir mode<br>MA6 = 1 | External MII interface<br>MA8 = 0 | External SRL interface<br>MA8 = 1 |
| 62  | BPAD0                        | MD0/DI                       | MII_TXD3 (o)                      | BPAD0                             |
| 63  | BPAD1                        | MD1                          | MII_TXD2 (o)                      | BPAD1                             |
| 64  | BPAD2                        | MD2                          | MII_TXD1 (o)                      | BPAD2                             |
| 65  | BPAD3                        | MD3                          | MII_RXER (i)                      | BPAD3                             |
| 66  | BPAD4                        | MD4                          | MII_RXDV (i)                      | BPAD4                             |
| 67  | BPAD5                        | MD5                          | MII_RXD1 (i)                      | BPAD5                             |
| 68  | BPAD6                        | MD6                          | MII_RXD2 (i)                      | BPAD6                             |
| 69  | BPAD7                        | MD7                          | MII_MDIO (b)                      | BPAD7                             |
| 72  | BPCS#                        | ROMCS                        | MII_MDC (o)                       | BPCS#                             |
| 73  | BPA0                         | MA0                          | NC                                | BPA0                              |
| 74  | BPA1                         | MA1                          | MII_RXD (i)                       | BPA1                              |
| 77  | EEDI                         | MA2                          | EEDI (i)                          | EEDI (i)                          |
| 78  | EEDO                         | MA3/DO                       | EEDO (o)                          | EEDO (o)                          |
| 79  | EECK                         | MA4/CK                       | EECK (o)                          | EECK (o)                          |
| 80  | EECS                         | MA5                          | EECS (o)                          | EECS (o)                          |
| 81  |                              | MA6                          | MII_COL (i)                       | SRL_COL (i)                       |
| 83  |                              | MA7                          | MII_TXCLK (i)                     | SRL_TXC (i)                       |
| 84  |                              | MA8                          | MII_TXEN (o)                      | SRL_TXE (o)                       |



# DM9102A

Single Chip Fast Ethernet NIC controller

|    |        |          |               |             |
|----|--------|----------|---------------|-------------|
| 85 |        | MA9      | MII_TXD0 (o)  | SRL_TXD (o) |
| 87 | TRFLED | MA10/TRF | NC            | NC          |
| 88 | FDXLED | MA11/FDX | OSC20 (o)     | OSC20 (o)   |
| 89 | SPD100 | MA12/100 | Link (i)      | Link (i)    |
| 90 | SPD10  | MA13/10  | NC            | NC          |
| 91 |        | MA14     | MII_CRS (i)   | SRL_CRS (i) |
| 92 |        | MA15     | MII_RXCLK (i) | SRL_RXC (i) |
| 93 |        | MA16     | MII_RXD0 (i)  | SRL_RXD (i) |
| 94 | MA17   | MA17     | NC            | NC          |

Where NC is no connection

Pin88 is 20MHz clock output for external PHY (such as DM9801)

Pin89 is link status input from external PHY for power management changed event and reflect at CR12 bit6.

**Absolute Maximum Ratings****Absolute Maximum Ratings\* ( 25°C )**

| Symbol    | Parameter                           | Min. | Max. | Unit | Conditions |
|-----------|-------------------------------------|------|------|------|------------|
| DVCC,AVCC | Supply Voltage                      | -0.3 | 3.6  | V    |            |
| VIN       | DC Input Voltage (VIN)              | -0.5 | 5.5  | V    |            |
| VOUT      | DC Output Voltage(VOUT)             | -0.3 | 3.6  | V    |            |
| Tc        | Case Temperature Range              | 0    | 85   | °C   |            |
| Tstg      | Storage Temperature Rang (Tstg)     | -65  | 150  | °C   |            |
| LT        | Lead Temp. (TL, Soldering, 10 sec.) | ---  | 220  | °C   |            |

**Operating Conditions**

| Symbol                       | Parameter        | Min.  | Max.  | Unit | Conditions |
|------------------------------|------------------|-------|-------|------|------------|
| DVCC,AVCC                    | Supply Voltage   | 3.135 | 3.465 | V    |            |
| Tc                           | Case Temperature | 0     | 85    | °C   |            |
| PD<br>(Power<br>Dissipation) | 100BASE-TX       | ---   | 115   | mA   | 3.3V       |
|                              | 100BASE-TX IDLE  | ---   | 115   | mA   | 3.3V       |
|                              | 10BASE-T TX      | ---   | 125   | mA   | 3.3V       |
|                              | 10BASE-T IDLE    | ---   | 45    | mA   | 3.3V       |
|                              | Auto-negotiation | ---   | 76    | mA   | 3.3V       |

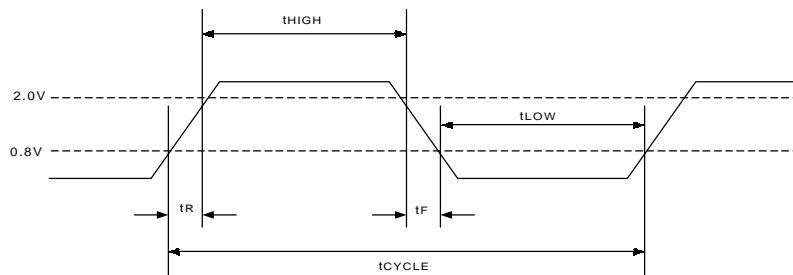
**Comments**

Stresses above those listed under “Absolute Maximum Ratings” may cause permanent damage to the device. These are stress ratings only. Functional operation of this device at these or any other conditions above those indicated

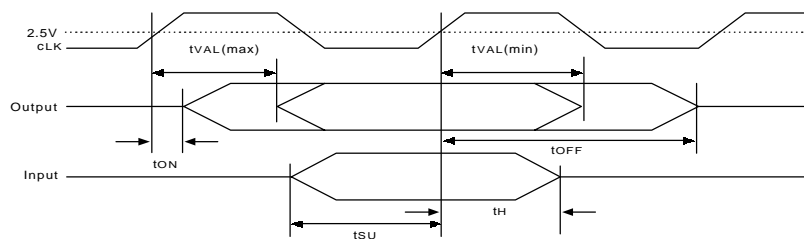
in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**DC Electrical Characteristics**(0°C < T<sub>c</sub> < 85°C, 3.135V < V<sub>CC</sub> < 3.465V, unless otherwise noted)

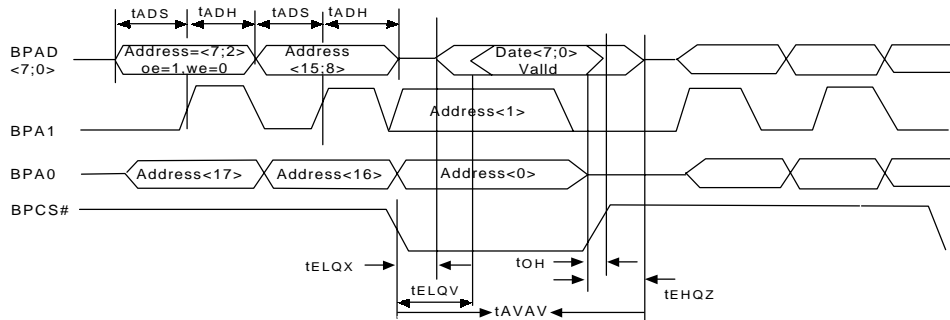
| Symbol             | Parameter                            | Min. | Typ. | Max. | Unit | Conditions               |
|--------------------|--------------------------------------|------|------|------|------|--------------------------|
| <b>Inputs</b>      |                                      |      |      |      |      |                          |
| V <sub>IL</sub>    | Input Low Voltage                    | ---  | ---  | 0.8  | V    |                          |
| V <sub>IH</sub>    | Input High Voltage                   | 2.0  | ---  | ---  | V    |                          |
| I <sub>IL</sub>    | Input Low Leakage Current            | ---  | ---  | 5    | uA   | V <sub>IN</sub> = 0V     |
| I <sub>IH</sub>    | Input High Leakage Current           | 5    | ---  | ---  | uA   | V <sub>IN</sub> = 3.3V   |
| <b>Outputs</b>     |                                      |      |      |      |      |                          |
| V <sub>OL</sub>    | Output Low Voltage                   | ---  | ---  | 0.4  | V    | I <sub>OL</sub> = 4mA    |
| V <sub>OH</sub>    | Output High Voltage                  | 2.4  | ---  | ---  | V    | I <sub>OH</sub> = -4mA   |
| <b>Receiver</b>    |                                      |      |      |      |      |                          |
| V <sub>ICM</sub>   | RX+/RX- Common mode Input Voltage    | ---  | 0.9  | ---  | V    | 100 Ω Termination Across |
| <b>Transmitter</b> |                                      |      |      |      |      |                          |
| V <sub>TD100</sub> | 100TX+/- Differential Output Voltage | 1.9  | 2.0  | 2.1  | V    | Peak to Peak             |
| V <sub>TD10</sub>  | 10TX+/- Differential Output Voltage  | 4.4  | 5    | 5.6  | V    | Peak to Peak             |
| I <sub>TD100</sub> | 100TX+/- Differential Output Current | 19   | 20   | 21   | mA   | Absolute Value           |
| I <sub>TD10</sub>  | 10TX+/- Differential Output Current  | 44   | 50   | 56   | mA   | Absolute Value           |

**AC Electrical Characteristics & Timing Waveforms**
**PCI Clock Specifications Timing**


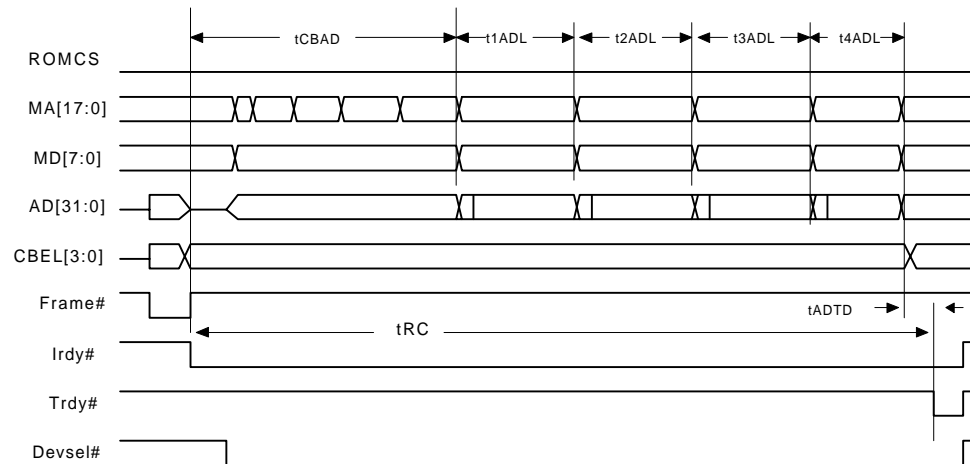
| Symbol      | Parameter            | Min. | Typ. | Max. | Unit | Conditions |
|-------------|----------------------|------|------|------|------|------------|
| $t_R$       | PCI_CLK rising time  | -    | -    | 4    | ns   | -          |
| $t_F$       | PCI_CLK falling time | -    | -    | 4    | ns   | -          |
| $t_{CYCLE}$ | Cycle time           | 25   | 30   | -    | ns   | -          |
| $t_{HIGH}$  | PCI_CLK High Time    | 12   | -    | -    | ns   | -          |
| $t_{LOW}$   | PCI_CLK Low Time     | 12   | -    | -    | ns   | -          |

**Other PCI Signals Timing Diagram**


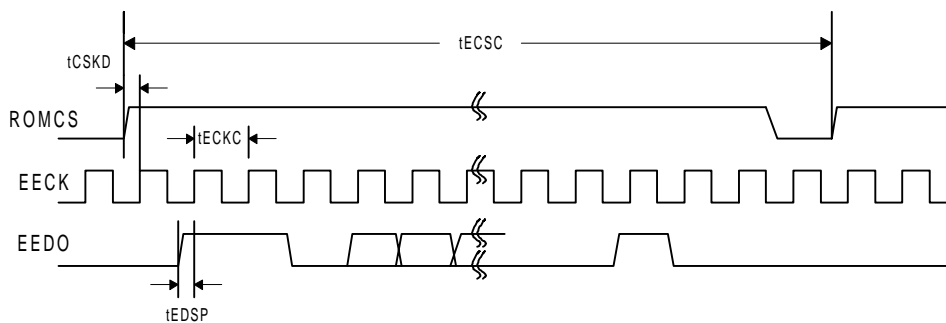
| Symbol    | Parameter                                | Min. | Typ. | Max. | Unit | Conditions   |
|-----------|--|------|------|------|------|--------------|
| $t_{VAL}$ | Clk-To-Signal Valid Delay                | 2    | -    | 11   | ns   | Clod = 50 pF |
| $t_{ON}$  | Float-To-Active Delay From Clk           | 2    | -    | -    | ns   | -            |
| $t_{OFF}$ | Active-To-Float Delay From Clk           | -    | -    | 28   | ns   | -            |
| $t_{SU}$  | Input Signal Valid Setup Time Before Clk | 7    | -    | -    | ns   | -            |
| $t_H$     | Input Signal Hold Time From Clk          | 0    | -    | -    | ns   | -            |

**Multiplex Mode Boot ROM Timing**


| Symbol | Parameter                                  | Min. | Type | Max. | Unit      | Conditions |
|--------|--|------|------|------|-----------|------------|
| tAVAV  | Read Cycle Time                            | -    | 31   | -    | PCI clock | -          |
| tELQV  | BPCS# To Output Delay                      | 0    | -    | 7    | PCI clock | -          |
| tEHQZ  | BPCS# Rising Edge To Output High Impedance | -    | 1    | -    | PCI clock | -          |
| toH    | Output Hold From BPCS#                     | 0    | -    | -    | PCI clock | -          |
| tADS   | Address Setup To Latch Enable High         | 4    | -    | -    | PCI clock | -          |
| TADH   | Address Hold From Latch Enable High        | 4    | -    | -    | PCI clock | -          |

**Direct Mode Boot ROM Timing**


| Symbol | Parameter                          | Min. | Typ. | Max. | Unit      | Conditions |
|--------|------------------------------------|------|------|------|-----------|------------|
| tRC    | Read Cycle Time                    | -    | 50   | -    | PCI clock | -          |
| tCBAD  | Bus Command to first address delay | -    | 18   | -    | PCI clock | -          |
| t1ADL  | first address length               | -    | 8    | -    | PCI clock | -          |
| t2ADL  | second address delay               | -    | 8    | -    | PCI clock | -          |
| t3ADL  | third address delay                | -    | 8    | -    | PCI clock | -          |
| t4ADL  | fourth address delay               | -    | 7    | -    | PCI clock | -          |
| tADTD  | end of address to Tardy active     | -    | 1    | -    | PCI clock | -          |

**EEPROM Timing**


| Symbol | Parameter                          | Min. | Typ. | Max. | Unit      | Conditions |
|--------|------------------------------------|------|------|------|-----------|------------|
| tECKC  | Serial ROM clock EECK period       | 64   | -    | -    | PCI clock | -          |
| tECSC  | Read Cycle Time                    | 1792 | -    | -    | PCI clock | -          |
| tCSKD  | Delay from ROMCS High to EECK High | 28   | -    | -    | PCI clock | -          |
| tEDSP  | Setup Time of EEDO to EECK         | 24   | -    | -    | PCI clock | -          |



**TP Interface**

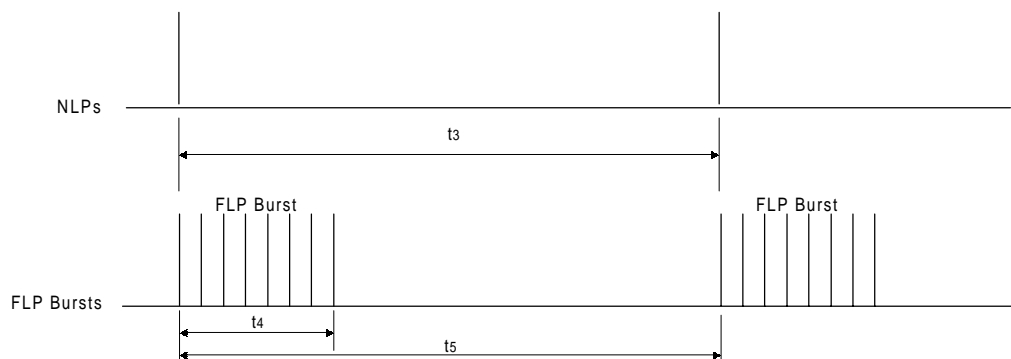
| Symbol | Parameter  | Min. | Typ. | Max. | Unit | Conditions |
|--------|--|------|------|------|------|------------|
| tTR/F  | 100TX+/- Differential Rise/Fall Time               | 3.0  | ---  | 5.0  | ns   |            |
| tTM    | 100TX+/- Differential Rise/Fall Time Mismatch      | 0    | ---  | 0.5  | ns   |            |
| tTDC   | 100TX+/- Differential Output Duty Cycle Distortion | 0    | 0    | 0.5  | ns   |            |
| tT/T   | 100TX+/- Differential Output Peak-to-Peak Jitter   | 0    | ---  | 1.4  | ns   |            |
| XOST   | 100TX+/- Differential Voltage Overshoot            | 0    | ---  | 5    | %    |            |

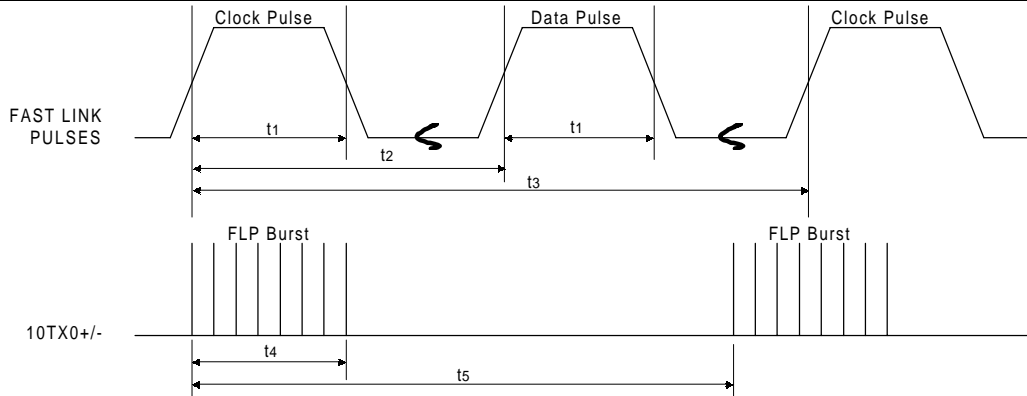
**Oscillator/Crystal Timing**

| Symbol | Parameter            | Min.   | Typ. | Max.   | Unit | Conditions |
|--------|----------------------|--------|------|--------|------|------------|
| tCKC   | OSC Cycle Time       | 39.996 | 40   | 40.004 | ns   |            |
| TPWH   | OSC Pulse Width High | 16     | 20   | 24     | ns   |            |
| TPWL   | OSC Pulse Width Low  | 16     | 20   | 24     | ns   |            |

**Auto-negotiation and Fast Link Pulse Timing Parameters**

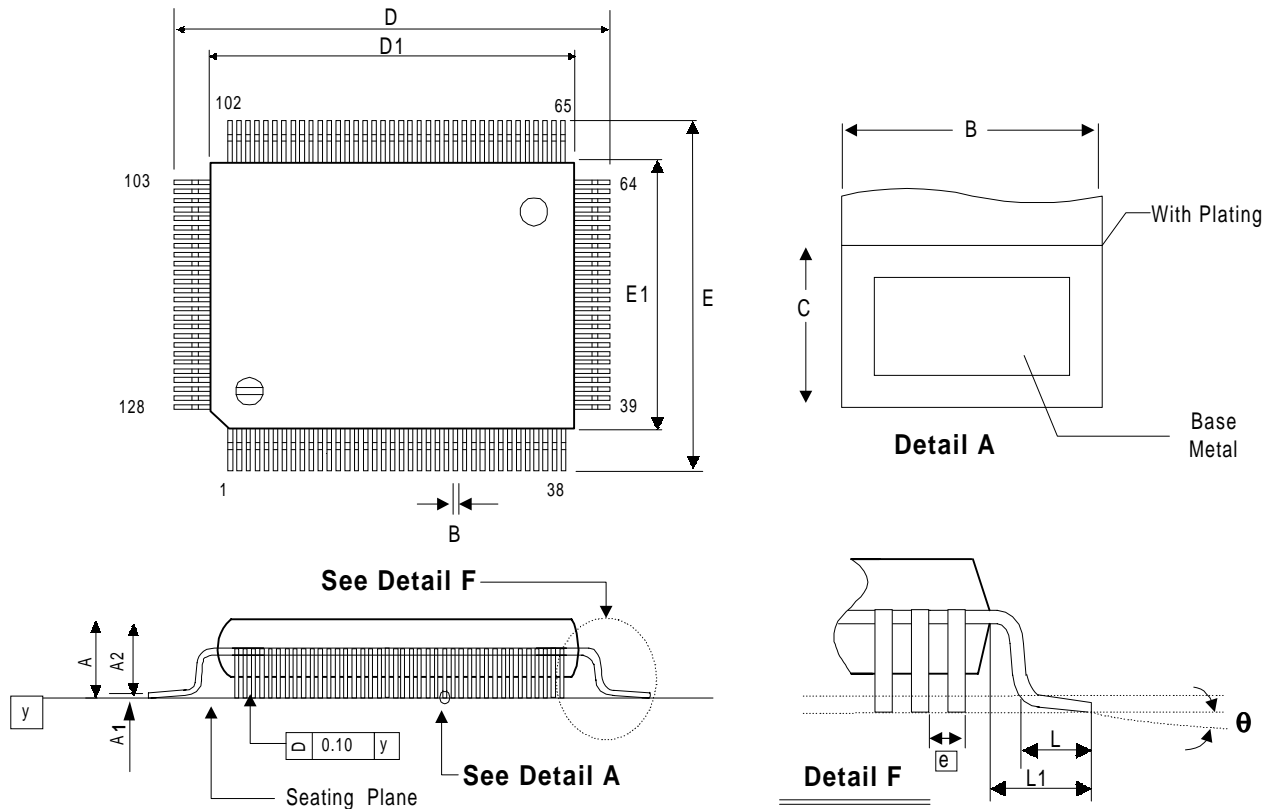
| Symbol | Parameter                         | Min. | Typ. | Max. | Unit | Conditions |
|--------|-----------------------------------|------|------|------|------|------------|
| t1     | Clock/Data Pulse Width            | ---  | 100  | ---  | ns   |            |
| t2     | Clock Pulse To Data Pulse Period  | 55.5 | 62.5 | 69.5 | us   | DATA = 1   |
| t3     | Clock Pulse To Clock Pulse Period | 111  | 125  | 139  | us   |            |
| t4     | FLP Burst Width                   | -    | 2    | -    | ms   |            |
| t5     | FLP Burst To FLP Burst Period     | 8    | 16   | 24   | ms   |            |
| -      | Clock/Data Pulses in a Burst      | 17   |      | 33   | #    |            |





**Package Information**
**QFP 128L Outline Dimensions**

Unit: Inches/mm



| Symbol | Dimension In Inch | Dimension In mm |
|--------|-------------------|-----------------|
| A      | 0.134 Max.        | 3.40 Max.       |
| A1     | 0.010 Min.        | 0.25 Min.       |
| A2     | 0.112± 0.005      | 2.85± 0.12      |
| B      | 0.009± 0.002      | 0.22±0.05       |
| C      | 0.006± 0.002      | 0.145± 0.055    |
| D      | 0.913± 0.007      | 23.20± 0.20     |
| D1     | 0.787± 0.004      | 20.00 ± 0.10    |
| E      | 0.677± 0.008      | 17.20± 0.20     |
| E1     | 0.551± 0.004      | 14.00± 0.10     |
| e      | 0.020 BSC         | 0.5 BSC         |
| L      | 0.035± 0.006      | 0.88± 0.15      |
| L1     | 0.063 BSC         | 1.60 BSC        |
| y      | 0.004 Max.        | 0.10 Max.       |
| θ      | 0°~12°            | 0°~12°          |

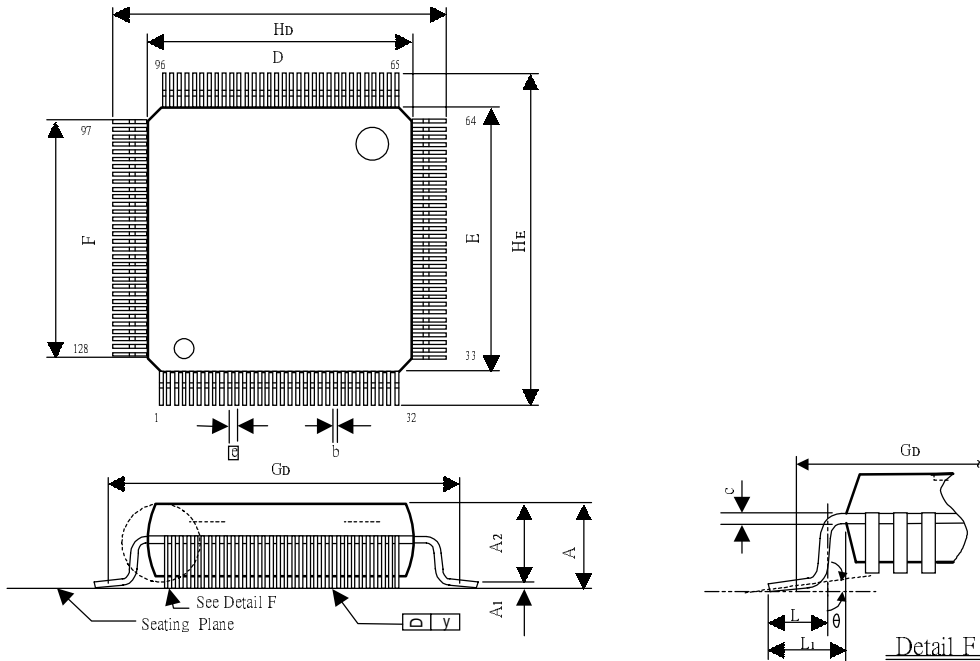
**Note:**

1. Dimension D1 and E1 do not include resin fins.
2. All dimensions are based on metric system.
3. General appearance spec. should base itself on final visual inspection spec.

## Package Information

### TQFP 128L Outline Dimensions

Unit: Inches/mm



| Symbol   | Dimensions In Inches      | Dimensions In mm        |
|----------|---------------------------|-------------------------|
| A        | 0.047 Max.                | 1.20 Max.               |
| A1       | $0.004 \pm 0.002$         | $0.1 \pm 0.05$          |
| A2       | $0.039 \pm 0.002$         | $1.0 \pm 0.05$          |
| b        | $0.006^{+0.003}_{-0.001}$ | $0.16^{+0.07}_{-0.03}$  |
| c        | $0.006 \pm 0.002$         | $0.15 \pm 0.05$         |
| D        | $0.551 \pm 0.005$         | $14.00 \pm 0.13$        |
| E        | $0.551 \pm 0.005$         | $14.00 \pm 0.13$        |
| $\theta$ | 0.016 BSC.                | 0.40 BSC.               |
| F        | 0.494 NOM.                | 12.56 NOM.              |
| $G_D$    | 0.606 NOM.                | 15.40 NOM.              |
| $H_D$    | $0.630 \pm 0.006$         | $16.00 \pm 0.15$        |
| $H_E$    | $0.630 \pm 0.006$         | $16.00 \pm 0.15$        |
| L        | $0.024 \pm 0.006$         | $0.60 \pm 0.15$         |
| $L_1$    | 0.039 Ref.                | 1.00 Ref.               |
| y        | 0.003 Max.                | 0.08 Max.               |
| $\theta$ | $0^\circ \sim 12^\circ$   | $0^\circ \sim 12^\circ$ |

- Note:**
1. Dimension D & E do not include resin fins.
  2. Dimension  $\theta$  is for PC Board surface mount, pad pitch design reference only.
  3. All dimensions are based on metric system.



### Ordering Information

| Part Number | Pin Count | Package |
|-------------|-----------|---------|
| DM9102AF    | 128       | QFP     |
| DM9102AT    | 128       | TQFP    |

### Disclaimer

The information appearing in this publication is believed to be accurate. Integrated circuits sold by DAVICOM Semiconductor are covered by the warranty and patent indemnification provisions stipulated in the terms of sale only. DAVICOM makes no warranty, express, statutory, implied or by description regarding the information in this publication or regarding the information in this publication or regarding the freedom of the described chip(s) from patent infringement. FURTHER, DAVICOM MAKES NO WARRANTY OF MERCHANTABILITY OR FITNESS FOR ANY PURPOSE. DAVICOM reserves the right to halt production or alter the specifications and prices at any time without notice. Accordingly, the reader is cautioned to verify that the data sheets and other information in this publication are current before placing orders. Products described herein are intended for use in normal commercial applications. Applications involving unusual environmental or reliability requirements, e.g. military equipment or medical life support equipment, are specifically not recommended without additional processing by DAVICOM for such applications. Please note that

application circuits illustrated in this document are for reference purposes only.

DAVICOM's terms and conditions printed on the order acknowledgment govern all sales by DAVICOM. DAVICOM will not be bound by any terms inconsistent with these unless DAVICOM agrees otherwise in writing. Acceptance of the buyer's orders shall be based on these terms.

### Company Overview

DAVICOM Semiconductor, Inc. develops and manufactures integrated circuits for integration into data communication products. Our mission is to design and produce IC products that are the industry's best value for Data, Audio, Video, and Internet/Intranet applications. To achieve this goal, we have built an organization that is able to develop chipsets in response to the evolving technology requirements of our customers while still delivering products that meet their cost requirements.

### Products

We offer only products that satisfy high performance requirements and which are compatible with major hardware and software standards. Our currently available and soon to be released products are based on our proprietary designs and deliver high quality, high performance chipsets that comply with modern communication standards and Ethernet networking standards.

### Contact Windows

*For additional information about DAVICOM products, contact the sales department at:*

#### Headquarters

##### Hsin-chu Office:

3F, No. 7-2, Industry E. Rd., IX,  
Science-based Park,  
Hsin-chu City, Taiwan, R.O.C.  
TEL: 886-3-5798797  
FAX: 886-3-5798858

##### Taipei Sales & Marketing Office:

8F, No. 3, Lane 235, Bao-chiao Rd.,  
Hsin-tien City, Taipei, Taiwan, R.O.C.  
TEL: 886-2-29153030  
FAX: 886-2-29157575  
Email: [sales@davicom.com.tw](mailto:sales@davicom.com.tw)

#### Davicom USA

##### Sunnyvale, California

1135 Kern Ave., Sunnyvale,  
CA94085, U.S.A.  
TEL: 1-408-7368600  
FAX: 1-408-7368688  
Email: [sales@davicom8.com](mailto:sales@davicom8.com)

#### WARNING

Conditions beyond those listed for the absolute maximum may destroy or damage the products. In addition, conditions for sustained periods at near the limits of the operating ranges will stress and may temporarily (and permanently) affect and damage structure, performance and/or function.